SYSMAC C200HW-COM01
C200HW-COM02-V1 to C200HW-COM06-EV1 Communications Boards

## OPERATION MANUAL

## C200HW-COM01

C200HW-COM02-V1 to C200HW-COM06-EV1 Communications Boards

## Operation Manual

Revised November 2003

## Notice:

OMRON products are manufactured for use according to proper procedures by a qualified operator and only for the purposes described in this manual.
The following conventions are used to indicate and classify precautions in this manual. Always heed the information provided with them. Failure to heed precautions can result in injury to people or damage to property.

DANGER Indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.

WARNING
Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.

Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.

## OMRON Product References

All OMRON products are capitalized in this manual. The word "Unit" is also capitalized when it refers to an OMRON product, regardless of whether or not it appears in the proper name of the product.
The abbreviation "Ch," which appears in some displays and on some OMRON products, often means "word" and is abbreviated "Wd" in documentation in this sense.

The abbreviation "PC" means Programmable Controller and is not used as an abbreviation for anything else.

## Visual Aids

The following headings appear in the left column of the manual to help you locate different types of information.

Note Indicates information of particular interest for efficient and convenient operation of the product.

1, 2, 3... 1. Indicates lists of one sort or another, such as procedures, checklists, etc.

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## About this Manual:

This manual describes the installation and operation of the C200HW-COM01, C200HW-COM02-V1, C200HW-COM03-V1, C200HW-COM04-EV1, C200HW-COM05-EV1, and C200HW-COM06-EV1 Communications Boards for the C200HX/C200HG/C200HE Programmable Controllers and includes the sections described below. The manual is also written so that it can be used for the previous versions of these Communications Boards even though some of the protocol macro functionality is not supported.
When using the Communications Boards, information in the following manuals will also be required. (Catalog number suffixes have been omitted. Please be sure you have the most recent version of your manual for your area. Contact your OMRON representative for more information.)

| Manual | Content | Cat. No. |
| :--- | :--- | :--- |
| C200HW-ZW3PC1 <br> Protocol Support Software <br> Operation Manual | Information on using the Software to <br> create protocol macros and information <br> on the system protocol macros. | W305 |
| SYSMAC WS01-PSTF1-E <br> Protocol Support Tool <br> SYSMAC-PST Operation <br> Manual | Information on SYSMAC-PST, a <br> Windows-95-based software package <br> that supports the protocol macro <br> functionality of models <br> C200HW-COM04(-EV1) to <br> C200HW-COM06(-EV1). | W319 |
| SYSMAC WS02-PSTC1-E <br> CX-Protocol Operation <br> Manual | Information on CX-Protocol, a <br> Windows-95/98-based software <br> package that supports the protocol <br> macro functionality of models <br> C200HW-COM04(-EV1) to <br> C200HW-COM06(-EV1), <br> CS1W-SCB21/41, and CS1W-SCU21. | W344 |
| C200HX/C200HG/C200HE <br> (-E/-ZE) Operation Manual | Information on programming and <br> operating the PC. | W303 |
| C200HX/C200HG/C200HE <br> Installation Guide | Information required to install and <br> maintain PC hardware. | W302 |

Please read this manual and the above related manuals carefully and be sure you understand the information provided before attempting to install and operate a Communications Board. Be sure to read the precautions in the following section and understand the information contained before attempting to set up or operate a PC system containing a Communications Board.

Section 1 Handling the Communications Board provides an outline of the functions of the Communications Boards, the installation method, the system configuration, and the system setup.
Section 2 Protocol Macro Function describes the protocol macro function supported by Communications Boards, and how to use the system protocol macros provided with the Protocol Support Software. Troubleshooting is also described in this section.
The Appendices provide configuration information for various OMRON products and Hayes Modems. These are as follows:

WARNING
Failure to read and understand the information provided in this manual may result in personal injury or death, damage to the product, or product failure. Please read each section in its entirety and be sure you understand the information provided in the section and related sections before attempting any of the procedures or operations given.

## About this Manual

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B E5 $\square K$ Digital Controller Writes
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G K3T $\square$ Intelligent Signal Processors
H V500/V520 Bar Code Readers
I 3Z4L Laser Micrometer
J F200/F300/F350 Visual Inspection Systems
K V600/620 ID Controllers
L Hayes Modem AT Commands

Refer to the following manuals when using the built-in protocols.

| Device/Manual name | Catalog No. |
| :--- | :--- |
| E5CK Digital Controller User's Manual | H 78 |
| E5ZE Multipoint Temperature Controller Operation Manual | H 76 |
| E5ZE Multipoint Temperature Controller COMMUNICATIONS MANUAL | H 77 |
| E5 $\square$ J Temperature Controller Operation Manual | Z103 |
| E5 $\square$ J Electronic Temperature Controller Manual | Z 103 |
| ES100P Digital Controller User's Manual | H 069 |
| ES100X DIGITAL CONTROLLER User's Manual | H 070 |
| ES100 COMMUNICATIONS GUIDE User's Manual | H 072 |
| K3TC Intelligent Signal Processor Operation Manual | Z117 |
| K3tC/K3TH/K3TR/K3TX Communication Output-type Intelligent Signal Processor <br> Operation Manual | Z81 |
| F200-C12E Specifications/Instruction Manual | Z110 |
| F300 Visual Inspection System Menu Mode Operation Manual | Z91 |
| F350-U001E Character Inspection Software 1 Operation Manual | Z105 |
| F350-U003E Position Software 1 Operation Manual | Z107 |
| V600/V620 FA ID SYSTEM Operation Manual | Z83 |

## PRECAUTIONS

This section provides general precautions for using the Communications Boards.
The information contained in this section is important for the safe and reliable application of the Communications Boards and the PC in general. You must read this section and understand the information contained before attempting to set up or operate a PC system containing a Communications Board.
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## 1 Intended Audience

This manual is intended for the following personnel, who must also have knowledge of electrical systems (an electrical engineer or the equivalent).

- Personnel in charge of installing FA systems.
- Personnel in charge of designing FA systems.
- Personnel in charge of managing FA systems and facilities.


## 2 General Precautions

The user must operate the product according to the performance specifications described in the operation manuals.
Before using the product under conditions which are not described in the manual or applying the product to nuclear control systems, railroad systems, aviation systems, vehicles, combustion systems, medical equipment, amusement machines, safety equipment, and other systems, machines, and equipment that may have a serious influence on lives and property if used improperly, consult your OMRON representative.
Make sure that the ratings and performance characteristics of the product are sufficient for the systems, machines, and equipment, and be sure to provide the systems, machines, and equipment with double safety mechanisms.
This manual provides information for programming and operating OMRON PCs. Be sure to read this manual before attempting to use the software and keep this manual close at hand for reference during operation.

It is extremely important that a Communications Board and all related units be used for the specified purpose and under the specified conditions, especially in applications that can directly or indirectly affect human life. You must consult with your OMRON representative before applying a Communication Board to the above mentioned applications.

## 3 Safety Precautions

WARNING Do not attempt to take any Unit apart while the power is being supplied. Doing so may result in electric shock.

WARNING Do not touch any of the terminals or terminal blocks while the power is being supplied. Doing so may result in electric shock.

WARNING Do not attempt to disassemble, repair, or modify any Units. Any attempt to do so may result in malfunction, fire, or electric shock.

WARNING Never open the back cover of devices containing monitors, such as CRTs. High-voltage parts are contained inside. Opening the back cover may result in electric shock.

[^0]When using the large-capacity C200HW-PA209R Power Supply Unit, the temperature of the Unit will increase during power supply and immediately after power supply is turned OFF. Do not touch the Unit at these times. Doing so may result in injury.

## 4 Operating Environment Precautions

Caution Do not operate the control system in the following locations:

- Locations subject to direct sunlight.
- Locations subject to temperatures or humidity outside the range specified in the specifications.
- Locations subject to condensation as the result of severe changes in temperature.
- Locations subject to corrosive or flammable gases.
- Locations subject to dust (especially iron dust) or salts.
- Locations subject to exposure to water, oil, or chemicals.
- Locations subject to shock or vibration.

1. Caution Take appropriate and sufficient countermeasures when installing systems in the following locations:

- Locations subject to static electricity or other forms of noise.
- Locations subject to strong electromagnetic fields.
- Locations subject to possible exposure to radioactivity.
- Locations close to power supplies.

Caution The operating environment of the PC system can have a large effect on the longevity and reliability of the system. Improper operating environments can lead to malfunction, failure, and other unforeseeable problems with the PC system. Be sure that the operating environment is within the specified conditions at installation and remains within the specified conditions during the life of the system.

## 5 Application Precautions

Observe the following precautions when using the PC system.
! WARNING Always heed these precautions. Failure to abide by the following precautions could lead to serious or possibly fatal injury.

- Always ground the system to $100 \Omega$ or less when installing the Units. Not connecting to a ground of $100 \Omega$ or less may result in electric shock.
- Always turn OFF the power supply to the PC before attempting any of the following. Not turning OFF the power supply may result in malfunction or electric shock.
- Mounting or dismounting I/O Units, CPU Units, Memory Units, or any other Units.
- Assembling the Units.
- Setting DIP switches or rotary switches.
- Connecting cables or wiring the system.
- Connecting or disconnecting the connectors.

Caution Failure to abide by the following precautions could lead to faulty operation of the PC or the system, or could damage the PC or PC Units. Always heed these precautions.

- Fail-safe measures must be taken by the customer to ensure safety in the event of incorrect, missing, or abnormal signals caused by broken signal lines, momentary power interruptions, or other causes.
- Interlock circuits, limit circuits, and similar safety measures in external circuits (i.e., not in the Programmable Controller) must be provided by the customer.
- Always use the power supply voltages specified in this manual. An incorrect voltage may result in malfunction or burning.
- Take appropriate measures to ensure that the specified power with the rated voltage and frequency is supplied. Be particularly careful in places where the power supply is unstable. An incorrect power supply may result in malfunction.
- Install external breakers and take other safety measures against short-circuiting in external wiring. Insufficient safety measures against short-circuiting may result in burning.
- Do not apply voltages to the Input Units in excess of the rated input voltage. Excess voltages may result in burning.
- Do not apply voltages or connect loads to the Output Units in excess of the maximum switching capacity. Excess voltage or loads may result in burning.
- Disconnect the functional ground terminal when performing withstand voltage tests. Not disconnecting the functional ground terminal may result in burning.
- Be sure that all the mounting screws, terminal screws, and cable connector screws are tightened to the torque specified in this manual. Incorrect tightening torque may result in malfunction.
- Check the user program for proper execution before actually running it on the Unit. Not checking the program may result in an unexpected operation.
- Do not pull on the cables or bend the cables beyond their natural limit. Doing either of these may break the cables.
- Do not place objects on top of the cables or other wiring lines. Doing so may break the cables.
- When replacing parts, be sure to confirm that the rating of a new part is correct. Not doing so may result in malfunction or burning.
- Before touching a Unit, be sure to first touch a grounded metallic object in order to discharge any static built-up. Not doing so may result in malfunction or damage.

This section provides an outline of the functions of the Communications Boards, the installation method, the system configuration, and the system setup.
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## 1-1 Functions

The Communications Boards are optional boards that can be installed in the option slot of various $\mathrm{C} 200 \mathrm{HX} / \mathrm{C} 200 \mathrm{HG} / \mathrm{C} 200 \mathrm{HE} \mathrm{CPU}$ Units (CPU $\square 5-\mathrm{E}$, CPU $\square 4-E, C P U \square 3-E, C P U \square 2-E)$.

## 1-1-1 Features

Connection to
Communications Units via CPU Bus

The following features are provided by mounting a Communications Board in the option slot of a CPU Unit.

The CPU Unit can be connected to Controller Link, SYSMAC LINK, SYSMAC NET or other Communications Units via a Bus Connection Unit.


## Expanded Communications

## Host Link Communications: $1: \mathrm{N}$

The PC can be controlled from a host computer (personal computer or Programmable Terminal (PT)) to read/write I/O memory, control the operating mode of the PC, etc. The PC can also use the TXD instruction to send specified words in I/O memory to a host.


Note The RP Host Link command can be used for C200HX//HE/HE-CPU $\square \square$-ZE CPU Units only when a V1 Communications Board is mounted.

## Non-procedure Communications

Simple (no-protocol) data transfers are possible using the communications port I/O instructions (TXD and RXD) to input data from a bar code reader, output data
to a printer, etc. The usage of start and end codes can be specified and RTS and CTS signals can be controlled.


## 1:1 Links

Common data areas can be created in the LR Area without using PC Link Units by connecting two PCs $1: 1$ via the RS-232C port.


NT Links: 1:1 or 1:N
A PC can be connected to one or more PTs (Programmable Terminals) via an RS-232C port to enable data transfer via NT Link commands.


## Protocol Macros

Data transfer procedures called protocols can be easily created using the Protocol Support Software (sold separately). Procedures can be designed to match
the communications specifications of the external devices that are being communicated with (half duplex or start-stop sync). The protocols that are created are loaded to the Communications Board to enable data transfer with the external devices simply by executing the PMCR instruction from the PC. There are also many system protocols provided with the Communications Boards and Protocol Support Software to enable communications with OMRON Temperature Controllers, Panel Meters, Intelligent Signal Processors, Bar Code Readers, Modems, etc. The system protocols can also be modified for other applications according to user needs.

RS-232C, RS-422A, or RS-485


Note The following protocol macro functionality has been added to the V1 Communications Boards. The following are possible only for the C200HWCOM $\square \square$-EV1 Communications Boards.

- SUM2 (SUM of two's complement) and CRC-16 can be used for error checking.
- The Repeat Counter N Present Value, a Sequence End Flag, and a Sequence Abort Flag are provided in the SR area.
- The check code can be placed after the terminator in the message sequence. (Supported by SYSMAC-PST and CX-Protocol.)
- The upper and lower bytes of the error check code can be swapped. (Supported by SYSMAC-PST and CX-Protocol.)


## 1-1-2 Protocols

The Communications Board supports the following protocols.

| Protocol | Device | Connection <br> configuration | Communications <br> instruction |  |
| :--- | :--- | :--- | :--- | :--- |
| Host Link | PC $\leftarrow \rightarrow$ Personal <br> computer or PT | 1 to 1 or <br> 1 to N | Communications procedure between a <br> host personal computer and PCs. <br> Can monitor operation status of PC or bit <br> status from a personal computer. <br> Can transfer data stored in the IOM area <br> of PC to a host personal computer using <br> the TXD instruction. | Host Link commands <br> or TXD instruction |
| Non-proce- <br> dure | PC $\leftarrow \rightarrow$ Personal <br> computer or Com- <br> ponent | 1 to 1 | Can achieve simple communications se- <br> quences using communications port I/O <br> instructions (TXD, RXD), including data <br> input from a bar code reader and data <br> output to a printer. <br> Can control RS, CS, ER, and DR control <br> signals using the instructions. | TXD and <br> RXD instructions |
| 1 to 1 link | PC $\leftarrow \rightarrow$ PC | 1 to 1 | Connects two PCs on a one to one basis. <br> The PCs share LR Area data. | --- <br> NT Link <br> PC $\leftarrow \rightarrow$ PT |
| Protocol <br> macros | PC to 1 or <br> components | Achieves data communications by con- <br> necting PCs and PTs on a one to one ba- <br> sis or one to N basis. | --- |  |

Note Refer to the operation/system manuals for details on the Host Link procedure, non-procedure communication, 1:1 links, and NT Links. This manual provides details on only protocol macros.

## 1-1-3 Communications Board Models

The following Communications Boards are available.
The features that are to be used from among those listed below as "YES" for any particular Communications Board is specified in the PC Setup at startup.

| Type | Physical specification |  | Function |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | CPU bus | Host Link | Non-procedure | 1:1 link | $\begin{aligned} & \text { NT Link } \\ & (1: 1,1: N) \end{aligned}$ | Protocol macros |
| C200HW-COM01 | Communications Unit connection port | $\left[\begin{array}{l}\vdots \\ \vdots \\ \vdots \\ 1\end{array}\right.$ | YES | - | - | - | - | - |
| $\begin{array}{r} \text { C200HW-COM02-V1 } \\ 2^{*} \end{array}$ | RS-232C port | $\underbrace{\left[\begin{array}{ll} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{array}\right]}$ | - | YES | YES | YES | YES | - |
| $\begin{array}{r} \text { C200HW-COM03-V1 } \\ 2^{*} \end{array}$ | $\begin{aligned} & \text { RS-422A/ } \\ & 485 \text { port } \end{aligned}$ | $\underbrace{\left[\begin{array}{lll} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{array}\right]}$ | - | YES | YES | YES | YES | - |
| C200HW-COM04-EV1 | Communications Unit connection port |  | YES | - | - | - | - | - |
|  | RS-232C port |  | - | YES | YES | YES | YES | YES |
| C200HW-  <br> COM05-EV1  <br>  $3^{*}$ | RS-232C port | $\underbrace{1}\left[\begin{array}{lll} 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 \end{array}\right]$ | - | YES | YES | YES | YES | YES |
|  | RS-232C <br> port | $\underbrace{\left[\begin{array}{lll} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{array}\right]}$ | - | YES | YES | YES | YES | YES |


| Type |  | Physical specification |  | Function |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | CPU bus | Host Link | Non-procedure | 1:1 link | $\begin{gathered} \hline \text { NT Link } \\ (1: 1,1: N) \end{gathered}$ | Protocol macros |
| C200HW-COM06-EV1 | 3* | $\begin{aligned} & \text { RS-232C } \\ & \text { port } \end{aligned}$ |  | - | YES | YES | YES | YES | YES |
|  |  | $\begin{aligned} & \text { RS-422A/ } \\ & 485 \text { port } \end{aligned}$ |  | - | YES | YES | YES | YES | YES |

1* Interface to C200HW-CE001/CE002 Bus Connection Unit for Link Units such as Controller Link, SYSMAC LINK, or SYSMAC NET Link Units.
2* The RP command (program read) can be used in Host Link Mode when V1 Communications Boards are used with $\mathrm{C} 200 \mathrm{HX} / \mathrm{C} 200 \mathrm{HG} / \mathrm{C} 200 \mathrm{HE}-\mathrm{CPU} \square \square$-ZE CPU Units. The RP command cannot be used with the previous version of Communications Boards (those without " V 1 " in the model number.
$3^{\star}$ The following protocol macro functionality has been added to the V1 Communications Boards. The following are possible only for the C200HW-COM $\square \square$-(E)V1 Communications Boards.

- SUM2 (SUM of two's complement) and CRC-16 can be used for error checking.
- The Repeat Counter N Present Value, a Sequence End Flag, and a Sequence Abort Flag are provided in the SR area.
- The check code can be placed after the terminator in the message sequence.
- The upper and lower bytes of the error check code can be swapped.

Note When using a $1:$ N Host Link, $1:$ N NT Link, or a protocol macro using a RS-232C port, a RS-232C-to-RS-422A/485 Link Adapter (NT-AL001) is required.


C200HW-COM04-EV1


C200HW-COM05-EV1


C200HW-COM06-EV1


Note 1. V1 Communications Boards are compatible with C200HX/HG/HECPU $\square-$ ZE CPU Units.
2. EV1 Communications Boards are compatible with $\mathrm{C} 200 \mathrm{HX} / \mathrm{HG} / \mathrm{HE}-$ CPU $\square \square$-ZE CPU Units and have improved protocol macro functionality.

## 1-1-4 DIP Switch Settings

To use port A (RS-422A/485) on the C200HW-COM03-V1 or C200HW-COM06-EV1, the DIP switches on the Communications Board must be set according to the application conditions. being used:

> 2-wire: Set to 2
> 4-wire: Set to 4

When a Communications Board is the terminator for a $1: \mathrm{N}$ link during communications, turn ON this switch on the last Board and turn OFF this switch on the rest of the Boards.


The factory settings are as follows.
DIP switch SW1: 2 (2-wire)
DIP switch SW2: 1 (Terminator OFF)

## 1-1-5 Applicable CPU Units

The following table lists the models of CPU Units to which Communications Boards can be installed in the option slot.

| C200HX | C200HG | C200HE |
| :---: | :---: | :---: |
| C200HX-CPU64-E | C200HG-CPU63-E | C200HE-CPU42-E |
| C200HX-CPU54-E | C200HG-CPU53-E | C200HE-CPU32-E |
| C200HX-CPU44-E | C200HG-CPU43-E |  |
| C200HX-CPU34-E | C200HG-CPU33-E |  |
| C200HX-CPU85-ZE | C200HG-CPU63-ZE | C200HE-CPU42-ZE |
| C200HX-CPU65-ZE | C200HG-CPU53-ZE | C200HE-CPU32-ZE |
| C200HX-CPU64-ZE | C200HG-CPU43-ZE |  |
| C200HX-CPU54-ZE | C200HG-CPU33-ZE |  |
| C200HX-CPU44-ZE |  |  |
| C200HX-CPU34-ZE |  |  |

## 1-1-6 Installation

The following describes how to install a Communications Board in the option slot of the CPU Unit.

Caution Always turn off the power supply before installing or removing a Communications Board. If the power supply is kept ON while a Communications Board is being installed or removed, operational errors can occur in the CPU Unit, internal devices may be destroyed, or communications may fail.

1, 2, 3... 1. Open the Memory Cassette cover.

2. Remove the Communications Board cover.

3. Slide in the Communications Board in slit and press it all the way to the back.

4. Close the Memory Cassette cover.


## 1-1-7 Indicators

The status of the Communications Board is displayed on the LED indicators on the front of the CPU Unit.

| Indi- <br> cator | Color | Status | Meaning | Contents |
| :--- | :--- | :--- | :--- | :--- |
| RDY | Green | OFF | Not Ready | Communications Board hardware error |
|  |  | Flash | Setting error | The system setup or the contents of the <br> protocol data contains an error. |
|  | ON | Ready | The Communications Board is operating <br> normally and communications are en- <br> abled. |  |
| COMB | Orange | Flash | Communi- <br> cating | Port B is being used for communications <br> (ON when there is data). |
| COMA | Orange | Flash | Communi- <br> cating | Port A is being used for communications <br> (ON when there is data) |



Note The above description is based on the C200HW-COM05-EV1 and C200HW-COM06-EV1.

## 1-1-8 Communications Board Specifications

| Item | C200HW- <br> COM01 | C200HW- <br> COM02-V1 | C200HW- <br> COM03-V1 | C200HW- <br> COM04-EV1 | C200HW- <br> COM05-EV1 | C200HW- <br> COM06-EV1 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Current <br> consumption <br> at 5 V | 0.03 A | 0.1 A | 0.2 A | 0.1 A | 0.1 A | 0.2 A |
| External <br> dimensions | $42.5 \times 134 \times 98 \mathrm{~mm}(\mathrm{~W} \times \mathrm{H} \times \mathrm{D}$ ) |  |  |  |  |  |
| Weight | 100 g max. | 100 g max. | 105 g max. | 110 g max. | 110 g max. | $115 \mathrm{~g} \mathrm{max}$. |
| Standard <br> accessories | --- | Plug: XM2A-0901 (OMRON) $\times 1$ <br> Hood: XM2S-0911 (OMRON) $\times 1$ | Plug: $\mathrm{XM} 2 \mathrm{~A}-0901($ OMRON $) \times 2$ <br> Hood: XM2S-0911 (OMRON) $\times 2$ |  |  |  |

## 1-1-9 Basic Specifications

The basic specifications will be determined by the basic specifications of the C200HX/HG/HE(-Z) PC used.

## 1-1-10 Communications Specifications

The following tables provide the communications specifications of RS-232C and RS-422A/485 ports.

## RS-232C Port

| Item | Specification |
| :--- | :--- |
| Communications method | Half duplex |
| Synchronization | Start-stop |
| Baud rate | $1,200 / 2,400 / 4,800 / 9,600 / 19,200 \mathrm{bps}$ |
| Transmission method | Point-to-point |
| Transmission distance | 15 m max. |
| Interface | Complies with EIA RS-232C |

## Connector Pin Assignment



| Pin <br> No. | Signal name | Abbreviation | Signal direc- <br> tion |
| :--- | :--- | :--- | :--- |
| 1 | Safety ground | FG | - |
| 2 | Send data | SD | Output |
| 3 | Receive data | RD | Input |
| 4 | Send request | RS | Output |
| 5 | Send enabled | CS | Input |
| 6 | Power supply | 5 V | - |
| 7 | Dataset ready | DR | Input |
| 8 | Data terminal ready | ER | Output |
| 9 | Signal ground | SG | - |
| Shell | Safety ground | FG | - |

## Connectors

Plug: XM2A-0901 (OMRON) or equivalent
Hood: XM2S-0911 (OMRON) or equivalent
Note One plug and one hood are provided.
Recommended Cable
AWG28 $\times 5$ P IFVV-SB (manufactured by FUJIKURA DENSEN)
CO-MAVV-SB 5P $\times$ AWG28 (manufactured by HITACHI DENSEN) Line length: 15 m max.

## RS-422A/485 Port

| Item | Specification |
| :--- | :--- |
| Communications method | Half duplex |
| Synchronization | Start-stop |
| Baud rate | $1,200 / 2,400 / 4,800 / 9,600 / 19,200$ bps |
| Transmission method | Point-to-multipoint |
| Transmission distance | 500 m max. |
| Interface | Complies with EIA RS-422A/485 |


| Connector Pin Assignment | Pin No. | Signal name | Abbreviation | Signal direction |
| :---: | :---: | :---: | :---: | :---: |
|  | 1 | Send data - | SDA | Output |
| $6$ | 2 | Send data + | SDB | Output |
|  | 3 | Unused | NC | - |
|  | 4 | Unused | NC | - |
|  | 5 | Unused | NC | - |
| $\left\|\begin{array}{ll} 0 & 0 \end{array}\right\|$ | 6 | Receive data - | RDA | Input |
|  | 7 | Unused | NC | - |
| $9$ | 8 | Receive data + | RDB | Input |
|  | 9 | Unused | NC | - |
|  | Shell | Safety ground | FG | - |

Note When the 2-wire communications is set, use 1 and 2, or 6 and 8 .

## Connectors

Plug: XM2A-0901 (OMRON) or equivalent
Hood: XM2S-0911 (OMRON) or equivalent

Note One plug and one hood are provided.

AWG28 $\times 5$ P IFVV-SB (manufactured by FUJIKURA DENSEN) CO-MAVV-SB 5P $\times$ AWG28 (manufactured by HITACHI DENSEN) Line length: 500 m max.

## 1-1-11 Communications Modes and Transmission Paths

The following table shows the transmission paths that can be used for each of the communications modes.

| Communications <br> mode | RS-232C | 4-wire 1:1 | 4-wire 1:N | 2-wire 1:1 | 2-wire 1:N |
| :--- | :--- | :--- | :--- | :--- | :--- |
| 1:N Host Link | YES | YES | YES | NO | NO |
| Non-procedure | YES | YES | YES | NO | NO |
| $1: 1$ link | YES | YES | NO | NO | NO |
| 1:1 NT Link | YES | YES | NO | NO | NO |
| 1:N NT Link | NO | YES | YES | YES | YES |
| Protocol macros | YES | YES | YES | YES |  |

## 1-2 Hardware Connections

The connections of the Communications Board to an external device with a RS-232C or RS-422A/485 port are shown below.

## Host Link Connections




## Computer Connections (Cross Connection)

IBM PC/AT or Compatible Computer
Computer C200HX/C200HG/C200HE

| 1 |  | , | 1 | FG |
| :---: | :---: | :---: | :---: | :---: |
| 2 | RD | 1 | 2 | SD |
| 3 | SD |  | 3 | RD |
| 4 |  |  | 4 | RS |
| 5 | SG |  | 5 | CS |
| 6 |  |  | 6 | 5 V |
| 7 | RS |  | 7 | DR |
| 8 | CS |  | 8 | ER |
| 9 |  |  | 9 | SG |

## Modem Connections (Straight)

Same for the 3G2A9-AL004-E Link Adapter

Modem

| 1 | FG |
| :---: | :---: |
| 2 | SD |
| 3 | RD |
| 4 | RS |
| 5 | CS |
| 6 | DR |
| 7 | SG |
| 8 | CD |
| 9 |  |
| 10 |  |
| 11 |  |
| 12 |  |
| 13 |  |
| 14 |  |
| 15 | ST2 |
| 16 |  |
| 17 | RT |
| 18 |  |
| 19 |  |
| 20 | ER |
| 21 |  |
| 22 | CI |
| 23 |  |
| 24 | ST1 |
| 25 |  |

C200HX/C200HG/C200HE

| 1 | FG |
| :---: | :---: |
| 2 | SD |
| 3 | RD |



5


## 1-3 PC Setup

Various parameters in the PC Setup relating to the Communications Board must be specified in advance for each RS-232C (or RS-422A/485) port to perform communications using the Communications Board. The Communications Board settings that are allocated to the PC Setup in the DM Area of the PC are shown in the following table.
Note 1. Specify the Communications Board system settings using the DM monitor function of the SYSMAC Support Software or System Settings of the Protocol Support Software. When the settings are incorrect (outside of the range or contradiction errors), the system will operate with the initial settings (default values). However, setting data remains in DM as it is.
2. The system error FAL-9C and a FAL-9B will be generated if errors are detected.

| Word | Bit | Mode | Details |  |  | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DM 6550 | 00 to 03 | Host Link Non-procedure Protocol macro | Port B communications parameter, standard settings enable <br> 1: Individual settings $\rightarrow$ Settings in DM6551 used. |  |  | --- |
|  | 04 to 07 | Host Link Non-procedure 1:1 link | CTS control enable <br> 0 : Disabled (default) <br> 1: CTS enabled |  |  | --- |
|  | 08 to 11 | 1:1 link master 1:N NT Link | Port B 1:1 link master: Link words <br> 0: LR00 to LR63 (default) 1: LR00 to LR31 <br> 2: LR00 to LR15 <br> Port B 1:N NT Link: Maximum PT unit No. <br> 1 to 7 (BCD) or 1 to 3 for C200HE-CPU $\square \square-E$ |  |  | Cannot be changed $1: 1$ link is set. |
|  | 12 to 15 | All modes | Port B mode <br> 0: Host Link (default) <br> 4: 1:1 NT Link <br> 1: RS-232C non-procedure <br> 5: 1:N NT Link <br> 2: 1:1 link slave <br> 6: Protocol macro <br> 3: 1:1 link master |  |  |  |
| DM 6551 | 00 to 07 | Host Link Non-procedure Protocol macro | Port B baud rate (bps)   <br> 00:1200 (default) $02: 4800$ $04: 19200$ <br> $01: 2400$ $03: 9600$  |  |  | Valid for individual settings only (see DM6550, bits 00 to 03) |
|  | 08 to 15 | Host Link Non-procedure Protocol macro | Port B frame format (default: 00)   <br>  Start bits Data length <br> $00:$ 1 7 <br> $01:$ 1 7 <br> $02:$ 1 7 <br> $03:$ 1 7 <br> $04:$ 1 7 <br> $05:$ 1 7 <br> $06:$ 1 8 <br> $07:$ 1 8 <br> $08:$ 1 8 <br> $09:$ 1 8 <br> $10:$ 1 8 <br> $11:$ 1 8 | Stop bits | Parity Even Odd None Even Odd None Even Odd None Even Odd None |  |


| Word | Bit | Mode | Details | Remarks |
| :---: | :---: | :---: | :---: | :---: |
| DM 6552 | 00 to 15 | Host Link Non-procedure | Port B send delay: 0000 (default) to 9999: Unit 10 ms | Check if RS-232C port communications are not possible (Max. delay; 99 s ) |
| DM 6553 | 00 to 07 | Host Link | Port B Host Link mode unit No. 00 (default) to 31 (unit No.) |  |
|  | 08 to 11 | Non-procedure | Port B non-procedure mode start code enable 0: Disabled (default); 1: Enabled | Valid when non-procedure mode start code is enabled in, DM6554, bits 00 to 07 |
|  | 12 to 15 | Non-procedure | Port B non-procedure mode end code enable <br> 0 : Disable (Specify the number of receive data items) (default) <br> 1: Enable (Specify the end code) <br> 2: CR, LF | If 0 : DM6554 contains number of receive data items. <br> If 1: DM6554 contains the end code. <br> If 2: DM6554 may contain any data. |
| DM 6554 | 00 to 07 | Non-procedure | Port B non-procedure mode start code 00 (default) to FF (binary) | Valid when non-procedure start code is enabled. <br> Can be updated. |
|  | 08 to 15 | Non-procedure | Port B <br> When 0 is specified in DM6553: <br> 12 to 15 <br> Number of non-procedure receive data items (binary) <br> 00: (default: 256 bytes) <br> 01 to FF:(1 to 255 bytes) <br> When 1 is specified in DM6553: <br> 12 to 15 <br> Non-procedure mode end code (binary) <br> 00 (default) to FF | Invalid when non-procedure end code is enabled <br> 00: Default (256 bytes) |
| DM 6555 | 00 to 03 | Host Link Non-procedure Protocol macro | Port A communications parameter, standard settings enable <br> 1: Individual settings $\rightarrow$ Settings in DM6556 used. | --- |
|  | 04 to 07 | Host Link Non-procedure 1:1 link | CTS control enable <br> 0: Disabled (default) <br> 1: CTS enabled | --- |
|  | 08 to 11 | 1:1 link master 1:N NT Link | Port A 1:1 link master: Link words <br> 0: LR00 to LR63 (default) 1: LR00 to LR31 <br> 2: LR00 to LR15 <br> Port A 1:N NT Link: Maximum PT unit No. <br> 1 to 7 (BCD) or 1 to 3 for C200HE-CPU $\square \square$-E | Cannot be changed $1: 1$ link is set. |
|  | 12 to 15 | All modes | Port A mode <br> 0: Host Link (default) <br> 4: 1:1 NT Link <br> 1: RS-232C non-procedure <br> 5: 1:N NT Link <br> 2: 1:1 link slave <br> 6: Protocol macro <br> 3: 1:1 link master |  |


| Word | Bit | Mode | Details |  |  |  | Remarks |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DM 6556 | 00 to 07 | Host Link Non-procedure Protocol macro | Port A baud rate 00:1200 (default) 01:2400 | bps) $\begin{aligned} & 02: 4800 \\ & 03: 9600 \end{aligned}$ | 04:19200 |  | Valid for individual settings only (see DM6555, bits 00 to 03) |
|  | 08 to 15 | Host Link Non-procedure Protocol macro | Port A frame form | $\begin{aligned} & \text { at (default: 00) } \\ & \text { Data length } \\ & 7 \\ & 7 \\ & 7 \\ & 7 \\ & 7 \\ & 7 \\ & 8 \\ & 8 \\ & 8 \\ & 8 \\ & 8 \\ & 8 \\ & \hline \end{aligned}$ | Stop bits 1 1 1 2 2 2 1 1 1 2 2 2 | Parity <br> Even <br> Odd <br> None <br> Even <br> Odd <br> None <br> Even <br> Odd <br> None <br> Even <br> Odd <br> None |  |
| DM 6557 | 00 to 15 | Host <br> Link <br> Non-pro- <br> cedure | Port A send delay: 0000 (default) to 9999: Unit 10 ms |  |  |  | Check if RS-232C port communications are not possible (Max. delay; 99 s) |
| DM 6558 | 00 to 07 | Host Link | Port A Host Link mode unit No. 00 (default) to 31 (unit No.) |  |  |  |  |
|  | 08 to 11 | Non-procedure | Port A non-procedure mode start code enable <br> 0: Disabled (default); 1: Enabled |  |  |  | Valid when non-procedure mode start code is enabled in, <br> DM6559, bits 00 to 07 |
|  | 12 to 15 | Non-procedure | Port A non-procedure mode end code enable <br> 0 : Disable (Specify the number of receive data items) (default) <br> 1: Enable (Specify the end code) <br> 2: CR, LF |  |  |  | If 0: DM6559 contains number of receive data items. <br> If 1: DM6559 contains the end code. <br> If 2: DM6559 may contain any data. |
| DM 6559 | 00 to 07 | Non-procedure | Port A non-procedure mode start code 00 (default) to FF (binary) |  |  |  | Valid when non-procedure start code is enabled. <br> Can be updated. |
|  | 08 to 15 | Non-procedure | Port A <br> When 0 is specified in DM6558: <br> 12 to 15 <br> Number of non-procedure receive data items (binary) <br> 00: (default: 256 bytes) <br> 01 to FF:(1 to 255 bytes) |  |  |  | Invalid when non-procedure end code is enabled <br> 00: Default (256 bytes) |

## 1-4 SR Words and Bits

The following table shows assignment of SR words and bits to the Communications Board in the PC.

| Word | Bit(s) | Function name | Read/ Write |
| :---: | :---: | :---: | :---: |
| SR 268 <br> Communications Board information for FAL9C | 00 | Hardware error for the Communications Board | R |
|  | 01 | Port recognition error (hardware error) | R |
|  | 02 | Protocol data error (protocol data checksum error due to memory corruption) | R |
|  | 03 to 10 | Reserved for future expansion | R |
|  | 11 | Port B protocol macro error (error relating PMCR) | R |
|  | 12 | Port A protocol macro error (error relating PMCR) | R |
|  | 13 to 15 | 15: System setting error <br> 14: Above error for port A <br> 13: Above error for port B | R |
| SR 283 | 00 to 03 | Port A error code <br> $0:$ No error (all modes) <br> 1:Parity error (all modes) <br> 2:Framing error (all modes) <br> 3:Overrun error (all modes) <br> 4:Timeout error (1:1 link master, 1:1 link slave mode) | R |
|  | 04 | ON for communication error at port A (all modes) | R |
|  | 05 | Port A Send Ready Flag (Host Link, non-procedure mode) | R |
|  | 06 | Port A Reception Completed Flag (Non-procedure mode) | R |
|  | 07 | Non-procedure mode: Port A Reception Overflow Flag Protocol macro mode: Port A Sequence Abort Flag (see note 1) | R |
|  | 08 to 11 | Port B error codes <br> $0:$ No error (all modes) <br> 1:Parity error (all modes) <br> 2:Framing error (all modes) <br> 3:Overrun error (all modes) <br> 4:Timeout error (1:1 link master, 1:1 link slave mode) | R |
|  | 12 | ON for communication error at port B (all modes) | R |
|  | 13 | Port B Send Ready Flag (Host Link, non-procedure mode) | R |
|  | 14 | Port B Reception Completed Flag (Non-procedure mode) | R |
|  | 15 | Non-procedure mode: Port B Reception Overflow Flag Protocol macro mode: Port B Sequence Abort Flag (see note 1) | R |
| SR 284 | 00 <br> to 07 | 1:N NT Link Mode: <br> Port A Communications In-progress Flag for Unit PTO <br> to <br> Port A Communications In-progress Flag for Unit PT7 <br> Protocol Macro Mode: <br> Port A Repeat Counter Present Value (see note 1) | R |
|  | 00 to 15 | Port A Receive Counter (non-procedure mode) | R |
| SR 285 | 00 <br> to <br> 07 | 1:N NT Link Mode: <br> Port B Communications In-progress Flag for Unit PTO <br> to <br> Port B Communications In-progress Flag for Unit PT7 <br> Protocol Macro Mode: <br> Port B Repeat Counter Present Value (see note 1) | R |
|  | 00 to 15 | Port B Receive Counter (non-procedure mode) | R |


| Word | Bit(s) | Function name | Read/ Write |
| :---: | :---: | :---: | :---: |
| SR 286 | 00 | Port A Trace In-progress Flag (both continuous/short traces) (protocol macro mode) (see note 2) | R |
|  | 01 | Port B Trace In-progress Flag (both continuous/short traces) (protocol macro mode) (see note 2) | R |
|  | 02 to 05 | Reserved for future expansion. | R |
|  | 06 | Port A Echoback Disabled Flag (for modem control in protocol macro mode; see note 3.) | R |
|  | 07 | Port B Echoback Disabled Flag (for modem control in protocol macro mode; see note 3.) | R |
|  | 08 to 11 | Port A Protocol macro error code (protocol macro mode) <br> 0:No error 1:No protocol macro function 2:Sequence number error <br> 3:Receive data write area exceeded (IOM area exceeded) <br> 4:Protocol data error <br> 5: Protocol macro executed during port initialization | R |
|  | 12 to 15 | Port B Protocol macro error code (protocol macro mode) 0:No error 1:No protocol macro function 2:Sequence number error 3 :Receive data write area exceeded (IOM area exceeded) <br> 4:Protocol data error <br> 5: Protocol macro executed during port initialization | R |
| SR 287 | 00 to 03 | Port A Executed Reception Matrix Case No. (0 to F) (protocol macro mode) | R |
|  | 04 to 07 | Port A Executed Step No. (0 to F) (protocol macro mode) | R |
|  | 08 to 14 | Not used. | R |
|  | 15 | Port A SR 287 Stored Flag 0:Not stored;1:Stored | R |
| SR 288 | 00 to 03 | Port B Executed Reception Matrix Case No. (0 to F) (protocol macro mode) | R |
|  | 04 to 07 | Port B Executed Step No. (0 to F) (protocol macro mode) | R |
|  | 08 to 14 | Not used. | R |
|  | 15 | Port B SR 288 Stored Flag $0:$ Not stored;1:Stored | R |


| Word | Bit(s) | Function name | Read/ Write |
| :---: | :---: | :---: | :---: |
| SR 289 | 00 | Port A Restart Bit (all modes) | W |
|  | 01 | Port B Restart Bit (all modes) | W |
|  | 02 | Port A Continuous Trace Start/Stop Bit (protocol macro mode) (see note 2) | W |
|  | 03 | Port B Continuous Trace Start/Stop Bit (protocol macro mode) (see note 2) | W |
|  | 04 | Port A Short Trace Start/Stop Bit (protocol macro mode) (see note 2) | W |
|  | 05 | Port B Short Trace Start/Stop Bit (protocol macro mode) (see note 2) | W |
|  | 06 | Port A Echoback Disable Bit (for modem control in protocol macro mode; see note 3.) | W |
|  | 07 | Port B Echoback Disable Bit (for modem control in protocol macro mode; see note 3.) | W |
|  | 08 | Port A Instruction Execution Flag (at execution of instruction) | R |
|  | 09 | Port A Step Error Processing Flag (protocol macro mode) | R |
|  | 10 | Port A Sequence End Flag (protocol macro mode) (see note 1) | R |
|  | 11 | Port A Abort Bit (protocol macro mode) | W |
|  | 12 | Port B Execution Instruction Flag (at execution of instruction) | R |
|  | 13 | Port B Step Error Processing Flag (protocol macro mode) | R |
|  | 14 | Port B Sequence End Flag (protocol macro mode) (see note 1) | R |
|  | 15 | Port B Abort Bit (protocol macro mode) | W |

Note 1. Supported only by the C200HW-COM04/05/06-EV1 Communications Boards.
2. These flags can be used only from the Protocol Support Software. They cannot be used in the ladder-diagram program.
3. These bits/flags are only available for models with lot number 0140 or later. The meaning of lot numbers is shown below.

Lot No: $\underline{0140}$ Manufactured on April 1st, 2000.


The year is indicated with the last digit. In this case, "0" indicates "2000."
Month of manufacture. October, November, and December are indicated with $X, Y$, and $Z$ respectively. In this case, the month is "April."
Day of manufacture. In this example, the day is "1."

## SECTION 2 <br> Protocol Macros

This section describes the protocol macro function supported by the Communications Board, and how to use the standard macros. Troubleshooting is also described.
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## 2-1 Outline

Protocol macros are used to create user communications procedure. The Protocol Support Software is used to create protocol macros, which can then be executed using the PMCR instruction to communicate with various devices connected to the RS-232C or RS-422A/485 port.
Twelve protocol macros are provided as standard communications protocols in the Communications Boards (COM04-EV1, COM05-EV1, and COM06-EV1) and in Protocol Support Software. These macros can be used as they are or they can be modified.


Protocols consist of send/receive sequences. A protocol is transferred to the Communications Board and then the required sequence is executed by specifying the sequence number in the PMCR instruction in the PC. A sequence consists of commands recorded in steps. Steps can be repeated, or they can be branched or ended depending on the responses received.


## 2-1-1 Protocol Macro Features

Support for a Wide Range of Communications Protocols

Create the Required Communications Frames

## Data Processing for Communications

## Send/Receive Time Monitoring

Retry Processing

PC Read/Write Variables in Send/Receive Frames

Repeat Counters

Improved Protocol Macros

Communications are possible using protocol macros with essentially any external device that has an RS-232C, RS-422A, or RS-485 port and supports half-du-plex/stop-start synchronization.
Essentially any communications frames can be created to fit the message specifications of the external device: command + data and other send frames, and anticipated response frames.
Error check code calculations, send frame length calculations, and ASCII-Hex conversions are all supported.

Reception time, reception end monitoring, and send end monitoring are supported. You can either retry or end processing with these times are exceeded.

The number of retries can be set to automatically repeat send/receive operations that end in errors.

Variables for reading PC I/O memory can be included in send message frames for use as addresses or data when reading PC data. Variables for writing PC I/O memory can be included in receive message frames for use as addresses or data when writing PC data

Repeat counters can be used can be used for send/receive processing to enable 1:N communications by switching addresses to send the same data, or to change write addresses when receiving data to write to PC I/O memory.

The following points have been improved in the protocol macro functionality for the C200HW-COM04/05//06-EV1 Communications Boards.

- Addition of SUM2 (2's complement of SUM) and CRC-16 error check codes.
- Addition of the following to the SR Area data: Repeat Counter N Present Value, Sequence End Flag, and Sequence Abort Flag.
- Specification of the check code after the terminator in the message sequence.
- Reverse direction for error check codes.


## 2-1-2 Connections

Connection to Devices with
RS-232C Interface
(C200HW-COM05-EV1
Example) C200HX/C200HG/C200HE
A 1:1 connection (cable length: up to 15 m ) is used for a RS-232C port. The following diagram shows the connections for a RS-232C port.


The connections required to use protocol macros are shown below.

## Connection to Devices with RS-422A/485 Interface (C200HW-COM06-EV1 Example)

A 1:N connection (cable length: up to 500 m ) can be used for a RS-422A/485 port. These connections are also useful for longer cable distances with a $1: 1$ connection. For $1: \mathrm{N}$ connections, up to 32 devices can be connected. (With 2 -wire communications, this figure includes the Communications Board whereas with 4 -wire communications it does not.) The following diagram shows the connections for a RS-422A/485 port.


Note 1. The total length of RS-232C cable must be 15 m max. If the length exceeds 15 m , normal operation cannot be guaranteed.
2. The total length of RS-422A/485 cable must be 500 m max. and each branch line must be 10 m max. If the total length exceeds 500 m or branch lengths exceed 10 m , normal operation cannot be guaranteed.

## 2-Wire Connections (PC is Master)

Connecting an RS-422A/485 Port

The following diagram shows the wiring configuration for connecting devices that support RS-422A/485 2-wire communications to the RS-422A/485 port of the C200HW-COM06-EV1 Communications Board.
Connections can be either 1:1 or $1: \mathrm{N}$. Up to 32 Units can be connected for $1: \mathrm{N}$ communications, including the Communications Board.


## Connecting an RS-232C

 PortThe following diagram shows the wiring configuration for connecting devices that support RS-422A/485 2-wire communications to the RS-232C port of a Communications Board (C200HW-COM04-EV1 port A, C200HW-COM05-EV1 port A/B, or C200HW-COM06-EV1 port B).
This application requires an NT-AL001-E Link Adapter (sold separately).
Connections can be either 1:1 or 1:N. Up to 32 Units can be connected for $1: \mathrm{N}$ communications, including the Communications Board.


## Connecting an RS-422A/485 Port

The following diagram shows the wiring configuration for connecting devices that support RS-422A/485 4 -wire communications to the RS-422A/485 port of the C200HW-COM06-EV1 Communications Board.

Connections can be either 1:1 or 1:N. Up to 32 Units can be connected for $1: \mathrm{N}$ communications, including the Communications Board.


## Connecting an RS-232C Port

The following diagram shows the wiring configuration for connecting devices that support RS-422A/485 4-wire communications to the RS-232C port of a Communications Board (C200HW-COM04-EV1 port AC200HW-COM04-EV1 port A, C200HW-COM05-EV1 port A/B, or C200HW-COM06-EV1 port B). This application requires NT-AL001-E Link Adapters (sold separately).

Connections can be either 1:1 or 1:N. Up to 32 Units can be connected for $1: \mathrm{N}$ communications, including the Communications Board.

| Communications Board |  |  |  | NT-AL001-E Link Adapter |  |  |  |  | 3G2A9-AL001-E Link Adapter |  |  |  |  |  |  | Shield | RS-422A/485 (4-wire) device |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RS-232 Interface | Signal name | Pin No. | Shield | Pin <br> No. | Signal name | Signal name | Pin No. | Shield | $\begin{aligned} & \text { Pin } \\ & \text { No. } \end{aligned}$ | Signal name | RS-422A <br> Interface |  |  | Signal name | Pin No. |  | Signal name | RS-422A Interface |
|  | FG | 1 | T | 1 | NC | GRD | 1 |  | 9 | SDA |  |  |  | SDA | 9 |  | SDA |  |
|  | SD | 2 |  | 2 | SD | SG | 2 |  | 5 | SDB |  |  |  | SDB | 5 |  | SDB |  |
|  | RD | 3 |  | 3 | RD | SDB | 3 |  | 6 | RDA |  |  |  | RDA | 6 |  | RDA |  |
|  | RS | 4 |  | 4 | RS | SDA | 4 |  | 1 | RDB |  |  |  | RDB | 1 |  | RDB |  |
|  | CS | 5 |  | 5 | CS | RDB | 5 |  | 3 | SG |  |  |  | SG | 3 | - |  |  |
|  | 5 V | 6 |  | 6 | 5 V | RDA | 6 |  | 7 | FG |  |  |  | FG | 7 | $\checkmark$ |  |  |
|  | DR | 7 |  | 7 | DR | CSB | 7 |  | Signal | SDA | SDB | RDA | RDB | SG | FG | D-sub, 9-pin connector (male) |  |  |
|  | ER | 8 |  | 8 | ER | CSA | 8 |  | Pin No. | . 9 | 5 | 6 | 1 | 3 | 7 |  |  |  |  |
|  | SG | 9 |  | 9 | SG |  |  | D-sub, 9-pin connector (male) |  |  |  |  |  |  |  | Shield |  |  |
|  | D-sub, 9-pin connector (male) |  |  | RS-232 |  | RS-422 |  |  |  |  |  |  |  |  | 3 |  |  |  |
|  |  |  |  | D-sub, 9-pin Termina <br> connector block <br> (male)  |  |  |  |  |  |  |  |  |  |  |  |  | RS-422A/485 <br> (4-wire) device |  |
|  |  |  |  |  | $\begin{array}{\|l\|} \hline \text { Signal } \\ \text { name } \\ \hline \end{array}$ | SDA | SDB | RDA | RDB | SG | FG |  |  |  |  |  |
|  |  |  |  |  |  |  |  | DIP Switch settings <br> Pin 1: ON <br> Pin 2: ON <br> (termination resistance) <br> Pin 3: OFF <br> Pin 4: OFF <br> Pin 5: OFF <br> Pin 6: ON |  |  |  |  | Pin No. | - 9 | 5 | 6 |  |  | 1 | 3 | 7 |  |
|  |  |  |  |  | Pin No. | Signal name | RS-422A Interface |  | Signal name |  | Pin <br> No. | Shield | Signal name | RS-422A Interface |  |  |  |  |
|  |  |  |  |  | 9 | SDA |  |  |  |  |  |  |  |  | SDA | 9 | SDA |  |
|  |  |  |  |  | 5 | SDB |  |  |  |  |  |  |  |  | SDB | 5 |  | SDB |
|  |  |  |  |  | 6 | RDA |  |  |  |  |  |  |  |  | RDA | 6 |  | RDA |
|  |  |  |  |  | 1 | RDB |  |  |  |  |  |  |  |  | RDB | 1 |  | RDB |
|  |  |  |  |  | 3 | SG |  |  |  |  |  |  |  | SG | 3 |  |  |  |
|  |  |  |  |  | 7 | FG |  |  |  |  |  |  |  | FG | 7 | V |  |  |

## Using Personal Computer as Master (PC is Slave)

Connecting an RS-422A/485 Port
The following diagram shows the wiring configuration for connecting devices that support RS-422A/485 4-wire communications to the RS-422A/485 port of the C200HW-COM06-EV1 Communications Board.

Connections can be either 1:1 or 1:N. Up to 32 Units can be connected for $1: \mathrm{N}$ communications, including the Communications Board.


## Connecting an RS-232C Port

The following diagram shows the wiring configuration for connecting devices that support RS-422A/485 4-wire communications to the RS-232C port of a Communications Board (C200HW-COM04-EV1 port A, C200HW-COM05-EV1 port A/B, or C200HW-COM06-EV1 port B).
This application requires NT-AL001-E Link Adapters (sold separately).

Connections can be either 1:1 or $1: \mathrm{N}$. Up to 32 Units can be connected for $1: \mathrm{N}$ communications, including the Communications Board.


## 2-1-3 PC Setup

## Communications Mode

Protocol macro: Set the DM6550 bits 12 to 15 to 6 (RS-232C port B)
Set the PC Setup as described next to communicate using a protocol macro.

Set the DM6555 bits 12 to 15 to 6 (RS-232C port A)

## Communications Parameters

Any conditions can be set. The following communications parameters are used for the default settings:

| Start bits: | 1 bit |
| :--- | :--- |
| Data length: | 7 bits |
| Parity: | Even |
| Stop bits: | 2 bits |
| Baud rate: | 9,600 bps |

Note 1. See 1-3 PC Setup for the PC Setup procedure.
2. The system is initially set to the default settings. The default settings must be changed to use any other settings for the protocol macro function.

## 2-1-4 Structure of Protocol Macros

The protocol macro function allows a user to create original communications procedure. Users can freely edit communications procedures (called communications sequences) for various communications devices, such as generalpurpose components connected to RS-232C or RS-422A/485 interfaces, and can execute these procedures using the PMCR instruction.

## Structure of Communications Sequences

Up to 1,000 ( 0 to 999 ) sequences can be registered and used. Each communications sequence consists of up to 16 steps.


## Communications Sequence Settings

The settings that can be made for communications sequence using the Protocol Support Software are shown in the following table.

| Unit | Item | Contents | Settings |
| :---: | :---: | :---: | :---: |
| Sequence | Transmission control | Set transmission control method such as X-on/X-off flow control or RS/CS flow control. | X-on/X-off, RTS/CTS, modem control, delimiter control, and contention control |
|  | Link words | Set words for which data is shared between the PC and a Communications Board. | IR, LR, HR, AR, DM, or EM address |
|  | Wait times | Set wait times for communications processing. | Receive wait, receive finish, send finish <br> Units of $0.01 \mathrm{~s}, 0.1 \mathrm{~s}, 1 \mathrm{~s}$, or 1 min |
|  | Response method | Set the timing for writing data that was received. | Scan or interrupt notification (see note 1) |
| Step | Repeat counter | Set the repeat count for the step. | Constants 1 to 255 , or IR, LR, HR, AR, DM, or EM address |
|  | Commands | Set the communications commands. | Send, Recv, or Send \& Recv |
|  | Retry count | Set an error retry count when the command setting is Send\&Recv. | 0 to 9 |
|  | Send wait time | Set the wait time required to send data at transmission. | Units of $0.01 \mathrm{~s}, 0.1 \mathrm{~s}, 1 \mathrm{~s}$ or 1 min |
|  | Send message | Set send data when the command is Send or Send\&Recv. | Header, address, length, data, error check code, and terminator |
|  | Receive message | Set expected receive data when the command is Recv or Send\&Recv. | Header, address, length, data, error check code, and terminator (see note 3) |
|  | Receive matrix | Set expected receive data (up to 15 sets) and change the processing according to the receive data when the command is Recv or Send\&Recv. | Header, address, length, data, error check code, terminator, next process |
|  | With/without response | Set whether the data that was received is written. | Yes or no (see note 2) |
|  | Next process | Set the next step to which control is to be passed when a step is terminated normally. | End, Goto, Next Abort |
|  | Error process | Set the next step to which control is to be passed when a step is terminated in error. | End, Goto, Next Abort |

Note 1. Valid only when "Yes" is specified for response notification.
2. When a response method is set, "Yes" must be set for response notification. If "No" is set for response notification, the specified response method will be invalid.
3. If protocol macro is executed with 31 or more write data attributes registered in one message, a protocol data error and a FAL-9C (non-fatal system error) will be generated.

## 2-2 Protocol Support Software

The Protocol Support Software was developed to allow users to create specific protocols using the protocol macro function supported by Communications Boards. The Protocol Support Software contains system protocols. These system protocols can be used as they are or can be used after modification.

## 2-2-1 Models

The following models of Protocol Support Software are available.

| Name | Specifications | Model No. |
| :--- | :--- | :--- |
| Protocol Support Software <br> (PSS) | MS-DOS, Ver. 6. $\square$ | C200HW-ZW3AT1-E |
| Protocol Support Tool <br> (SYSMAC-PST) <br> (for C200HX/HG/HE PCs) | Windows 95 | WS01-PSTF1-E |
| CX-Protocol <br> (for CS1 and <br> C200HX/HG/HE PCs) | Windows 95/98 | WS02-PSTC1-E |

## 2-2-2 Features of the Protocol Support Software

The features of the Protocol Support Software are outlined below.

System Protocols

Simultaneously Monitor
Tree and Table Displays

Object Oriented Operation

## Trace Send/Receive

Messages

System protocols are provided for data transfer for OMRON Temperature Controllers, Panel Meters, Intelligent Signal Processors, Bar Code Readers, Modems, and other components.
With the Protocol Support Tool for Windows 95/98, you can display data in a tree hierarchy on the left side of the screen to monitor present values and set values and still be able to easily see overall data relationships.
With the Protocol Support Tool for Windows 95/98, you can activate dialog boxes by double-clicking objects instead of using the menus, enabling easy creation of protocols without having to learn complex menu operations.
Trace operations can be executed from the Protocol Support Software to trace up to 670 bytes of text string data when the Communications Board sends and receives messages. The data that is recorded can be read and displayed or it can be saved in trace files.

## 2-2-3 Connecting the Protocol Support Software

The following diagrams show how to connect an RS-232C port on a computer to either the peripheral connector on the CPU Unit or an RS-232C port on the Communications Board.

| RS-232C port


Note A D-sub 25-pin (female) to 9-pin (female) converter is requite at the computer.

## 2-2-4 Function List

The following table lists functions of the Protocol Support Software.

| Function name | Subfunction | Contents |
| :---: | :---: | :---: |
| Protocol list | --- | Displays a list of the protocols that are registered. |
|  | Create Protocol | Creates a new protocol. |
|  | Delete protocol | Deletes a protocol. |
|  | Copy protocol | Copies a protocol. |
|  | Change protocol name | Changes a protocol name. |
|  | Sequence No. range | Sets the sequence numbers to be used by the protocol. |
| Save | Save all | Saves the protocol data and system settings. |
|  | Save protocol | Saves the protocol data of the specified protocol. |
|  | Save system settings | Saves the system settings. |
| Retrieve | Retrieve all | Retrieves the protocol data and system settings. |
|  | Retrieve protocol | Retrieves the protocol data of the specified protocol. |
|  | Retrieve system settings | Retrieves the system settings. |
| System settings | Environment | Sets the printer and a default data directory path. |
|  | Communications | Sets the PC communications parameters. |
|  | PC setup | Sets the PC setup. |
| Transfer/Protocol | PC protocol list | Displays a list of protocols that are registered for the PC. |
|  | File protocol list | Displays a list of protocols in an object file. |
|  | PC $\rightarrow$ Computer | Reads protocol data from the PC. |
|  | Computer $\rightarrow$ PPC | Writes protocol data to the PC. |
|  | Computer $\longrightarrow$ PC | Compares protocol data between the PC and support software. |
|  | Protect | Sets/releases protection of protocol data. |
| Transfer/PC setup | PC $\rightarrow$ Computer | Reads setup information from the PC. |
|  | Computer $\rightarrow$ P PC | Writes setup information to the PC. |
| Area monitor | --- | Changes the monitor word or the present value of the specified word. |
| Trace/Read trace | --- | Traces a transmission line and reads trace data. |
| Print | Print all | Prints all protocol data. |
|  | Print protocol | Prints the protocol data of the specified protocol. |


| Function name | Subfunction |  |
| :--- | :--- | :--- |
| Files | Files | Displays a file list of the specified drive. |
|  | Copy file | Copies the specified file. |
|  | Delete file | Deletes the specified file. |
|  | Change name | Changes the name of the specified file. |
|  | Change drive | Changes the drive of the file display. |
| Communications se- <br> quence list | --- | Displays a list of sequences in the specified protocol. |
|  | Copy sequence | Copies the specified sequence. |
|  | Delete sequence | Deletes the sequence. |
|  | Change sequence name | Changes the name of the specified sequence. |
| Seive message list/ Re- | --- | Displays a list of send messages and received messages in the <br> specified protocol. |
|  | Copy message | Copies the specified message. |
|  | Delete message | Deletes the specified message. |
|  | Change message name | Changes the message name of the specified message. |
|  | --- | Display a list of receive matrices of the specified protocol. |
|  | Copy matrix | Copies the specified matrix. |
|  | Delete matrix | Deletes the specified matrix. |
|  | Change matrix name | Changes the matrix name of the specified matrix. |
| Edit communications <br> sequence | --- | Edits a communications sequence. |
| Edit send message/ <br> Edit receive message | --- | Edits send/receive messages. |
| Edit receive matrix | --- | Edits a receive matrix. |

## 2-2-5 Computer Requirement

This section shows the operating environment for the Protocol Support Software.

## MS-DOS (PSS)

| Item | Condition |
| :--- | :--- |
| CPU | $80386 / 80486$ |
| Memory | 440 k bytes or more free |
| Hard disk | 1M bytes or more free |
| Floppy disk drive | 1 drive min. |
| Extended memory | 1 M byte or more of extended memory is desirable to use the <br> software comfortably. |
| Operating system | MS-DOS V6. $\square$ |
| Display | $640 \times 480$ dots (VGA) |
| Keyboard | 101,106 keyboard |

## Windows 95/98 (SYSMAC-PST)

| Item | Minimum | Recommended |
| :--- | :--- | :--- |
| Computer | MS-DOS | Pentium, 90 MHz or higher |
| CPU | $486 \mathrm{DX}, 100 \mathrm{MHz}$ |  |
| OS | Microsoft Windows 95 | 24 Mbytes or more free |
| Memory | 16 Mbytes or more free | 50 M bytes or more free |
| Hard disk | 20 M bytes or more free |  |
| Floppy disk drive | 1 drive min. (1.44 Mbyte) |  |
| Display | VGA or better | SVGA or better |

Note SYSMAC-PST is not supported for Microsoft Windows Ver. 3.1.

## Windows 95/98 (CX-Protocol)

| Item | Minimum | Recommended |
| :--- | :--- | :--- |
| Computer | MS-DOS |  |
| CPU | Pentium, 90 MHz | Pentium, 166 MHz or higher |
| OS | Microsoft Windows $95 / 98$ |  |
| Memory | 16 Mbytes or more free | 24 Mbytes or more free |
| Hard disk | 24 M bytes or more free | 50 M bytes or more free |
| Floppy disk drive | 1 drive min. $(1.44 \mathrm{Mbyte})$ |  |
| CD-ROM drive | 1 drive min. |  |
| Display | SVGA $(800 \times 600$ pixels) or better |  |

Note CX-Protocol is not supported for Microsoft Windows Ver. 3.1.

## 2-3 Using the System Protocol Macros

This section describes how to use system protocols that are built into the Protocol Support Software and Communications Boards.

## 2-3-1 System Protocols

The following 12 standard protocols are provided with the Protocol Support Software and Communications Boards.

| Protocol name | Function |
| :--- | :--- |
| E5 $\square$ Kigital Controller Read | Protocol for controlling an E5 <br> Procedures for reading the MV the operating parameter settings |
| E5 $\square$ K Digital Controller Write | Protocol for controlling an E5■K Digital Controller via the Communications Board. <br> Procedures for writing set points and operating parameters. |
| E5ZE Temperature Controller <br> Read | Protocol for controlling an E5ZE Temperature Controller via the Communications <br> Board. Procedures for reading measured temperature and operating parameter <br> settings. |
| E5ZE Temperature Controller <br> Write | Protocol for controlling an E5ZE Temperature Controller via the Communications <br> Board. Procedures for writing control temperatures and operating parameters. |
| E5 $\square$ J Temperature Controller | Protocol for controlling a E5 $\square$ J Temperature Controller via the Communications <br> Board. Procedures for writing set points, reading output amounts, and <br> reading/writing operating parameters. |
| ES100■ Controller | Protocol for controlling an ES100 Controller via the Communications Board. <br> Procedures for writing adjustment parameters, reading operation amounts, and <br> writing/reading operating parameters. |
| Digital Panel Meter | Protocol for controlling a Digital Panel Meter via the Communications Board. <br> Procedures for writing comparison values and reading display values are set. |
| V500/V520 Bar Code Reader | Protocol for controlling a Bar Code Reader via the Communications Board. <br> Procedures for controlling the Bar Code Reader in remote mode, reading the data <br> that has been read by the Bar Code Reader, and reading/writing operating <br> parameters. |
| 3Z4L Laser Micrometer | Protocol for controlling a Laser Micrometer via the Communications Board. <br> Procedures for controlling the Laser Micrometer in remote mode, reading measured <br> data, and writing/reading operating parameters. |
| F200/F300/F350 Visual <br> Inspection Systems | Protocol for controlling a Visual Inspection System via the Communications Board. <br> Procedures for controlling the Visual Inspection System in remote mode, reading <br> measured values, and writing/reading operating parameters. |
| V600/V620 ID Controllers | Protocol for controlling an ID Controller via the Communications Board. Procedures <br> for performing Read/Write operations of the ID Controller and writing/reading <br> operating parameters. |
| Hayes modem AT commands | Protocol for controlling a Hayes modem (AT commands) via the Communications <br> Board. Procedures for initialization of the modem, dialing, data transmission, <br> switching to escape mode, and disconnecting the line. |

Note There are system protocols for which sending and receiving data between 32 devices in a $1: \mathrm{N}$ connection cannot be executed in one sequence. This is because of limits on the number of words that can be sent and received between the PC and the Communications Board. With these kind of sequences, unit numbers that represent the connected devices can be specified separately. Therefore, specify unit numbers with the send data, and repeat the sequence for the necessary number of times.

## 2-3-2 Executing System Protocols

Use the PMCR instruction to execute system protocols. The execution procedure and operand settings of the PMCR instruction are described below.

Ladder Symbols


Operand Data Areas

| C: Control word |
| :---: |
| IR, SR, AR, DM, EM, HR, TC, LR, \# |
| S: First output word |
| IR, SR, AR, DM, EM, HR, TC, LR, \# |
| D: First input word |
| IR, SR, AR, DM, EM, HR, TC, LR |

## Description

## Operands

$\operatorname{PMCR}(260)$ calls and executes the specified communications sequence (protocol) that has been registered in the Communications Board installed in the PC. Execution results in data transfer with a external device connected to the Communications Board's port A or port B.

The leftmost digit of the control word, C (bits 12 to 15), specifies the Communications Board port and the right three digits specify the communications sequence ( 000 to 999 ), as shown in the following diagram.


Digit 1: Port specifier
1: Communications port $A$
2: Communications port B
The first output word, S, specifies the address of the first word containing the data to be sent.
If there is no send data, set $S$ to \#0000. If any other constant or an address is specified when there is no send data, the Error Flag (SR 25503) will turn ON and the instruction will not be executed.
S actually contains the number of words to be sent and $\mathrm{S}+1$ and the following words contains the actual data to be sent, as shown in the following diagram.

| S: | No. of send words | Specifies the number of words to send, including S (256 words max.) |
| :---: | :---: | :---: |
| S+1: | Send data |  |
| S+2: | Send data |  |
| S+3: | . |  |
| . | . |  |
| . | . |  |

The first input word, D, specifies the address of the first word in which to store the receive data.
If there is no receive data, set $D$ to a dummy address. If a constant is specified, the Error Flag (SR 25503) will turn ON and the instruction will not be executed. (Nothing will be written to the dummy address and it can be used for another purpose.)

When data is received, $D$ will actually contain the number of words received and D+1 and the following words contains the actual receive data, as shown in the following diagram.


## Flags

ER: The Error Flag (SR25503) will turn ON when any of the following conditions occur.
The content of a word containing an indirect DM/EM address is not BCD or the DM/EM area boundary has been exceeded.
D is not BCD or DM 6144 through DM 6655 has been used for D.
Another $\operatorname{PMCR}(260)$ instruction was already in progress when the instruction was executed.
The port specified was not 1 or 2.

## Application Example: E5 $\square$ K Digital Controller Read (Sequence 000)

This example uses the following system. The unit number of the Temperature Controller is specified and a command to read the present value is sent. The present value in the response is then received in the specified words.


## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

| Receive data | +0 | Number of receive data words |
| :--- | :--- | :--- |
| storage words | +1 | Process value |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Process value (4 digits BCD) | Scaling lower limit to upper limit |

The following operands would be used to read the present value of Unit \#3 and store it in DM 0201.

|  | PMCR |
| ---: | ---: |
| C | \#1000 |
|  | DM0100 |
|  |  |
|  |  |
|  |  |

C: Control Data

S: First output word (command control data): DM0100


|  | 15 |  |  |
| ---: | :---: | :---: | :---: |
| D: DM0200 | 0 0 0 2 <br> Present value    | No. of received words: 2 <br> Present value: 4-digit BCD |  |

## Application Example: E5 $\square$ K Digital Controller Write (Sequence 050)

This example uses the following system. The unit number of the Temperature Controller and the target value is specified and a command to change the target value of the Controller is sent.


## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  | set point |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Set point (4 digits BCD) | Set point lower limit to upper limit |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
The following operands would be used to write the target value $\left(300^{\circ} \mathrm{C}\right)$ contained in DM 0102 to Unit \#5.

C: Control Data

S: First output word
S: DM0100

| 15 |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| S: DM0100 | 0 | 0 | 0 | 3 | No. of send words: | 3 |
| S+1: DM0101 | 0 | 0 |  | 5 | Unit No.: | 5 |
| S+2: DM0102 | 0 | 3 | 0 | 0 | Target value: | 300 |

D: First input word
D: DM 0200 (dummy address)
A dummy address is set because no data will be received. Nothing
will be written to DM 0200 and it can be used for another purpose.

## Application Example: V500/V520 Bar Code Reader (Sequence 350)

This example uses the following system. A command is sent to the Bar Code Reader to start a reading operation.


## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

The following operands would be used to start a reading operation for the Bar Code Reader.

|  | PMCR |
| :--- | ---: |
|  |  |
| S | $\# 1350$ |
|  |  |
|  |  |
|  |  |

C: Control Data

S: First output word
S: \#0000
S must be set to \#0000 when there is no send data.
D: First input word
D: DM 0000 (dummy address)
A dummy address is set because no data will be received. Nothing will be written to DM 0000 and it can be used for another purpose.

## PMCR Execution

Ladder Diagram Structure
Only one PMCR instruction can be executed at the same time. To ensure that a PMCR instruction is not executed before execution of another PMCR instruction has been completed, the Port A/B Instruction Execution Flag (SR 28908 or SR 28912) is used in a NC condition in the execution condition for PMCR. An OFF condition for the Flag can then be used to activate processing to read the
results of sequence execution, handle errors, etc. The basic structure of this type of programming is shown below for port A.


## Ladder Diagram Example

In the following ladder diagram, sequence number 000 (E5 $\square \mathrm{K}$ Digital Controller Read) is executed through PMCR to read the PV. When sequence execution has been completed, the PV is transferred to words to store it.


If SR 28908 is OFF when the execution condition turns ON, sequence \#000 is executed and the PV is stored in DM 0201.

When SR 28908 changes from ON to OFF, IR 00100 will turn ON for one cycle.

If IR 00100 is ON, SR 28908 is OFF, and SR 28908 is OFF, the PV in DM 0201 is moved to DM 0300.

If IR 00100 is ON and SR 28908 is ON, an error will have occurred in the sequence and a non-fatal error is generated.

|  | Port A Instruction <br> Execution Flag <br> (SR 28908) | 0 |
| :--- | :--- | :--- |

The following examples show execution of End at normal completion of sequence and Abort when sequences end in errors. If End and Abort are set in this way, the Sequence Abort Flag and Sequence End Flag can be used to determine whether or not sequences have completed normally.
The Step Error Processing Flag shows the status of individual steps and not the status of the overall sequence. The Step Error Processing Flag will turn ON when any one step in a sequence ends in an error and will remain ON even if the next step in the sequence ends normally. It is thus not always possible to use the Step Error Processing Flag to determine if the overall sequence executed successfully.

## Example 1



## Sequence Executed Normally



## Error in Sequence Execution



## Example 2



## Sequence Executed Normally



## Error in Sequence Execution



## Flag and Memory Area

## Status for Protocol Macros

The following table describes the operation and contents of bits and memory area words used with protocol macros. Refer to 2-4 Troubleshooting for details on Error Flags.

| Name | Name | Port A | Port B | Read/ Write |
| :---: | :---: | :---: | :---: | :---: |
| Instruction Execution Flag | Turns ON when PMCR is executed, but will remain OFF is execution fails. <br> Turns OFF when PMCR execution is aborted or completed. | SR 28908 | SR 28912 | R |
| Step Error Processing Flag | Turns ON when an error occurs in execution of a step. Turns OFF when retry successfully executes the step. Remains OFF unless an error occurs. | SR 28909 | SR 28913 | R |
| Sequence End Flag | Turns ON when sequence execution is completed normally (End Processing: See note). (The Instruction Execution Flag must be OFF for the status of the Sequence End Flag to be valid). <br> Remains OFF unless normal End processing is executed for the sequence. <br> This Flag can be used to determine if a sequence ended normally is End is set for normal sequence completion and Abort is set for error completion. | SR 28910 | SR 28914 | R |
| Sequence Abort Flag | Turns ON when sequence execution is aborted (Abort Processing: See note). (The Instruction Execution Flag must be OFF for the status of the Sequence End Flag to be valid). <br> Remains OFF unless the sequence is aborted. | SR 28307 | SR 28315 | R |
| Abort Bit | Turn ON from the ladder diagram program to abort a sequence that is being executed. | SR 28911 | SR 28915 | W |
| Restart Bit | Turn ON from a Programming Device or the ladder diagram program to initialize the send/receive buffers and SR 283 to SR 285. <br> This Bit can be used to initialize the above memory/buffer contents after completion of a sequence. This Bit will not cancel a sequence that is being executed. <br> This Bit will automatically reset to OFF. | SR 28900 | SR 28901 | W |
| Executed Reception Matrix Case No. (0 to F) | Contains the number of the reception case selected for the reception message when a reception matrix is set. SR 28715/SR 28815 will turn ON when a number is stored. | $\begin{aligned} & \text { SR } 28700 \\ & \text { to } \\ & \text { SR } 28703 \end{aligned}$ | $\begin{aligned} & \text { SR } 28800 \\ & \text { to } \\ & \text { SR } 28803 \end{aligned}$ | R |
| Executed Step No. (0 to F) | Contains the number of the step that was just executed. SR 28715/SR 28815 will turn ON when a number is stored. | $\begin{aligned} & \text { SR } 28704 \\ & \text { to } \\ & \text { SR } 28707 \end{aligned}$ | $\begin{aligned} & \text { SR } 28804 \\ & \text { to } \\ & \text { SR } 28807 \end{aligned}$ | R |
| SR 287/SR 288 Stored Flag | Turns ON when a reception matrix case number or step number is stored in SR 287 or SR 288. | SR 28715 | SR 28815 | R |
| Repeat Counter Present Value | Contains the present value of the step repeat counter, N . | $\begin{aligned} & \hline \text { SR } 28400 \\ & \text { to } \\ & \text { SR } 28407 \end{aligned}$ | $\begin{array}{\|l\|} \hline \text { SR } 28500 \\ \text { to } \\ \text { SR } 28507 \end{array}$ | R |

## Using the Abort Bits (SR 28911/SR 28915)

The Instruction Execution Flag will turn OFF as soon as the Abort Bit is turned ON from the user program. If the Abort Bit is turned OFF in the user program as soon as the Instruction Execution Flag turns OFF, Abort Processing will not be executed. Be sure that the Abort Bit remains ON at least $15 \mathrm{~ms}+$ the CPU Unit's cycle time.
Also, if an NC condition is programmed using the Instruction Execution Flag as the execution condition for PMCR, then the PMCR instruction may be executed during Abort Processing, causing a FAL-9C error. Do not allow PMCR to be
executed for at least $15 \mathrm{~ms}+$ the CPU Unit's cycle time after the Abort Bit is turned ON.

## Example

The Forced Abort Flag is turned ON and the 30 ms period elapses, then the Forced Abort Flag is turned OFF and simultaneously the PMCR instruction interlock is released.


Transmission Method
Basically, there are two transmission methods: Half duplex and full duplex. With half-duplex transmissions, data can be transferred between two devices in only one direction at a time (either $\mathrm{A} \rightarrow \mathrm{B}$ or $\mathrm{B} \rightarrow \mathrm{A}$ ). With full-duplex transmissions, data can be transferred in both directions at the same time ( $\mathrm{A} \leftrightarrow \mathrm{B}$ ). C200HX/ $\mathrm{HG} / \mathrm{HE}(-\mathrm{Z})$ protocol macros support only half-duplex transmissions. For this reason, the following restriction applies: The receive buffer is cleared immediately before sequence execution and immediately after the send operation (for the send command or the send/receive command) is completed. Therefore, any data received just before or during the send operation will not be processed as receive data.

| Transmission <br> method | Times at which <br> receive buffer is <br> cleared | Times at which <br> data can be <br> received | Character trace |  | Timing chart |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Half duplex | Immediately before <br> execution of <br> send/receive <br> sequence, and <br> immediately after <br> completion of send <br> operation for the <br> send command or <br> the send/receive <br> command. | From end of send <br> operation until end <br> of receive <br> operation, or from <br> end of send <br> operation until <br> immediately before <br> next send <br> operation. | Trace performed <br> for all data <br> transferred during <br> execution of <br> character trace. | Send/receive <br> sequence | Receive buffer <br> cleared <br> Data received <br> Character <br> trace |

Note Although data received before the completion of the send operation is lost, it is still recorded in the character trace.

## Time Delay

When a send operation is performed for half-duplex communications, there is actually a time delay (t; see table below) between the completion of data send processing and the completion of the send operation. Therefore, if the response from the connected device is so fast that it is received between the time that the data is sent (with the communications command) and the time send operation is completed, the portion of the response data received in this interval will not be processed as receive data.


Time Delay (t)

| Baud rate (bps) | Time delay (unit: $\mathbf{~ m s}$ ) |
| :--- | :--- |
| 1,200 | 30 |
| 2,400 | 15 |
| 4,800 | 8 |
| 9,600 | 5 |
| 19,200 | 3 |

Note The above time delays are approximate values. They may be longer depending on the protocol macro processing.

## Error Flags for Overrun Errors, Framing Errors, and Parity Errors

With the protocol macro function, when any of the above errors are detected, the receive data is stored together with error information data in the internal receive buffer. Whether or not the error flags will turn ON depends on the following conditions.

- When error information data is included in the data that matches the expected receive message:

When the receive operation is performed, the receive buffer is searched, and if data matching the expected receive message is found, it is handled as receive data. If this reception data contains error information, each error flag will turn ON. In the following example, 100 bytes of data matching the expected receive message were received.


- When error information data is included in data which does not match the expected receive message:

Even if the receive data contains error information data, if the data does not match the expected receive message, the data will be ignored and the error flag status will not change. The example below shows data which contained parity errors but did not match the expected receive message.


All error information obtained from the receive buffer, however, will be stored as trace data within the trace data capacity range.

Using the Restart Bits (SR 28900/SR 28901)

The Restart Bits can be used to initialize the communications ports. The port will be initialized the next time protocol macro execution is completed after a Restart Bit is turned ON from the ladder diagram or from a Programming Device. The Restart Bits will automatically turn OFF when restart processing has been completed. The Restart Bits will not end a protocol macro even if they are turned ON during protocol macro execution.
Do not allow PMCR to be executed for at least $15 \mathrm{~ms}+$ the CPU Unit's cycle time after a Restart Bit is turned ON. This time will be required to complete restart processing for the Communications Board. If the PMCR instruction executed during restart processing, a FAL 9C error will occur and the protocol macro may not be executed normally.

Echoback Disable Function
When a communications error or retries occur with RS-485 2-wire communica- tions, take the countermeasure explained below. This countermeasure, howev-
er is possible only for models of lot numbers 0140 or later. The meaning of lot numbers is shown below.


When the serial communications mode for the Communications Board's ports is set to Protocol Macro Mode, and the transmission control parameter in the protocol macro data is set to modem control, the following bits/flags in the SR Area will be enabled.

| Bit/Flag | Name/Operation | Notes |
| :--- | :--- | :--- |
| SR 28906 | Port A Echoback Disable Bit <br> 1: Echoback disabled <br> 0: Echoback enabled | Settings sent to the <br> Communications Board |
| SR 28907 | Port B Echoback Disable Bit <br> 1: Echoback disabled <br> 0: Echoback enabled | Settings sent to the <br> Communications Board |
| SR 28606 | Port A Echoback Disabled Flag <br> 1: Echoback disabled <br> 0: Echoback enabled | Used to monitor the setting of the <br> Communications Board. |
| SR 28607 | Port B Echoback Disabled Flag <br> 1: Echoback disabled <br> 0: Echoback enabled | Used to monitor the setting of the <br> Communications Board. |

In RS-485 2-wire communications, if an Echoback Disable Bit (port A: SR 28906; port B: SR 28907) is set to 1 (ON), data sent from the respective Communications Board's port will be prevented (via the software) from returning to the receive line of the local node while the RS signal is $1(\mathrm{ON})$.
In situations where communications errors and retries occur in RS-485 2-wire communications, incorporate programming in the ladder programming that will turn these bits ON as required. When echoback is disabled, data received while data is being sent (i.e., the RS signal is ON) is neither processed as receive data or recorded as trace data. If either of the Echoback Disable Bits are turned ON while the ladder program is running, this is reflected in the Communications Boards, but, conversely, the OFF status is only reflected in the Communications Boards at the start of the ladder program. Therefore, during execution of protocol macros, echoback cannot be disabled by simply turning the Echoback Disable Bits ON. Either go into PROGRAM mode once, before restarting the ladder program, or turn the power supply OFF and ON again.
The status of each of the Echoback Disable Bits can be monitored using the Echoback Disabled Flags (port A: SR 28606; port B: SR 28607).

## Example: Ladder Diagram



## Note RS-485 2-wire Communications and Echoback

When 2-wire communications are performed, the send line and the receive line use the same pair of wires. Therefore, send data will come back along the receive line (refer to the diagram below). In this manual, returning the send data is referred to an echoback.

So that this echoback data can be received and sent without the user having to set an expected receive message, the protocol macro functions are designed so that a receive trace is performed in the firmware of the Communications Board and then the data is discarded.
Because of delays in echoback timing, and because of inconsistencies in the processing time for the Communications Board, however, it can become difficult to distinguish between actual responses and echoback, and it is possible that the echoback data is mistaken for an expected receive message, resulting in a communications error. This problem can be prevented by turning ON the appropriate Echoback Disable Bit so that receive processing is not performed for echoback data.
Two-wire Communications Using the RS-422/485 Port on the C200HW-
COM06-EV1


Two-wire Communications Using the RS-232C Port on the C200HW-COM04-EV1 to C200HW-COM06-EV1 and the NT-ALO01-E


## Timing for Receive/Send in 2-wire Communications



## Abort Flags

The status of bits SR 28900 to SR 28907, SR 28911 and SR 28915 is held when power is turned OFF. If bits SR 28911 and SR 28915 (Abort Flags for port A and port B) are ON, send/receive cannot be executed. Either turn OFF these bits from a Programming Device, or include a section in the ladder program that will turn them OFF as shown below.


## 2-4 Troubleshooting

When an error occurs during operation of the Communications Board, the error is notified by displaying it in LED of the PC or outputting the error code to the controller. The error type and error section are also stored in the Communications Board related data area also. When an error occurs in the Communications Board, take the appropriate action by referencing the table below.

Note 1. When a system FAL-9C error occurs, ERR/ALM LED of the PC will flash.
2. When a system FAL-9C error occurs, the Communications Board will be disabled.
3. When a system FAL-9B error occurs, operation of the Communications Board can be continued.

| Condition | Indication | Cause | Action |
| :---: | :---: | :---: | :---: |
| Communications Board will not operate. | RDY indicator does not light. | Communications Board failure. | Replace the Communications Board and toggle the power supply. |
| System FAL9C error | SR $26800=0 \mathrm{~N}$ | Communications Board failure. | Replace the Communications Board and toggle the power supply. |
|  | SR 26801 = ON and RDY indicator not lit. | Error occurring due to non-recognition of the RS-232C port at startup. Normally occurs due to a hardware error. | Replace the Communications Board and toggle the power supply. |
|  | SR $26802=\mathrm{ON}$ | Protocol data is in error. | Correct the protocol data using the Protocol Support Software. |
| System FAL9C error and system FAL9B error | $\text { SR } 26815=\text { ON }$ <br> RDY indicator flashing. | a) System Setup for the Communications Board (DM6550 to DM6559) is corrupt. $\begin{aligned} & \text { SR } 26813=\text { ON (port B) } \\ & \text { SR } 26814=\text { ON (port A) } \end{aligned}$ <br> OR <br> b) The Communications Board does not support protocol macros. | a) Correct the System Setup and restart the system. <br> b) Use a Communications Board that supports protocol macros. |
| System FAL9C error when PMCR is executed and the Instruction Execution Flag does not turn ON . <br> Port A = SR 28908 <br> Port B = SR 28912 | SR 26811= ON (Port B) <br> SR 26812= ON (Port A) <br> Error Code <br> SR 28608 to SR 28611 <br> (Port A) <br> SR 28612 to SR 28615 (Port B) | A protocol macro error related to the PMCR instruction has occurred. Troubleshoot using the following error codes. |  |
|  |  | Error Code = 1 <br> a)The protocol macro mode has not been set in the System Setup for the Communications Board (DM6550 to DM6559). <br> b) The Communications Board does not support protocol macros. | a) Correct the System Setup and restart the system. <br> b) Use a Communications Board that supports protocol macros. |
|  |  | Error Code = 2 <br> The specified sequence number does not exist. | Correct the PMCR operands or transfer the sequence to the Communications Board. |
|  |  | Error Code = 3 <br> The received data was too large to be written into I/O memory. | Use a different area or less data. |
|  |  | Error Code = 4 <br> The protocol data in the Communications Board is bad. | Rewrite the protocol data using the Protocol Support Software. |
|  |  | Error Code $=5$ <br> PMCR instruction executed during port initialization. | Include an interval between port initialization, such as for a port restart, and execution of the PMCR instruction. |
| PMCR instruction not executed. System FAL9C error not generated. |  | Abort Flag SR 28911 (for port A) or SR 28915 (for port $B$ ) is ON. | Turn OFF the Abort Flags SR 28911 and SR 28915. |


| Condition | Indication | Cause | Action |
| :---: | :---: | :---: | :---: |
| PMCR executed but data not sent/ received properly. <br> The Instruction Execution Flag turned ON. <br> Port A = SR 28908 <br> Port B = SR 28912 | $\begin{array}{\|l} \text { SR 28909= ON (Port A) } \\ \text { SR 28913= ON (Port B) } \end{array}$ | Step error processing is being executed during a sequence, possibly because of an unexpected receive message. | Find the cause of the error and correct it. |
|  | $\begin{aligned} & \text { SR 28304= ON (Port A) } \\ & \text { SR 28312= ON (Port B) } \end{aligned}$ | A communications error occurred during message reception. | Check the communications path between the devices. |
| Communications not possible with other devices. | $\begin{aligned} & \text { SR 28304= ON (Port A) } \\ & \text { SR 28312= ON (Port B) } \end{aligned}$ | There is a problem with the communications path between the RS-232C port ( A or B ) and the device or communications parameters are not set correctly. <br> Refer to the error codes in the following words. <br> SR 28300 to SR 28303 (Port A) <br> SR 28608 to SR 28611 (Port B) | Restart the port, or execute RXD or PMCR to initialize memory. <br> Check the communication path. <br> Check the communications parameters. |
| PMCR, RXD, and TXD cannot be executed. | ER Flag (SR 25503) = ON | The instruction operands may be incorrect. | Correct the operands. |

## Appendices System Protocols

The following appendices describe the protocols that are provided with the Communications Board and the Protocol Support Software/Tool (sold separately). These sequences can be executed by specifying the sequence number as an operand in the PMCR instruction.
A E5 $\square$ K Digital Controller Read Protocol ..... 59
B E5 $\square$ K Digital Controller Write Protocol ..... 77
C E5ZE Temperature Controller Read Protocol ..... 93
D E5ZE Temperature Controller Write Protocol ..... 115
E E5 $\square$ J Temperature Controller Protocol ..... 135
F ES100 $\square$ Digital Controller Protocol ..... 149
G K3T $\square$ Intelligent Signal Processor Protocol ..... 191
H V500/V520 Bar Code Reader Protocol ..... 213
I 3Z4L Laser Micrometer Protocol ..... 225
J Visual Inspection System Protocol ..... 257
K V600/V620 ID Controller Protocol ..... 275
L Hayes Modem AT Command Protocol ..... 311

# Appendix A <br> E5 $\square$ K Digital Controller Read Protocol 

The E5 $\square$ K Digital Controller Read Protocol reads and controls various parameters in remote mode for the Controller connected to the Communications Board via RS-232C or RS-485 cable.

## Structure of the Protocol

The following table shows the structure of the E5 $\square \mathrm{K}$ Digital Controller Read Protocol.

| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 000 | Read process value | Reads the process value. | Yes | Yes |
| 001 | Read set point during SP ramp | Reads the set point during SP ramp. | Yes | Yes |
| 002 | Read MV | Reads the MV (heating, cooling). | Yes | Yes |
| 003 | Read set point | Reads the set point. | Yes | Yes |
| 004 | Read alarm value | Reads alarm value 1, 2. | Yes | Yes |
| 005 | Read proportional band, integral time, and derivative time | Reads the proportional band, integral (reset) time, and derivative (rate) time | Yes | Yes |
| 006 | Read cooling coefficient | Reads the cooling coefficient. | Yes | Yes |
| 007 | Read dead band | Reads the dead band. | Yes | Yes |
| 008 | Read manual reset value | Reads the manual reset value. | Yes | Yes |
| 009 | Read hysteresis | Reads the hysteresis (heating, cooling). | Yes | Yes |
| 010 | Read control period | Reads the control period (heating, cooling). | Yes | Yes |
| 011 | Read SP ramp time unit and set value | Reads the SP ramp time unit and SP ramp set value. | Yes | Yes |
| 012 | Read LBA detection time | Reads the LBA detection time. | Yes | Yes |
| 013 | Read MV at stop and PV error | Reads the MV at stop and the MV at PV error. | Yes | Yes |
| 014 | Read MV limits | Reads the MV limits. | Yes | Yes |
| 015 | Read input digital filter | Reads the input digital filter. | Yes | Yes |
| 016 | Read alarm hysteresis | Reads the alarm 1, 2 hysteresis. | Yes | Yes |
| 017 | Read input shifts | Reads the input shift limits. | Yes | Yes |
| 018 | Read level 0 parameters | Reads parameters in level 0. | Yes | Yes |
| 019 | Read level 1 parameters 1 | Reads parameters in level 1. | Yes | Yes |
| 020 | Read level 1 parameters 2 | Reads parameters in level 1. | Yes | Yes |
| 021 | Read level 2 parameters 1 | Reads parameters in level 2. | Yes | Yes |
| 022 | Read level 2 parameters 2 | Reads parameters in level 2. | Yes | Yes |
| 023 | General-purpose read | Reads the value of the specified parameter. | Yes | Yes |

## Note Ladder Interface Settings

YES: User settings are required for the 2nd or 3rd operands of PMCR.
NO: Send word allocation: Set the constant 0000 for the 2nd operand (S). Receive word allocation: Set a dummy word (e.g., DMO000) address for the 3rd operand (D).

## Connection Configuration

The connection configuration for using the E5 $\square$ K Digital Controller Read Protocol is shown below.

## RS-232C Connection



Note 1. The communications configuration is a one-to-one configuration and the maximum cable length is 15 m .
2. Use a shielded twisted-pair cable (AWG28i or greater) for the cable.

## RS-485 Connection



Up to 3,1 Units can be connected with 2-wire communications and up to 32 Units can be connected with 4-wire communications.


Note 1. The communications configuration is a one-to-one configuration or a one-to-N configuration. In the one-to-N configuration, up to 32 units including the Communications Board can be connected.
2. The maximum cable length is 500 m . Use a shielded twisted-pair cable for the cable (AWG28i or greater).
3. Connect a terminator only at both ends of the transmission path. For instance, in the example shown below, connect a terminator to the Communications Board and unit No. 30 and do not connect any terminator to units No. 0 to No.29. Use a resistance of $120 \Omega(1 / 2 \mathrm{~W})$ for the terminators (the total resistance of both ends must be $54 \Omega$ or more).


## Read Process Value (Sequence No. 000)

Reads the process value and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |
| :---: | :---: |
|  | Process value |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Process value (4 digits BCD) | Scaling lower limit to upper limit |

## Read Set Point during SP Ramp (Sequence No. 001)

Reads the set point during the SP ramp and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 | Number of send data words |  |
| :--- | ---: | ---: | :---: |
|  | Unit No. |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |
| :---: | :---: |
|  | Set point during SP ramp |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Set point during SP ramp <br> $(4$ digits BCD) | Set point lower limit to upper limit |

## Read MV (Sequence No. 002)

Reads the MV (manipulated variable) for heating and cooling and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send +0 data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) |  |
|  |  |  |
|  |  |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |
| :--- | :---: |
|  | MV (heating) |
|  |  |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0003 |
| +1 | MV (heating) (4 digits BCD) | F050 to 1050, 0000 to 1050 for <br> heating/cooling control <br> F indicates a negative value. |
| +2 | MV (cooling) (4 digits BCD) | F050 to 1050 <br> F indicates a negative value. |

## Read Set Point (Sequence No. 003)

Reads the set point and stores the results in the specified word.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Set point (4 digits BCD) | Set point lower limit to upper limit |

## Read Alarm Value (Sequence No. 004)

Reads alarm value 1 and alarm value 2 and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send +0 data

| Number of send data words |  |
| :---: | :---: |
| +1 | (Undefined) |
|  | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |
| :---: | :---: |
|  | Alarm value 1 |
|  | Alarm value 2 |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0003 |
| +1 | Alarm value 1 (4 digits BCD) | A999 to 9999 <br> F indicates a negative value and A <br> indicates -1. |
| +2 | Alarm value 2 (4 digits BCD) | A999 to 9999 <br> F indicates a negative value and A <br> indicates -1. |

## Read Proportional Band, Integral Time, and Derivative Time (Sequence No. 005)

Reads the proportional band, integral time, and derivative time and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

| $\begin{array}{c}\text { First word of send } \\ \text { data } \\ \text { data }\end{array}$ |  | Number of send data words |  |
| :--- | :--- | :--- | :--- |
|  | +1 | (Undefined) | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)
Receive data storage words

| +0 | Number of receive data words |
| :---: | :---: |
| +1 | Proportional band |
| +2 | Integral time |
| +3 | Derivative time |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0004 |
| +1 | Proportional band (4 digits BCD) | 0000 to 9999 |
| +2 | Integral time (4 digits BCD) | 0000 to 3999 |
| +3 | Derivative time (4 digits BCD) | 0000 to 3999 |

## Read Cooling Coefficient (Sequence No. 006)

Reads the cooling coefficient and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Cooling coefficient (4 digits BCD) | 0001 to 9999 |

## Read Dead Band (Sequence No. 007)

Reads the dead band and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| Number of send data words |  |  |
| :---: | :---: | :---: |
|  | N |  |
|  | (Undefined) |  | Unit No.


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |
| :---: | :---: |
|  | Dead band |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Dead band (4 digits BCD) | A999 to 9999 <br> F indicates a negative value and A <br> indicates -1. |

## Read Manual Reset Value (Sequence No. 008)

Reads the manual reset value and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

| $\begin{array}{l}\text { First word of send } \\ \text { data } \\ \text { data }\end{array}$ |  | Number of send data words |  |
| :--- | ---: | :---: | :---: |
|  |  | (Undefined) | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Manual reset value (4 digits BCD) | 0000 to 1000 |

## Read Hysteresis (Sequence No. 009)

Reads the hysteresis for heating and for cooling and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |
| :---: | :---: |
| +1 | Hysteresis (heating) |
| +2 | Hysteresis (cooling) |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0003 |
| +1 | Hysteresis (heating) <br> (4 digits BCD) | 0001 to 9999 |
| +2 | Hysteresis (cooling) <br> $(4$ digits BCD) | 0001 to 9999 |

## Read Control Period (Sequence No. 010)

Reads the control period for heating and for cooling and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data
storage words

|  | Number of receive data words |
| :---: | :---: |
|  | Control period (heating) |
|  | Control period (cooling) |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0003 |
| +1 | Control period (heating) <br> (4 digits BCD) | 0001 to 0099 |
| +2 | Control period (cooling) <br> $(4$ digits BCD) | 0001 to 0099 |

## Read SP Ramp Time Unit and Set Value (Sequence No. 011)

Reads the SP ramp time unit and SP ramp set value and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

|  | First word of send +0  Number of send data words  <br>     <br> data    |  | (Undefined) |
| :--- | ---: | :---: | :---: |
|  |  |  | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

| +0 | Number of receive data words |
| :---: | :---: |
| +1 | SP ramp time unit |
| +2 | SP ramp set value |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0003 |
| +1 | SP ramp time unit (4 digits BCD) | $0000: \mathrm{s}, 0001: \mathrm{hr}$ |
| +2 | SP ramp set value (4 digits BCD) | 0000 to 9999 |

## Read LBA Detection Time (Sequence No. 012)

Reads the LBA (loop break alarm) detection time and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | Undefined) |  |
|  | Unit No. |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)
Receive data storage words

|  | Number of receive data words |
| :--- | :---: |
|  | LBA detection time |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0002 |
| +1 | LBA detection time (4 digits BCD) | 0000 to 9999 |

## Read MV at Stop Time and at PV Error (Sequence No.013)

Reads the MV at stop time and at PV error and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) |  |
|  | Unit No. |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |
| :---: | :---: |
|  | MV at stop time |
|  |  |
|  |  |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0003 |
| +1 | MV at stop time (4 digits BCD) | F050 to 1050 <br> F indicates a negative value. <br> A050 to 1050 for heating/cooling control <br> A indicates a negative value. |
| +2 | MV at PV error (4 digits BCD) | F050 to 1050 <br> F indicates a negative value. |

## Read MV Limits (Sequence No. 014)

Reads the MV upper limit, MV lower limit, and MV change rate limit and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |
| :--- | :---: |
|  | MV upper limit |
|  | MV lower limit |
|  |  |
|  |  |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0004 |
| +1 | MV upper limit (4 digits BCD) | MV lower limit + 1 to 1050 <br> 0000 to 1050 for heating/cooling control |
| +2 | MV lower limit (4 digits BCD) | F050 to MV upper limit -1 <br> F indicates a negative value values. <br> A050 to 1050 for heating/cooling control <br> A indicates a negative value. |
| +3 | MV change rate limit <br> (4 digits BCD) | 0000 to 1000 |

## Read Input Digital Filter (Sequence No. 015)

Reads the input digital filter and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of
send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  |  |  |
|  | (Undefined) |  | Unit No.


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data

| +0 | Number of receive data words |
| :---: | :---: |
| +1 | Input digital filter |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Input digital filter (4 digits BCD) | 0000 to 9999 |

## Read Alarm Hysteresis (Sequence No. 016)

Reads the alarm 1 hysteresis and alarm 2 hysteresis and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |
| :---: | :---: |
|  | Alarm 1 hysteresis |
|  | Alarm 2 hysteresis |
|  |  |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0003 |
| +1 | Alarm 1 hysteresis <br> $(4$ digits BCD) | 0001 to 9999 |
| +2 | Alarm 2 hysteresis <br> $(4$ digits BCD $)$ | 0001 to 9999 |

## Read Input Shift Limits (Sequence No. 017)

Reads the input shift upper limit and input shift lower limit and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | Unit No. |  |
|  | (Undefined) | Un |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |
| :---: | :---: |
|  | Input shift upper limit |
|  | Input shift lower limit |
|  |  |
|  |  |
|  |  |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0003 |
| +1 | Input shift upper limit (4 digits BCD) | A999 to 9999 <br> F indicates a negative value and A <br> indicates -1. |
| +2 | Input shift lower limit (4 digits BCD) | A999 to 9999 <br> F indicates a negative value and A <br> indicates -1. |

## Read Level 0 Parameters (Sequence No. 018)

Reads parameters in level 0 (process value, set point during SP ramp, MV (heating), MV (cooling), and set point) from multiple units and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)



Receive Data Word Allocation (3rd Operand of PMCR)
Receive
data storage
words


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 5+1$ |
| +1 | 1st unit Process value (4 digits BCD) | Scaling lower limit to upper limit |
| +2 | 1st unit <br> Set point during SP ramp <br> (4 digits BCD) | Set point lower limit to upper limit |
| +3 | $\begin{array}{\|l} \text { 1st unit } \\ \text { MV (heating) (4 digits BCD) } \end{array}$ | F050 to 1050 $F$ indicates a negative value. 0000 to 1050 for heating/cooling control |
| +4 | ```1st unit MV (cooling) (4 digits BCD)``` | 0000 to 1050 |
| +5 | 1st unit Set point (4 digits BCD) | Set point lower limit to upper limit |
|  | $\stackrel{-}{\bullet}$ |  |
| $\begin{aligned} & \hline+40 \\ & \text { (max.) } \\ & \hline \end{aligned}$ | 8th unit Set point (4 digits BCD) | Set point lower limit to upper limit |

## Read Level 1 Parameters 1 (Sequence No. 019)

Reads parameters in level 1 (alarm value 1, alarm value 2 , alarm value 3, proportional band, integral time, and derivative time) from multiple units and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


1st unit

8th unit (max.)

| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 6+1$ |
| +1 | 1st unit <br> Alarm value 1 (4 digits BCD) | A999 to 9999 <br> $F$ indicates a negative value and $A$ indicates -1 . |
| +2 | 1st unit <br> Alarm value 2 (4 digits BCD) | A999 to 9999 <br> $F$ indicates a negative value and $A$ indicates -1 . |
| +3 | 1st unit Alarm value 3 (4 digits BCD) | A999 to 9999 <br> $F$ indicates a negative value and $A$ indicates -1 . |
| +4 | 1st unit Proportional band (4 digits BCD) | 0001 to 9999 |
| +5 | 1st unit Integral time (4 digits BCD) | 0000 to 3999 |
| +6 | 1st unit Derivative time (4 digits BCD) | 0000 to 3999 |
|  |  |  |
| $\begin{aligned} & \hline+48 \\ & \text { (max.) } \end{aligned}$ | 8th unit <br> Derivative time (4 digits BCD) | 0000 to 3999 |

## Read Level 1 Parameters 2 (Sequence No. 020)

Reads parameters in level 1 (cooling coefficient, dead band, manual reset value, hysteresis (heating), hysteresis (cooling), control period (heating), and control period (cooling)) from multiple units and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | Number of units +2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 to 9 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | Number of units $\times 7+1$ |
| +1 | 1st unit <br> Cooling coefficient (4 digits BCD) | 0001 to 9999 |
| +2 | 1st unit <br> Dead band (4 digits BCD) | A999 to 9999 <br> F indicates a negative value and A <br> indicates -1. |
| +3 | 1st unit <br> Manual reset value <br> (4 digits BCD) | 0000 to 1000 |
| +4 | 1st unit <br> Hysteresis (heating) <br> (4 digits BCD) | 0001 to 9999 |
| +5 | 1st unit <br> Hysteresis (cooling) (4 digits BCD) | 0001 to 9999 |
| +6 | 1st unit <br> Control period (heating) <br> (4 digits BCD) | 0001 to 0099 |
| +7 | 1st unit <br> Control period (cooling) <br> (4 digits BCD) | 0001 to 0099 |
|  | $\bullet$ | 0001 to 0099 |
| +56 |  |  |
| (max.) | 8th unit <br> Control period (cooling) <br> (4 digits BCD) |  |

## Read Level 2 Parameters 1 (Sequence No. 021)

Reads parameters in level 2 (SP ramp time unit, SP ramp set value, LBA detection time, MV at stop, MV at PV Error, MV upper limit, MV lower limit, and MV change rate limit) from multiple units and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

## First word of send data



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units +2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 to 9 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 8+1$ |
| +1 | 1st unit <br> SP ramp time unit (4 digits BCD) | 0000: s, 0001: hr |
| +2 | 1st unit SP ramp set value (4 digits BCD) | 0000 to 9999 |
| +3 | 1st unit <br> LBA detection time (4 digits BCD) \} | 0000 to 9999 |
| +4 | 1st unit MV at stop (4 digits BCD) | F050 to 1050 <br> $F$ indicates a negative value. <br> A050 to 1050 for heating/cooling control A indicates a negative value. |
| +5 | 1st unit MV at PV error (4 digits BCD) | F050 to 1050 <br> $F$ indicates a negative value. <br> A050 to 1050 for heating/cooling control A indicates a negative value. |
| +6 | 1st unit MV upper limit (4 digits BCD) | MV lower limit + 1 to 1050 0000 to 1050 for heating/cooling control |
| +7 | 1st unit MV lower limit (4 digits BCD) | F050 to MV upper limit -1 $F$ indicates a negative value. <br> A050 to 1050 for heating/cooling control A indicates a negative value. |
| +8 | 1st unit MV change rate limit (4 digits BCD) | 0000 to 1000 |
|  |  |  |
| $\begin{array}{\|l\|} \hline+64 \\ \text { (max.) } \end{array}$ | 8th unit <br> MV change rate limit <br> (4 digits BCD) | 0000 to 1000 |

## Read Level 2 Parameters 2 (Sequence No. 022)

Reads parameters in level 2 (input digital filter, alarm 1 hysteresis, alarm 2 hysteresis, alarm 3 hysteresis, input shift upper limit, and input shift lower limit) from multiple units and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units +2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 to 9 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | Number of units $\times 6+1$ |
| +1 | 1st unit <br> Input digital filter (4 digits BCD) | 0000 to 9999 |
| +2 | 1st unit <br> Alarm 1 hysteresis <br> (4 digits BCD) | 0001 to 9999 |
| +3 | 1st unit <br> Alarm 2 hysteresis <br> (4 digits BCD) | 0001 to 9999 |
| +4 | 1st unit <br> Alarm 3 hysteresis <br> (4 digits BCD) | 0001 to 9999 |
| +5 | 1st unit <br> Input shift upper limit (4 digits BCD) | A999 to 9999 <br> F indicates a negative value and A <br> indicates -1. |
| +6 | 1st unit <br> Input shift lower limit (4 digits BCD) | A999 to 9999 <br> F indicates a negative value and A <br> indicates -1. |
| $\bullet$ |  |  |
| +48 <br> (max.) | 8th unit <br> Input shift lower limit (4 digits BCD) | A999 to 9999 <br> F indicates a negative value and A <br> indicates -1. |

## General-purpose Read (Sequence No. 023)

Reads the specified parameter and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send <br> data | Number of send data words |  |  |
| :--- | :--- | :--- | :---: |
|  | +1 | (Undefined) | Unit No. |
|  | (Undefined) | Parameter No. |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Parameter No. (2 digits BCD) | Refer to the manual for the E5 $\square$ K. |

Receive Data Word Allocation (3rd Operand of PMCR)
Receive data storage words

|  | Number of receive data words |
| :---: | :---: |
|  | Read data |
|  |  |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Read data (4 digits BCD) | A999 to 9999 <br> F indicates a negative value and A <br> indicates -1. |

Note To read parameters in the setup mode or extended mode, execute Switch to Level 1 (Sequence No. 075) in advance.

# Appendix B <br> E5 $\square$ K Digital Controller Write Protocol 

The E5 $\square$ K Digital Controller Write Protocol writes and controls various settings in remote mode for the Controller connected to the Communications Board via RS-232C or RS-485 cable.
Note Negative values cannot be written. All values must be set as unsigned BCD.

## Structure of the Protocol

The following table shows the structure of the E5 $\square$ K Digital Controller Write Protocol.

| Sequence <br> No. | Communications <br> sequence name |  | Function |  |
| :--- | :--- | :--- | :---: | :---: |
|  |  |  | Send word <br> allocation | Receive word <br> allocation |
| 050 | Write set point | Writes the set point. | Yes | No |
| 051 | Write alarm value | Writes alarm value 1, 2. | Yes | No |
| 052 | Write proportional band, <br> integral time, and deriva- <br> tive time | Writes the prolortional band, integral <br> time, and derivative time. | Yes | No |
| 053 | Write cooling coefficient | Writes the cooling coefficient. | Yes | No |
| 054 | Write dead band | Writes the dead band. | Yes | No |
| 055 | Write manual reset value | Writes the manual reset value. | Yes | No |
| 056 | Write hysteresis | Writes the hysteresis (heating, cooling) | Yes | No |
| 057 | Write control period | Writes the control period (heating, cool- <br> ing) | Yes | No |
| 058 | Write SP ramp time units <br> and set value | Writes the SP ramp time unit and SP <br> ramp set value. | Yes | No |
| 059 | Write LBA detection time | Writes the LBA detection time. | Yes | No |
| 060 | Write MV at stop time and <br> PV error | Writes the MV at stop and the MV at PC <br> error. | Yes | No |
| 061 | Write MV limits | Writes the MV limits. | Yes | No |
| 062 | Write input digital filter | Writes the input digital filter. | Yes | No |
| 063 | Write alarm hysteresis | Writes alarm 1, 2 hysteresis. | Yes | No |
| 064 | Write input shift values | Writes the input shift values. | Yes | No |
| 065 | Write level 0 parameters | Writes parameters in level 0. | Yes | No |
| 066 | Write level 1 parameters 1 | Writes parameters in level 1. | Yes | No |
| 067 | Write level 1 parameters 2 | Writes parameters in level 1. | Yes | No |
| 068 | Write level 2 parameters 1 | Writes parameters in level 2. | Yes | No |
| 069 | Write level 2 parameters 2 | Writes parameters in level 2. | Yes | No |
| 070 | General-purpose write | Writes the value of the specified parame- <br> ter. | Yes | No |
| 071 | Switch to level 0 (software <br> reset) | Switches the setting level to level 0. | Yes | No |
| 072 | Run/stop | Initiates Run or Stop. | Yes | No |
| 073 | Remote/local | Switches the mode to remote or local <br> mode. | Yes | No |
| 074 | Execute/cancel AT | Executes or cancels AT. | Yes | No |
| 075 | Switch to level 1 | Switches the setting level to level 1. | Yes | No |
| 076 | Software reset | Resets the E5 $\square K . ~$ | Yes | No |

## Note Ladder Interface Settings

YES: User settings are required for the 2nd or 3rd operands of PMCR.
NO: Send word allocation: Set the constant 0000 for the 2nd operand (S).
Receive word allocation: Set a dummy word (e.g., DM0000) address for the 3rd operand (D).

## Connections

The connections are the same as that for the E5 $\square$ K Digital Controller Read Protocol.

## Write Set Point (Sequence No. 050)

Writes the set point.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of

|  | Number of send data words |  |  |
| :---: | :---: | :---: | :---: |
|  | (Undefined) |  | Unit No. |
|  | set point |  |  |
|  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Set point (4 digits BCD) | Set point lower limit to upper limit |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Alarm Value (Sequence No. 051)

Writes alarm value 1 and alarm value 2.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 data$+1$ | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
| +2 | Alarm value 1 |  |
| +3 | Alarm value 2 |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Alarm value 1 (4 digits BCD) | 0000 to 999 |
| +3 | Alarm value 2 (4 digits BCD) | 0000 to 9999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Proportional Band, Integral Time, and Derivative Time (Sequence No. 052)

Writes the proportional band, integral time, and derivative time.
Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 data | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
| +2 | Proportional band |  |
| +3 | Integral time |  |
| +4 | Derivative time |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0005 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Proportional band (4 digits BCD) | 0001 to 9999 |
| +3 | Integral time (4 digits BCD) | 0000 to 3999 |
| +4 | Derivative time (4 digits BCD) | 0000 to 3999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Cooling Coefficient (Sequence No. 053)

Writes the cooling coefficient.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  | Cooling coefficient |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Cooling coefficient (4 digits BCD) | 0001 to 9999 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Dead Band (Sequence No. 054)

Writes the dead band.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  | Dead band |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Dead band (4 digits BCD) | 0000 to 9999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Manual Reset Value (Sequence No. 055)

Writes the manual reset value.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) |  |
|  | Manual reset value |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Manual reset value (4 digits BCD) | 0000 to 1000 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Hysteresis (Sequence No. 056)

Writes the hysteresis for heating and for cooling.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| $+0 \mid$ | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  | Hysteresis (heating) |  |
|  | Hysteresis (cooling) |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Hysteresis (heating) <br> (4 digits BCD) | 0001 to 9999 |
| +3 | Hysteresis (cooling) <br> (4 digits BCD) | 0001 to 9999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Control Period (Sequence No. 057)

Writes the control period for heating and for cooling.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |
|  | Control period (heating) |  |
|  | Control period (cooling) |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Control period (heating) <br> (4 digits BCD) | 0001 to 0099 |
| +3 | Control period (cooling) <br> $(4$ digits BCD) | 0001 to 0099 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write SP Ramp Time Unit and Set Value (Sequence No. 058)

Writes the SP ramp time unit and SP ramp set value.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | SP ramp time unit (4 digits BCD) | $0000:$Minutes <br> $0001: \quad$ Hours <br> +3 |
|  | SP ramp set value (4 digits BCD) | 0000 to 9999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write LBA Detection Time (Sequence No. 059)

Writes the LBA detection time.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  | LBA detection time |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | LBA detection time (4 digits BCD) | 0000 to 9999 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write MV at Stop Time and at PV Error (Sequence No. 060)

Writes the MV at stop time and the MV at PV error.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  | MV at stop time |  |
| +3 | MV at PV error |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | MV at stop time (4 digits BCD) | 0000 to 1050 |
| +3 | MV at PV error (4 digits BCD) | 0000 to 1050 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write MV Limits (Sequence No. 061)

Writes the MV upper limit, MV lower limit, and MV change rate limit.
Send Data Word Allocation (2nd Operand of PMCR)


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0005 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | MV upper limit (4 digits BCD) | MV lower limit +1 to 1050 <br> Heating/cooling control time: 0000 to 1050 <br> +3 |
| +4 | MV lower limit (4 digits BCD) | 0000 to MV upper limit -1 |
|  | MV change rate limit <br> (4 digits BCD) | 0000 to 1000 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Input Digital Filter (Sequence No. 062)

Writes the input digital filter.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  | Input digital filter |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Input digital filter (4 digits BCD) | 0000 to 9999 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Alarm Hysteresis (Sequence No. 063)

Writes the alarm 1 hysteresis and alarm 2 hysteresis.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  | Alarm 1 hysteresis |  |
|  | Alarm 2 hysteresis |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Alarm 1 hysteresis <br> (4 digits BCD) | 0001 to 9999 |
| +3 | Alarm 2 hysteresis <br> (4 digits BCD) | 0001 to 9999 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Input Shift Value (Sequence No. 064)

Writes the input shift upper limit and input shift lower limit.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Input shift upper limit (4 digits BCD) | 0000 to 9999 |
| +3 | Input shift lower limit (4 digits BCD) | 0000 to 9999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Level 0 Parameters (Sequence No. 065)

Writes parameters (set points) in level 0 to multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)



Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Level 1 Parameters 1 (Sequence No. 066)

Writes parameters in level 1 (alarm value 1, alarm value 2, alarm value 3, proportional band, integral time, and derivative time) to multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | Number of units $\times 7+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 | 1st unit Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit Alarm value 1 (4 digits BCD) | A999 to 9999 <br> $F$ indicates a negative value and $A$ indicates -1 . |
| +4 | 1st unit Alarm value 2 (4 digits BCD) | A999 to 9999 <br> $F$ indicates a negative value and $A$ indicates -1 . |
| +5 | 1st unit Alarm value 3 (4 digits BCD) | A999 to 9999 <br> $F$ indicates a negative value and $A$ indicates -1 . |
| +6 | 1st unit Proportional band (4 digits BCD) | 0001 to 9999 |
| +7 | 1st unit Integral time (4 digits BCD) | 0000 to 3999 |
| +8 | 1st unit Derivative time (4 digits BCD) | 0000 to 3999 |
|  |  |  |
| $\begin{aligned} & +57 \\ & (\text { max. }) \end{aligned}$ | 8th unit <br> Derivative time (4 digits BCD) | 0000 to 3999 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Level 1 Parameter 2 (Sequence No. 067)

Writes parameters in level 1 (cooling coefficient, dead band, manual reset value, hysteresis (heating), hysteresis (cooling), control period (heating), and control period (cooling)) to multiple units.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units $\times 8+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit <br> Cooling coefficient (4 digits BCD) | 0001 to 9999 |
| +4 | 1st unit <br> Dead band (4 digits BCD) | 0000 to 9999 |
| +5 | 1st unit <br> Manual reset value (4 digits BCD) | 0000 to 1000 |
| +6 | 1st unit <br> Hysteresis (heating) <br> (4 digits BCD) | 0001 to 9999 |
| +7 | 1st unit <br> Hysteresis (cooling) <br> (4 digits BCD) | 0001 to 9999 |
| +8 | 1st unit <br> Control period (heating) <br> (4 digits BCD) | 0001 to 0099 |
| +9 | 1st unit <br> Control period (cooling) <br> (4 digits BCD) | 0001 to 0099 |
|  | • | 0001 to 0099 |
| +65 |  |  |
| (max.) | 8th unit <br> Control period (cooling) <br> (4 digits BCD) | • |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Level 2 Parameters 1 (Sequence No. 068)

Writes parameters in level 2 (SP ramp time unit, SP ramp set value, LBA detection time, MV at stop time, MV at PV error, MV upper limit, MV lower limit, and MV change rate limit) to multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


1st unit

8th unit (max.)

| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | Number of units $\times 9+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 | 1st unit Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit SP ramp time unit (4 digits BCD) | 0000 to 0001 |
| +4 | 1st unit SP ramp set value (4 digits $B C D$ ) | 0000 to 9999 |
| +5 | 1st unit LBA detection time (4 digits BCD) | 0000 to 9999 |
| +6 | 1st unit MV at stop (4 digits BCD) | 0000 to 1050 |
| +7 | ```1st unit MV at PV error (4 digits BCD)``` | 0000 to 1050 |
| +8 | 1st unit MV upper limit (4 digits BCD) | MV lower limit +1 to 1050 |
| +9 | 1st unit MV lower limit (4 digits BCD) | 0000 to MV upper limit -1 |
| +10 | 1st unit MV change rate limit (4 digits BCD) | 0000 to 1000 |
|  |  |  |
| $\begin{aligned} & \hline+73 \\ & \text { (max.) } \end{aligned}$ | 8th unit <br> MV change rate limit <br> (4 digits BCD) | 0000 to 1000 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Level 2 Parameters 2 (Sequence No. 069)

Writes parameters in level 2 (input digital filter, alarm 1 hysteresis, alarm 2 hysteresis, alarm 3 hysteresis, input shift upper limit, and input shift lower limit) to multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |  |
| :---: | :---: | :---: | :---: |
| +1 | Number of units |  |  |
| +2 | (Undefined) | Unit No. |  |
| +3 | Input digital filter |  |  |
| +4 | alarm 1 hysteresis |  |  |
| +5 | alarm 2 hysteresis |  | 1st unit |
| +6 | alarm 3 hysteresis |  |  |
| +7 | Input shift upper limit |  |  |
| $+8$ | Input shift lower limit |  |  |
|  |  |  |  |
| +51 | (Undefined) | Unit No. | 8th unit (max.) |
| +52 | Input digital filter |  |  |
| +53 | alarm 1 hysteresis |  |  |
| +54 | alarm 2 hysteresis |  |  |
| +55 | alarm 3 hysteresis |  |  |
| +56 | Input shift upper limit |  |  |
| +57 | Input shift lower limit |  |  |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | Number of units $\times 7+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 | 1st unit Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit Input digital filter (4 digits BCD) | 0000 to 9999 |
| +4 | 1st unit <br> Alarm 1 hysteresis <br> (4 digits BCD) | 0001 to 9999 |
| +5 | 1st unit <br> Alarm 2 hysteresis <br> (4 digits BCD) | 0001 to 9999 |
| +6 | 1st unit <br> Alarm 3 hysteresis <br> (4 digits BCD) | 0001 to 0099 |
| +7 | 1st unit Input shift upper limit (4 digits BCD) | 000 to 9999 |
| +8 | 1st unit Input shift lower limit (4 digits BCD) | 000 to 9999 |
|  | $\stackrel{-}{\bullet}$ |  |
| $\begin{aligned} & +57 \\ & \text { (max.) } \end{aligned}$ | 8th unit Input shift lower limit (4 digits BCD) | 000 to 9999 |

None.

## General-purpose Write (Sequence No. 070)

Writes the specified parameter.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |
| +2 | (Undefined) | Parameter No. |
| +3 | Write data |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0004 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Parameter No. (2 digits BCD) | Refer to the manual of E5 $\square$ K. |
| +3 | Write data (4 digits BCD) | 0000 to 9999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note To write parameters in the setup mode or extended mode, execute Switch to Level 1 (Sequence No. 075) in advance.

## Switch to Level 0 (Software Reset) (Sequence No. 071)

Resets the operation of the $\mathrm{E} 5 \square \mathrm{~K}$ and waits until communications are enabled. This sequence can be executed for multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send data |  | Number of send data words |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Number of units |  |  |  |
|  |  | (Undefined) |  | Unit No. |  |
|  |  | (Undefined) |  | Unit No. |  |
|  | +3 | $\sim$ |  |  |  |
|  | +9 | (Undefined) Unit No. (max.) |  |  |  |
|  |  | Offset |  | s (data format) | Data |
|  |  | +0 | $\begin{aligned} & \text { Numbe } \\ & \text { (4 digits } \end{aligned}$ | d data words | Number of units + 2 |
|  |  | +1 | Numbe (4 digits |  | 0001 to 0008 |
|  |  | +2 to 9 | Unit No (2 digit |  | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note When this sequence is executed, a software reset command is issued and the operation of the E5 $\square \mathrm{K}$ is reset (equivalent to turning on the power supply). About five seconds will be required until communications are enabled.

## Run/Stop (Sequence No. 072)

Switches the mode to Run or Stop according to the command code. This sequence can be executed for multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of
send data


| Offset | Contents (data format) | Data |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units $\times 2+2$ |  |  |  |  |  |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |  |  |  |  |  |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |
| +3 | 1st unit <br> Command code (4 digits BCD) | 0000: Run <br> $0001: ~ S t o p ~$ |  |  |  |  |  |
|  | $\bullet$ |  |  |  |  |  |  |
| (17 <br> (max.) | 8th unit <br> Command code (4 digits BCD) | $0000:$ Run <br> $0001: ~ S t o p ~$ |  |  |  |  |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Remote/Local (Sequence No. 073)

Switches to remote operation or local operation according to the command mode. This sequence can be executed for multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |  |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> $(4$ digits BCD) | Number of units $\times 2+2$ |  |  |  |  |  |  |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |  |  |  |  |  |  |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |  |
| +3 | 1st unit <br> Command code (4 digits BCD) | 0000: Local <br> 0001: Remote |  |  |  |  |  |  |
|  | $\bullet$ |  |  |  |  |  |  |  |
| +17 <br> (max.) | 8th unit <br> Command code (4 digits BCD) | 0000: Local <br> 0001: Remote |  |  |  |  |  |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Execute/Cancel AT (Sequence No. 074)

Executes or cancels AT (autotuning) according to the command code. This sequence can be executed for multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | Number of units $\times 2+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 | 1st unit Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit Command code (4 digits BCD) | 0000: Stop <br> 0001: Execute AT 40\% <br> 0002: Execute AT 100\% |
|  |  |  |
| $\begin{aligned} & \hline+17 \\ & \text { (max.) } \end{aligned}$ | 8th unit Command code (4 digits BCD) | 0000: Stop <br> 0001: Execute AT 40\% <br> 0002: Execute AT 100\% |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Switch to Level 1 (Sequence No. 075)

Switches the setting level to level 1 (setup mode, extended mode). This sequence can be executed for multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units +2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 to 9 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Software Reset (Sequence No. 076)

Resets the operation of the $\mathrm{E} \square \square \mathrm{K}$ (equivalent to turning on the power supply). This sequence can be executed for multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | Number of units +2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 to 9 | Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.
Note Communications with the E5 $\square \mathrm{K}$ are disabled for about five seconds after this sequence is executed.

# Appendix C E5ZE Temperature Controller Read Protocol 

The E5ZE Temperature Controller Read Protocol reads and controls various parameters in remote mode for the Temperature Controller connected to the Communications Board via RS-232C or RS-422A/485 cable.
Note All sequences in this appendix operate on memory bank 0 and cannot be used for other memory banks.

## Structure of the Protocol

The following table shows the structure of the E5ZE Temperature Controller Read Protocol

| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 100 | Read set point | Reads the set points. | Yes | Yes |
| 101 | Read process value | Reads the process values. | Yes | Yes |
| 102 | Read output value | Reads the output values. | Yes | Yes |
| 103 | Read set point, process value, and output value | Reads the set points, process values, and output values. | Yes | Yes |
| 104 | Read proportional band, integral time, and derivative time | Reads the proportional bands, integral times, and derivative times. | Yes | Yes |
| 105 | Read control period | Reads the control periods. | Yes | Yes |
| 106 | Read output mode | Reads the output modes. | Yes | Yes |
| 107 | Read alarm mode | Reads the alarm modes. | Yes | Yes |
| 108 | Read alarm temperature | Reads the alarm temperatures. | Yes | Yes |
| 109 | Read hysteresis | Reads the hysteresis. | Yes | Yes |
| 110 | Read operation status | Reads the operation status. | Yes | Yes |
| 111 | Read error status | Reads the error status. | Yes | Yes |
| 112 | Read setting unit | Reads the setting units. | Yes | Yes |
| 113 | Read input shift value | Reads the input shift values. | Yes | Yes |
| 114 | Read manual reset value | Reads the manual reset values. | Yes | Yes |
| 115 | Read ramp value | Reads the ramp values. | Yes | Yes |
| 116 | Read present set point | Reads the present set points. | Yes | Yes |
| 117 | Read output value limits | Reads the output value limits. | Yes | Yes |
| 118 | Read output value change rate limit | Reads the output value change rate limits. | Yes | Yes |
| 119 | Read HB alarm and HS alarm valid channels | Reads the HB alarm and HS alarm valid channels. | Yes | Yes |
| 120 | Read heater burnout/SSR failure detection currents | Reads the heater burnout/SSR failure detection currents. | Yes | Yes |
| 121 | Read heater current and SSR leakage current | Reads the heater currents and SSR leakage currents. | Yes | Yes |
| 122 | Read dead band/overlap band | Reads the dead bands and overlap bands. | Yes | Yes |
| 123 | Read cooling coefficient | Reads the cooling coefficients. | Yes | Yes |

## Note Ladder Interface Settings

YES: User settings are required for the 2nd or 3rd operands of PMCR.
NO: Send word allocation: Set the constant 0000 for the 2nd operand (S).
Receive word allocation: Set a dummy word (e.g., DM0000) address for the 3rd operand (D).

## Connections

This section shows connections for using the E5ZE Temperature Controller Read Protocol.

## RS-232C Connections

C200HX/HG/HE


| Signal name | Ab- <br> brevi- <br> ation | Signal direction | Pin No. |
| :--- | :--- | :--- | :--- |
| Signal ground or common <br> return line | SG | - | 7 |
| Send data | SD | Output | 2 |
| Receive data | RD | Input | 3 |
| Request to send | RS | Output | 4 |
| Clear to send | CS | Input | 5 |
| Data set ready | DR | Input | 6 |
| Data terminal ready | ER | Output | 20 |
| Disabled (Do not connect.) | NC | - | 1,8 to 19, 21 to 25 |



Note 1. The maximum communications cable length is 15 m . Use a shielded twisted-pair cable (AWG28 or greater) for the cable.
2. Use a 25 -pin D-sub Plug (OMRON XM2A-2501).
3. Use XM2S-2511 Hood (OMRON) or an equivalent.

## RS-422/485 Connections

## - RS-485

| Pin No. | Signal name | Abbreviation | Signal direction |
| :--- | :--- | :--- | :--- |
| 1 | Disabled (Do not connect.) | - | - |
| 2 | Disabled (Do not connect.) | - | - |
| 3 | Signal ground | SG | - |
| 4 | Terminal B (+ side) | B | I/O |
| 5 | Terminal A (- side) | A | I/O |

Turn off the communications switch


Note Terminal block pins 1 and 2 cannot be connected. If these blocks are used, operation of the E5ZE may fail.

- RS-422A

| Pin No. | Signal name | Abbreviation | Signal direction |
| :--- | :--- | :--- | :--- |
| 1 | Receive data B | RDB | Input |
| 2 | Receive data A | RDA | Input |
| 3 | Signal ground | SG | - |
| 4 | Send data B | SDB | Output |
| 5 | Send data A | SDA | Output |



Terminal resistance $240 \Omega$

## Switch Settings

This section shows the switch settings for using the E5ZE Temperature Controller Read Protocol.

## Communications Parameter DIP Switch

Pins 3 and 4: Terminal resistance
Pins 1 and 2: RS-422A/RS-485


Factory defaults: All OFF

| Pins | Parameter |  | RS-422A | RS-485 |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 3 and 4 | Terminal resistance | ON |  |  |  |
|  |  | OFF |  |  |  |
| 1 and 2 | RS-422A or RS-485 |  |  |  |  |

## Unit Number Switch

| Setting | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | $A$ | $B$ | $C$ | $D$ | $E$ | $F$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| Unit No. | 00 | 01 | 02 | 03 | 04 | 05 | 06 | 07 | 08 | 09 | $0 A$ | $0 B$ | $0 C$ | $0 D$ | $0 E$ | $0 F$ |

A Factory defaults

## Baud Rate DIP Switch



## Read Set Point (Sequence No. 100)

Reads the set points and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0017 |
| +1 | Channel 0 <br> Set point (rightmost 4 digits) <br> (4 digits BCD) | Varies according to the temperature sensor <br> type. Refer to the manual for the E5ZE. <br> F indicates a negative value. |
| +2 | Channel 0 (leftmost 1 digit) <br> Set point (etm <br> (1 digit BCD) | • |
| +15 | Channel 7 <br> Set point (rightmost 4 digits) <br> (4 digits BCD) | Varies according to the temperature sensor <br> type. Refer the manual for the E5ZE. <br> F indicates a negative value. |
| +16 | Channel 7 <br> Set point (leftmost 1 digit) <br> (1 digit BCD) | n |

## Read Process Value (Sequence No. 101)

Reads the process values and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 | Number of send data words |  |
| :---: | :---: | :---: |
| data +1 | (Undefined) | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0017 |
| +1 | Channel 0 <br> Process value (rightmost 4 digits) <br> (4 digits BCD) | Varies according to the temperature sensor <br> type. Refer to the manual for the E5ZE. <br> F indicates a negative value. |
| +2 | Channel 0 <br> Process value (leftmost 1 digit) <br> (1 digit BCD) |  |
| +15 | Channel 7 <br> Process value (rightmost 4 digits) <br> (4 digits BCD) | Varies according to the temperature sensor <br> type. Refer to the manual for the E5ZE. <br> F indicates a negative value. |
| +16 | Channel 7 <br> Process value (leftmost 1 digit) <br> (1 digit BCD) |  |

## Read Output Values (Sequence No. 102)

Reads the output values of the control outputs and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data
storage words

| +0 | Number of receive data words | Channel 0 |
| :---: | :---: | :---: |
| +1 | Output value |  |
| +2 | Cooling output value |  |
| +3 | Output value | Channel 1 |
| +4 | Cooling output value |  |
|  |  |  |
| +15 | Output value | Channel 7 |
| +16 | Cooling output value |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0017 |
| +1 | Channel 0 <br> Output value (4 digits BCD) | 0000 to 1000 |
| +2 | Channel 0 <br> Cooling output value (4 digits BCD) | 0000 to 1000 |
| +3 | Channel 1 <br> Output value (4 digits BCD) | 0000 to 1000 |
| +4 | Channel 1 <br> Cooling output value (4 digits BCD) | 0000 to 1000 |
| +15 | Channel 7 <br> Output value (4 digits BCD) | 0000 to 1000 |
| +16 | Channel 7 <br> Cooling output value (4 digits BCD) | 0000 to 1000 |

## Read Set Point, Process Value, and Output Value (Sequence No. 103)

Reads the set points, process values, and output values and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)

| First word of | +0 | Number of send data words |  |
| :--- | :--- | :--- | :--- |
| send data | +1 | (Undefined) | Unit No. |
|  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to OF |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0041 |
| +1 | Channel 0 <br> Set point (rightmost 4 digits) (4 digits BCD) | Varies according to the temperature sensor type. Refer to the manual for the E5ZE. |
| +2 | Channel 0 <br> Set point (leftmost 1 digit) <br> (1 digit BCD) |  |
| +3 | Channel 0 <br> Process value (rightmost 4 digits) <br> (4 digits BCD) | Varies according to the temperature sensor type. Refer to the manual for the E5ZE. |
| +4 | Channel 0 <br> Process value (leftmost 1 digit) <br> (1 digit BCD) |  |
| +5 | Channel 0 <br> Output value (4 digits BCD) | 0000 to 1000 |
|  |  |  |
| +36 | Channel 7 <br> Set point (rightmost 4 digits) (4 digits BCD) | Varies according to the temperature sensor type. Refer to the manual for the E5ZE. |
| +37 | Channel 7 <br> Set point (leftmost 1 digit) <br> (1 digit BCD) |  |
| +38 | Channel 7 <br> Process value (rightmost 4 digits) <br> (4 digits BCD) | Varies according to the temperature sensor type. Refer to the manual for the E5ZE. |
| +39 | Channel 7 <br> Process value (leftmost 1 digit) <br> (1 digit BCD) |  |
| +40 | Channel 0 <br> Output value (4 digits BCD) | 0000 to 1000 |

## Read Proportional Band, Integral Time, and Derivative Time (Sequence No. 104)

Reads the proportional bands (constant P), integral times (constant I), and derivative times (Constant D) and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0025 |
| +1 | Channel 0 <br> Constant P (4 digits BCD) | 0000 to 9999 |
| +2 | Channel 0 <br> Constant I (4 digits BCD) | 0000 to 3999 |
| +3 | Channel 0 <br> Constant D (4 digits BCD) | 0000 to 3999 |
|  | $\stackrel{-}{\bullet}$ |  |
| +22 | Channel 7 <br> Constant P (4 digits BCD) | 0000 to 9999 |
| +23 | Channel 7 <br> Constant I (4 digits BCD) | 0000 to 3999 |
| +24 | Channel 7 <br> Constant D (4 digits BCD) | 0000 to 3999 |

## Read Control Period (Sequence No. 105)

Reads the control periods and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data


| Offset | Contents (data format) | Data |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| +0 | Number of receive data words <br> (4 digits BCD) | 0017 |  |  |  |  |
| +1 | Channel 0 <br> Control period (4 digits BCD) | 0001 to 0099 |  |  |  |  |
| +2 | Channel 0 <br> Cooling control period <br> (4 digits BCD) | 0001 to 0099 |  |  |  |  |
|  | $\bullet$ |  |  |  |  |  |
| $\bullet$ | 0001 to 0099 |  |  |  |  |  |
| +15 | Channel 7 <br> Control period (4 digits BCD) | Channel 7 <br> Cooling control period <br> $(4$ digits BCD) |  |  |  |  |

## Read Output Mode (Sequence No. 106)

Reads the output modes (normal/reverse) and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) |  | Data |
| :--- | :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |  |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words $\square$

| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Set code (2 digits Hex) | 00 to FF |

## Read Alarm Mode (Sequence No. 107)

Reads the alarm modes and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data
storage words


| Offset | Contents (data format) | Data |  |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of receive data words <br> (4 digits BCD) | 0017 |  |  |  |  |  |  |
| +1 | Channel 0 <br> Alarm 1 set code (2 digits Hex) | 00 to 0C |  |  |  |  |  |  |
| +2 | Channel 0 <br> Alarm 2 set code (2 digits Hex) | 00 to 0C |  |  |  |  |  |  |
|  | $\quad \bullet$ |  |  |  |  |  |  |  |
| +15 | Channel 7 <br> Alarm 1 set code (2 digits Hex) | 00 to 0C |  |  |  |  |  |  |
| +16 | Channel 7 <br> Alarm 2 set code (2 digits Hex) | 00 to 0C |  |  |  |  |  |  |

## Read Alarm Temperatures (Sequence No. 108)

Reads the alarm temperatures and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0033 |
| +1 | Channel 0 <br> Alarm 1 set value (rightmost 4 digits) <br> (4 digits BCD) | 0000 to 9999 <br> F indicates a negative number. |
| +2 | Channel 0 <br> Alarm 1 set value (leftmost 1 digit) <br> (4 digits BCD) | 0000 to 0009 <br> F indicates a negative number. |
| +3 | Channel 0 <br> Alarm 2 set value (rightmost 4 digits) <br> (4 digits BCD) | 0000 to 9999 <br> F indicates a negative number. |
| +4 | Channel 0 <br> Alarm 2 set value (leftmost 1 digit) <br> (4 digits BCD) | 0000 to 0009 <br> F indicates a negative number. |
| +29 | Channel 7 <br> Alarm 1 set value (rightmost 4 digits) <br> (4 digits BCD) | 0000 to 9999 <br> F indicates a negative number. |
| +30 | Channel 7 <br> Alarm 1 set value (leftmost 1 digit) <br> (4 digits BCD) | 0000 to 0009 <br> F indicates a negative number. |
| +31 | Channel 7 <br> Alarm 2 set value (rightmost 4 digits) <br> (4 digits BCD) | 0000 to 9999 <br> F indicates a negative number. |
| +32 | Channel 07 <br> Alarm 2 set value (leftmost 1 digit) <br> (4 digits BCD) | 0000 to 0009 <br> F indicates a negative number. |

## Read Hysteresis (Sequence No. 109)

Reads the hysteresis and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0017 |
| +1 | Channel 0 <br> Hysteresis (4 digits BCD) | 0000 to 0999 |
| +2 | Channel 0 <br> Cooling hysteresis (4 digits BCD) | 0000 to 0999 |
|  | $\bullet \bullet$ |  |
| $\bullet$ |  |  |$\quad$| - |
| :--- |

## Read Operation Status (Sequence No. 110)

Reads the operation status of the E5ZE and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0009 |
| +1 | Channel 0 <br> Status code (4 digits Hex) | 0000 to FFFF |
| +2 | Channel 1 <br> Status code (4 digits Hex) | 0000 to FFFF |
|  | $\bullet \bullet$ |  |
| $\bullet$ |  |  |
| +8 | Channel 7 <br> Status code (4 digits Hex) | 0000 to FFFF |

## Read Error Status (Sequence No. 111)

Reads the contents of errors if they have occurred and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0009 |
| +1 | Status code (4 digits BCD) | 0000 to FFFF |

## Read Setting Unit (Sequence No. 112)

Reads the setting units and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |  |
| :---: | :---: | :---: | :---: |
|  | Numefined) |  | Unit No. |
|  |  |  |  |
|  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Set code (4 digits BCD) | 0000: unit of 1 <br> 0001 : unit of 0.1 |

## Read Input Shift Value (Sequence No. 113)

Reads the input shift values and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | Unit No. |  |
|  | (Undefined) | Und |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of receive data words <br> (4 digits BCD) | 0009 |  |  |  |  |  |
| +1 | Channel 0 <br> Input shift value (4 digits BCD) | 0000 to 0999 <br> F indicates a negative number. |  |  |  |  |  |
| +2 | Channel 1 <br> Input shift value (4 digits BCD) | 0000 to 0999 <br> F indicates a negative number. |  |  |  |  |  |
|  | $\bullet \bullet$ |  |  |  |  |  |  |
|  | $\bullet$ |  |  |  |  |  |  |
| +8 | Channel 7 <br> Input shift value (4 digits BCD) | 0000 to 0999 <br> F indicates a negative number. |  |  |  |  |  |

## Read Manual Reset Value (Sequence No. 114)

Reads the manual reset value and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| Number of send data words |  |  |
| :---: | :---: | :---: |
|  | Num |  |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| +0 | Number of receive data words <br> (4 digits BCD) | 0009 |  |  |  |  |
| +1 | Channel 0 <br> Manual reset value <br> (4 digits BCD) | 0000 to 1000 |  |  |  |  |
| +2 | Channel 1 <br> Manual reset value <br> (4 digits BCD) | 0000 to 1000 |  |  |  |  |
|  | $\bullet$ |  |  |  |  |  |
| +8 | Channel 7 <br> Manual reset value <br> $(4$ digits BCD) | 0000 to 1000 |  |  |  |  |

## Read Ramp Value (Sequence No. 115)

Reads the ramp values and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |  |  | Channel 0 |
| :---: | :---: | :---: | :---: | :---: |
| +1 | (Undefined) | Ramp value |  |  |
| +2 | Time unit |  | (Undefined) |  |
| +3 | (Undefined) | Ramp value |  | Channel 1 |
| $+4$ | Time unit |  | (Undefined) |  |
|  |  |  | $\sim$ |  |
| +15 | (Undefined) | Ramp value |  | Channel 7 |
| +16 | Time unit |  | (Undefined) |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | $\begin{array}{l}\text { Number of receive data words } \\ \text { (4 digits BCD) }\end{array}$ | 0017 |
| +1 | $\begin{array}{l}\text { Channel 0 } \\ \text { Ramp value (3 digits BCD) }\end{array}$ | 000 to 999 |
| +2 | $\begin{array}{l}\text { Channel 0 } \\ \text { Time unit (one ASCII character) }\end{array}$ | S: Seconds; M: Minutes; H: Hours |
|  | $\bullet$ |  |
| $\bullet$ |  |  |
| $\bullet$ |  |  |$)$

## Read Present Set Point (Sequence No. 116)

Reads the present set points during ramp operation and stores the results in the specified word.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

| Receive data storage words | $\begin{array}{r} +2 \\ \\ +15 \\ +16 \end{array}$ |  | Number of receive data words Present set point (rightmost 4 digits) Present set point (leftmost 1 digit) Present set point (rightmost 4 digits) Present set point (leftmost 1 digit) | Channel 0 Channel 7 |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Offset | Contents (data format) | Data |
|  |  | +0 | Number of receive data words (4 digits BCD) | 0017 |
|  |  | +1 | Channel 0 <br> Present set point (rightmost 4 digits) <br> (4 digits BCD) | Varies according to the temperature sensor type. Refer to the manual for the E5ZE. <br> F indicates a negative value. |
|  |  | +2 | Channel 0 <br> Present set point (leftmost 1 digit) <br> (1 digit BCD) |  |
|  |  |  |  |  |
|  |  | +15 | Channel 7 <br> Present set point (rightmost 4 digits) (4 digits BCD) | Varies according to the temperature sensor type. Refer to the manual for the E5ZE. $F$ indicates a negative value. |
|  |  | +16 | Channel 7 <br> Present set point (leftmost 1 digit) (1 digit $B C D$ ) |  |

## Read Output Value Limit (Sequence No. 117)

Reads the output value limits and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0033 |
| +1 | Channel 0 <br> Output value lower limit <br> (4 digits BCD) | 0000 to 1000 |
| +2 | Channel 0 <br> Output value upper limit <br> (4 digits BCD) | 0000 to 1000 |
| +3 | Channel 0 <br> Cooling control output value upper <br> limit (4 digits BCD) | 0000 to 1000 |
| +4 | Channel 0 <br> Cooling control output value upper <br> limit (4 digits BCD) | 0000 to 1000 |
| +31 | Channel 7 <br> Cooling control output value upper <br> limit (4 digits BCD) | 0000 to 1000 |
| +32 | Channel 7 <br> Cooling control output value upper <br> limit (4 digits BCD) | 0000 to 1000 |

## Read Output Value Change Rate Limit (Sequence No. 118)

Reads the output value change rate limits and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| Number of send data words |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Und |  | Undefined) | Unit No. |
|  |  |  |  |  |


| Offset | Contents (data format) |  |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | Data |
| +1 | Unit No. (2 digits Hex) | 0002 (fixed) |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

Channel 0 Channel 1 Channel 7

| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0009 |
| +1 | Channel 0 <br> Output value change rate limit <br> (4 digits BCD) | 0000 to 1000 |
| +2 | Channel 1 <br> Output value change rate limit <br> (4 digits BCD) | 0000 to 1000 |
|  | $\bullet$ | 0 |
| +8 | Channel 7 <br> Output value change rate limit <br> $(4$ digits BCD) | 0000 to 1000 |

## Read HB Alarm and HS Alarm Valid Channels (Sequence No. 119)

Reads the valid or invalid channels for HB alarms and HS alarms and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |  |
| :---: | :---: | :---: | :---: |
|  | (Undefined) |  | Unit No. |
|  |  |  |  |
|  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Set code |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0009 |
| +1 | Set code (2 digits Hex) | 00 to FF |

## Read Heater Burnout and SSR Failure Detection Currents (Sequence No. 120)

Reads the heater burnout and SSR failure detection currents and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0017 |
| +1 | Channel 0 <br> Heater burnout detection current ( 4 digits BCD) | 0000 to 0500 |
| +2 | Channel 0 SSR failure detection current (4 digits BCD) | 0000 to 0500 |
|  |  |  |
| +15 | Channel 7 <br> Heater burnout detection current (4 digits BCD) | 0000 to 0500 |
| +16 | Channel 7 <br> SSR failure detection current <br> (4 digits BCD) | 0000 to 0500 |

## Read Heater Current and SSR Leakage Current (Sequence No.121)

Reads the heater currents and SSR leakage currents and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of receive data words <br> (4 digits BCD) | 0017 |  |  |  |  |  |
| +1 | Channel 0 <br> Heater current <br> (4 digits BCD) | 0000 to 0500 |  |  |  |  |  |
| +2 | Channel 0 <br> SSR leakage current <br> (4 digits BCD) | 0000 to 0500 |  |  |  |  |  |
|  | $\bullet$ |  |  |  |  |  | 0000 to 0500 |
| +15 | Channel 7 <br> Heater current <br> (4 digits BCD) | Channel 7 <br> SSR leakage current <br> $(4$ digits BCD) |  |  |  |  |  |
| +16 | 0000 to 0500 |  |  |  |  |  |  |

Note The read data will be 0000 for all channels for which HB and HS alarms are not enabled and for all channels for which control is stopped.

## Read Dead Band/Overlap Band (Sequence No. 122)

Reads the dead bands/overlap bands and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| Number of send data words |  |  |
| :---: | :---: | :---: |
|  | Number |  |
|  | (Undefined) |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0009 |
| +1 | Channel 0 Dead band/overlap band ( 4 digits BCD) | 0000 to 0999 <br> $F$ indicates a number. |
| +2 | Channel 1 <br> Dead band/overlap band (4 digits BCD) | $\begin{aligned} & 0000 \text { to } 0999 \\ & \text { F indicates a number. } \end{aligned}$ |
|  |  |  |
| +8 | Channel 7 <br> Dead band/overlap band ( 4 digits BCD) | 0000 to 0999 <br> $F$ indicates a number. |

## Read Cooling Coefficient (Sequence No. 123)

Reads the cooling coefficients and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | Unit No. |  |
|  | (Undefined) |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0009 |
| +1 | Channel 0 <br> Cooling coefficient (4 digits BCD) | 0000 to 0100 |
| +2 | Channel 1 <br> Cooling coefficient (4 digits BCD) | 0000 to 0100 |
|  | $\bullet$ <br> $\bullet$ |  |
| +8 | Channel 7 <br> Cooling coefficient (4 digits BCD) | 0000 to 0100 |

# Appendix D <br> E5ZE Temperature Controller Write Protocol 

The E5ZE Temperature Controller Write Protocol writes and controls various settings in remote mode for the Temperature Controller connected via a RS-232C or RS-422A/485 cable from the PC via the Communications Board.
Note 1. Negative values cannot be written. All values must be set as unsigned BCD.
2. All sequences in this appendix operate on memory bank 0 and cannot be used for other memory banks.

## Structure of the Protocol

The following table shows the structure of the E5ZE Temperature Controller Write Protocol.

| quence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 150 | Write set point (setting unit 1) | Writes the set points using a setting unit of 1. | Yes | No |
| 151 | Write set point (setting unit 0.1) | Writes the set points using a setting unit of 0.1 . | Yes | No |
| 152 | Write proportional band, integral time, and derivative time | Writes the proportional bands, integral times, and derivative times. | Yes | No |
| 153 | Write control period | Writes the control periods. | Yes | No |
| 154 | Write output mode | Writes the output modes. | Yes | No |
| 155 | Write alarm mode | Writes the alarm modes. | Yes | No |
| 156 | Write alarm temperature (setting unit 1) | Writes the alarm temperatures using a setting unit of 1 . | Yes | No |
| 157 | Write alarm temperature (setting unit 0.1) | Writes the alarm temperatures using a setting unit of 0.1 . | Yes | No |
| 158 | Write hysteresis | Writes the hysteresis. | Yes | No |
| 159 | Start autotuning | Starts autotuning. | Yes | No |
| 160 | Cancel autotuning | Cancels autotuning. | Yes | No |
| 161 | Write setting unit | Writes the setting units. | Yes | No |
| 162 | Write input shift value | Writes the input shift values. | Yes | No |
| 163 | Write manual reset value | Writes the manual reset values. | Yes | No |
| 164 | Write ramp value | Writes the ramp values. | Yes | No |
| 165 | Write manual output value | Writes the manual output values. | Yes | No |
| 166 | Write output value limit | Writes the output value limits. | Yes | No |
| 167 | Write output value change rate limit | Write output value change rate limits. | Yes | No |
| 168 | Save settings | Saves settings. | Yes | No |
| 169 | Initialize settings | Initializes settings. | Yes | No |
| 170 | Write HB alarm and HS alarm valid channels | Writes the HB alarm and HS alarm valid channels. | Yes | No |
| 171 | Write heater burnout and SSR failure detection currents | Writes the heater burnout and SSR failure detection currents. | Yes | No |
| 172 | Write dead band/overlap band | Writes the dead bands/overlap bands. | Yes | No |
| 173 | Write cooling coefficient | Writes the cooling coefficients. | Yes | No |
| 174 | Start control | Starts temperature control. | Yes | No |
| 175 | Stop operation or control | Stops temperature control or manual operation. | Yes | No |
| 176 | Start manual operation | Starts manual operation. | Yes | No |

## Note Ladder Interface Settings

YES: User settings are required for the 2nd or 3rd operands of PMCR.
NO: Send word allocation: Set the constant 0000 for the 2nd operand (S).
Receive word allocation: Set a dummy word (e.g., DM0000) address for the 3rd operand (D).

## Connections

The connections are the same as that for the E5ZE Temperature Controller Read Protocol.

## Write Set Point (Setting Unit 1) (Sequence No. 150)

Writes the set points using a setting unit of 1 (4 digits).

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | 0018 (fixed) |  |  |  |  |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |  |  |  |  |
| +2 | Channel 0 <br> Set point <br> (4 digits BCD) | Varies according to the temperature sensor <br> type. Refer to the manual for the E5ZE. |  |  |  |  |
|  | $\bullet$ |  |  |  |  |  |
| +16 | Channel 7 <br> Set point <br> (4 digits BCD) | Varies according to the temperature sensor <br> type. Refer to the manual for the E5ZE. |  |  |  |  |
| +17 | Not used | --- |  |  |  |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note When the setting unit for the set point is 0.1 ( 5 digits), use Write Set Point (Setting Unit 0.1), Sequence No. 151.

## Write Set Point (Setting Unit 0.1) (Sequence No. 151)

Writes the set points using a setting unit of 0.1 ( 5 digits).

## Send Data Word Allocation (2nd Operand of PMCR)



## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note When the setting unit for the set point is 1 (4 digits), use Write Set Point (Setting Unit 1), Sequence No. 150.

## Write Proportional Band, Integral Time, and Derivative Time (Sequence No. 152)

Writes the proportional bands (constant P), integral times (constant I), and derivative times (constant D).

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0026 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel 0 <br> Constant P (4 digits BCD) | 0000 to 9999 |
| +3 | Channel 0 <br> Constant I (4 digits BCD) | 0000 to 3999 |
| +4 | Channel 0 <br> Constant D (4 digits BCD) | 0000 to 3999 |
| +23 | Channel 7 <br> Constant P (4 digits BCD) | 0000 to 9999 |
| +24 | Channel 7 <br> Constant I (4 digits BCD) | 0000 to 3999 |
| +25 | Channel 7 <br> Constant D (4 digits BCD) | 0000 to 3999 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Control Period (Sequence No. 153)

Writes the control periods and cooling control periods.

## Send Data Word Allocation (2nd Operand of PMCR)



Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Output Mode (Sequence No. 154)

Writes the output mode (normal/reverse).

## Send Data Word Allocation (2nd Operand of PMCR)

| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Write code (2 digits Hex) | 00 to FF |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Alarm Mode (Sequence No. 155)

Writes the alarm modes for alarm 1 and alarm 2.

## Send Data Word Allocation (2nd Operand of PMCR)



Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Alarm Temperature (Setting Unit 1) (Sequence No. 156)

Writes the alarm temperatures using a setting unit of 1 (4 digits)
Send Data Word Allocation (2nd Operand of PMCR)


Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Alarm Temperature (Setting Unit 0.1) (Sequence No. 157)

Writes the alarm temperatures using a setting unit of 0.1 ( 5 digits)
Send Data Word Allocation (2nd Operand of PMCR)


Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Hysteresis (Sequence No. 158)

Writes the hysteresis for control outputs for ON/OFF control.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of
send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0018 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel 0 <br> Hysteresis (4 digits BCD) | 0000 to 0999 |
| +3 | Channel 0 <br> Cooling hysteresis (4 digits BCD) | 0000 to 0999 |
| +4 | Channel 1 <br> Hysteresis (4 digits BCD) | 0000 to 0999 |
| +5 | Channel 1 <br> Cooling hysteresis (4 digits BCD) | 0000 to 0999 |
| +16 | $\bullet$ | Channel 7 <br> Hysteresis (4 digits BCD) |
| +17 | Channel 7 <br> Cooling hysteresis (4 digits BCD) | 0000 to 0999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Start Autotuning (Sequence No. 159)

Starts autotuning (AT).

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel (Channel) No. (1 digit BCD) | 0 to 7 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Cancel Autotuning (Sequence No. 160)

Cancels Autotuning (AT) for all channels.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Setting Unit (Sequence No. 161)

Writes the setting unit.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  | Write code |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD $)$ | 0003 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Write code (4 digits BCD) | 0000 : unit of 1 <br> $0001:$ unit of 0.1 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Input Shift Value (Sequence No. 162)

Writes the input shift values.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  | Channel 0 |
| :---: | :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |  |
| +2 | Input shift value |  |  |
| +3 | Input shift value |  | Channel 1 |
| +4 | Input shift value |  | Channel 2 |
| +5 | Input shift value |  | Channel 3 |
| +6 | Input shift value |  | Channel 4 |
| +7 | Input shift value |  | Channel 5 |
| +8 | Input shift value |  | Channel 6 |
| +9 | Input shift value |  | Channel 7 |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0010 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel 0 <br> Input shift value (4 digits BCD) | 0000 to 0999 |
| +3 | Channel 1 <br> Input shift value (4 digits BCD) | 0000 to 0999 |
| +4 | Channel 2 <br> Input shift value (4 digits BCD) | 0000 to 0999 |
| +8 | Channel 6 <br> - |  |
| +9 | Channel 7 <br> Input shift value (4 digits BCD) | 0000 to 0999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Manual Reset Value (Sequence No. 163)

Writes the manual reset values.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |  |
| :---: | :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |  |
| +2 | Manual reset value |  | Channel 0 |
| +3 | Manual reset value |  | Channel 1 |
| +4 | Manual reset value |  | Channel 2 |
| +5 | Manual reset value |  | Channel 3 |
| +6 | Manual reset value |  | Channel 4 |
| +7 | Manual reset value |  | Channel 5 |
| +8 | Manual reset value |  | Channel 6 |
| +9 | Manual reset value |  | Channel 7 |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0010 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel 0 <br> Manual reset value <br> (4 digits BCD) | 0000 to 1000 |
| +3 | Channel 1 <br> Manual reset value <br> (4 digits BCD) | 0000 to 1000 |
| +4 | Channel 2 <br> Manual reset value <br> (4 digits BCD) | 0000 to 1000 |
| +8 | Channel 6 <br> Manual reset value <br> (4 digits BCD) | Channel 7 <br> Manual reset value <br> (4 digits BCD) |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Ramp Value (Sequence No. 164)

Writes the ramp values.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0018 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel 0 <br> Ramp value (3 digits BCD) | 000 to 999 |
| +3 | Channel 0 <br> Time unit (one ASCII character) | S: Seconds; M: Minutes; H: Hours |
| +4 | Channel 1 <br> Ramp value (3 digits BCD) | 000 to 999 |
| +5 | Channel 1 <br> Time unit (one ASCII character) | S: Second M: Minute H: Hour |
| $\quad \bullet$ | $\bullet$ | © |
| +16 | Channel 7 <br> Ramp value (3 digits BCD) | Channel 7 <br> Time unit (one ASCII character) |
| +17 | S: Seconds; M: Minutes; H: Hours |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Manual Output Value (Sequence No. 165)

Writes the manual output values for control output in manual operation.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0018 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel 0 <br> Output value (4 digits BCD) | 0000 to 1000 |
| +3 | Channel 0 <br> Cooling output value <br> (4 digits BCD) | 0000 to 1000 |
| +4 | Channel 1 <br> Output value (4 digits BCD) | 0000 to 1000 |
| +5 | Channel 1 <br> Cooling output value <br> (4 digits BCD) | 0000 to 1000 |
| +16 | Channel 7 <br> Output value (4 digits BCD) | 0000 to 1000 |
| +17 | Channel 7 <br> Cooling output value <br> (4 digits BCD) | 0000 to 1000 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Output Value Limit (Sequence No. 166)

Writes the output value limits that restrict the values of the control outputs.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0034 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel 0 <br> Output value lower limit <br> $(4$ digits BCD) | 0000 to 1000 |
| +3 | Channel 0 <br> Output value upper limit <br> $(4$ digits BCD) | 0000 to 1000 |
| +4 | Channel 0 <br> Cooling output value lower limit <br> (4 digits BCD) | 0000 to 1000 |
| +5 | Channel 0 <br> Cooling output value upper limit <br> (4 digits BCD) | 0000 to 1000 |
|  | • | 0000 to 1000 |
| +32 | Channel 7 <br> Cooling output value lower limit <br> $(4$ digits BCD) | Channel 7 <br> Cooling output value upper limit <br> (4 digits BCD) |
| +33 | 0000 to 1000 |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Output Value Change Rate Limit (Sequence No. 167)

Writes the output value change rate limits that restrict the rates of change in the control value output.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  | Channel 0 |
| :---: | :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |  |
| +2 | Output change rate limit |  |  |
| +3 | Output change rate limit |  | Channel 1 |
| +4 | Output change rate limit |  | Channel 2 |
| +5 | Output change rate limit |  | Channel 3 |
| +6 | Output change rate limit |  | Channel 4 |
| +7 | Output change rate limit |  | Channel 5 |
| +8 | Output change rate limit |  | Channel 6 |
| +9 | Output change rate limit |  | Channel 7 |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0010 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel 0 <br> Output change rate limit <br> (4 digits BCD) | 0000 to 1000 |
| +3 | Channel 1 <br> Output change rate limit <br> (4 digits BCD) | 0000 to 1000 |
| +4 | Channel 2 <br> Output change rate limit <br> (4 digits BCD) | 0000 to 1000 |
| +8 | Channel 6 <br> Output change rate limit <br> (4 digits BCD) | 0000 to 1000 |
| +9 | Channel 7 <br> Output change rate limit <br> (4 digits BCD) | 0000 to 1000 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Save Settings (Sequence No. 168)

Saves the settings.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |
|  |  |  |


| Offset | Contents (data format) |  | Data |
| :--- | :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |  |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Initialize Settings (Sequence No. 169)

Initializes all the settings to the factory defaults.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write HB and HS Alarm Valid Channels (Sequence No. 170)

Writes the valid or invalid channels of HB alarm and HS alarm.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
| +2 | (Undefined) | Write code |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Write code (2 digits Hex) | 00 to FF |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Heater Burnout and SSR Failure Detection Current (Sequence No. 171)

Writes the currents for detecting heater burnouts and SSR failures.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


## Write Dead Band/Overlap Band (Sequence No. 172)

Writes the dead bands or overlap bands for control outputs during heating/cooling control.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  | Channel 0 |
| :---: | :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |  |
| +2 | Dead band/overlap band |  |  |
| +3 | Dead band/overlap band |  | Channel 1 |
| +4 | Dead band/overlap band |  | Channel 2 |
| +5 | Dead band/overlap band |  | Channel 3 |
| +6 | Dead band/overlap band |  | Channel 4 |
| +7 | Dead band/overlap band |  | Channel 5 |
| +8 | Dead band/overlap band |  | Channel 6 |
| +9 | Dead band/overlap band |  | Channel 7 |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0010 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel 0 <br> Dead band/overlap band <br> (4 digits BCD) | 0000 to 0999 |
| +3 | Channel 1 <br> Dead band/overlap band <br> (4 digits BCD) | 0000 to 0999 |
| +4 | Channel 2 <br> Dead band/overlap band <br> (4 digits BCD) | 0000 to 0999 |
| +8 | Channel 6 <br> Dead band/overlap band <br> (4 digits BCD) | 0000 to 0999 |
| +9 | Channel 7 <br> Dead band/overlap band <br> (4 digits BCD) | 0000 to 0999 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Cooling Coefficient (Sequence No. 173)

Writes the cooling coefficients for the cooling proportional bands for heating/cooling control.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of

| +0 | Number of send data words |  | Channel 0 |
| :---: | :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |  |
| +2 | Cooling coefficient |  |  |
| +3 | Cooling coefficient |  | Channel 1 |
| +4 | Cooling coefficient |  | Channel 2 |
| +5 | Cooling coefficient |  | Channel 3 |
| +6 | Cooling coefficient |  | Channel 4 |
| +7 | Cooling coefficient |  | Channel 5 |
| +8 | Cooling coefficient |  | Channel 6 |
| +9 | Cooling coefficient |  | Channel 7 |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0010 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |
| +2 | Channel 0 <br> Cooling coefficient (4 digits BCD) | 0000 to 0100 |
| +3 | Channel 1 <br> Cooling coefficient (4 digits BCD) | 0000 to 0100 |
| +4 | Channel 2 <br> Cooling coefficient (4 digits BCD) | 0000 to 0100 |
| +8 | Channel 6 <br> Cooling coefficient (4 digits BCD) | 0000 to 0100 |
| +9 | Channel 7 <br> Cooling coefficient (4 digits BCD) | 0000 to 0100 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Start Control (Sequence No. 174)

Starts temperature control for all channels in the specified Unit.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) |  |
|  | Unit No. |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Stop Operation or Control (Sequence No. 175)

Stops temperature control or manual operation for all channels of the specified Unit.
Send Data Word Allocation (2nd Operand of PMCR)

|  | First word of send +0 |  | Number of send data words |  |
| :--- | :--- | :--- | :--- | :---: |
|  | data | Unit No. |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Start Manual Operation (Sequence No. 176)

Starts manual operation based on the output values that were set for all channels of the specified Unit.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits Hex) | 00 to 0F |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

# Appendix E <br> E5 $\square \mathbf{J}$ Temperature Controller Protocol 

The E5 $\square J$ Temperature Controller Protocol performs various settings and controls in remote mode for the Temperature Controller connected to the Communications Board via RS-232C or RS-422A/485 cable.
Note Negative values cannot be written. All values must be set as unsigned BCD.

## Structure of the Protocol

The following table shows the structure of the E5 $\square \mathrm{J}$ Temperature Controller Protocol.

| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 200 | Select remote mode | Switches the Controller to remote mode. | Yes | No |
| 201 | Select local mode | Switches the Controller to local mode. | Yes | No |
| 202 | Select backup mode | Switches from set point write mode to backup mode. | Yes | No |
| 203 | Select RAM write mode | Switches from set point write mode to RAM write mode. | Yes | No |
| 204 | Save set point | Saves the set point. | Yes | No |
| 205 | Write parameters 1 | Writes the set point, alarm value 1, alarm value 2, and heater burnout alarm value. | Yes | No |
| 206 | Write parameters 2 | Writes the proportional band, integral time, and derivative time. | Yes | No |
| 207 | Write input shift value | Writes the input shift value. | Yes | No |
| 208 | Read parameters 1 | Reads the set point, alarm value 1, alarm value 2, and heater burnout alarm value. | Yes | Yes |
| 209 | Read parameters 2 | Reads the proportional band, integral time, and derivative time. | Yes | Yes |
| 210 | Read input shift value | Reads the input shift value and writes it in IOM. | Yes | Yes |
| 211 | Read output value | Reads the output value and stores it in IOM. | Yes | Yes |
| 212 | Read process value | Reads the process value and stores it in IOM. | Yes | Yes |
| 213 | Read set point limit | Reads the set point limits and stores them in IOM. | Yes | Yes |
| 214 | Read heater current | Reads the heater current and stores it in IOM. | Yes | Yes |
| 215 | Read initial status | Reads the initial status and stores it in IOM. | Yes | Yes |
| 216 | General-purpose write | Writes the specified parameter by setting a header code. | Yes | No |
| 217 | General-purpose read | Reads the specified parameter by setting a header code. | Yes | Yes |

## Note Ladder Interface Settings

YES: User settings are required for the 2nd or 3rd operands of PMCR.
NO: Send word allocation: Set the constant 0000 for the 2nd operand (S).
Receive word allocation: Set a dummy word (e.g., DM0000) address for the 3rd operand (D).

## Connections

The connections for using the E5 $\square J$ Temperature Controller Protocol are shown below.

## RS-232C Connections

## C200HX/HG/HE



RS-232C

| Signal name | Abbreviation | Signal direction | Pin No. |
| :--- | :--- | :--- | :--- |
| Signal ground or common <br> return line | SG | - | 25,27 |
| Send data | SD | Output | 26 |
| Receive data | RD | Input | 28 |



Note 1. The connection configuration is a one-to-one configuration and the maximum cable length is 15 m .
2. Use shielded twisted-pair cable (AWG28i or greater).

## RS-422A/485 Connections



- RS-422A

| Signal name | Abbreviation | Signal direction | Pin No. |
| :--- | :--- | :--- | :--- |
| Send data A | SDA | Output | 26 |
| Send data B | SDB | Output | 25 |
| Receive data A | RDA | Input | 28 |
| Receive data B | RDB | Input | 29 |
| Signal ground | SG | - | 27 |



| Signal name | Abbreviation | Signal direction | Pin No. |
| :--- | :--- | :--- | :--- |
| Terminal A | A | I/O | 26,28 |
| Terminal B | B | I/O | 25,29 |
| Signal ground | SG | - | 27 |



Note 1. The connection configuration is a one-to-one or a one-to-N configuration. Using a one-to-N configuration, up to 32 units can be connected including the Communications Board.
2. The maximum cable length is 500 m . Use shielded twisted-pair cable (AWG28i or greater).
3. Connect termination resistance to the devices only at both ends of the transmission path.
4. The total termination resistance at both ends must be at least $100 \Omega$ for RS-422A or $54 \Omega$ for RS-485.

## Select Remote Mode (Sequence No. 200)

Switches the Controller to remote mode.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Select Local Mode (Sequence No. 201)

Switches the Controller to local mode.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Select Backup Mode (Sequence No. 202)

Switches from the set point write mode to backup mode.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Select RAM Write Mode (Sequence No. 203)

Switches from set point write mode to RAM write mode.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Save Set Point (Sequence No. 204)

Saves the set point.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Parameters 1 (Sequence No. 205)

Writes the set point, alarm value 1, alarm value 2, and a heater burnout alarm value to multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)



Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Parameters 2 (Sequence No. 206)

Writes the proportional bands, integral times, and derivative times to multiple units.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units $\times 4+2$ |  |  |  |  |
| +1 | Number of units (4 digits BCD) | 0001 to 0031 |  |  |  |  |
| +2 | 1st unit Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |
| +3 | 1st unit <br> Proportional band (4 digits BCD) | 0000 to 9999 |  |  |  |  |
| +4 | 1st unit <br> Integral time (4 digits BCD) | 0000 to 9999 |  |  |  |  |
| +5 | 1st unit <br> Derivative time (4 digits BCD) | 0000 to 9999 |  |  |  |  |
| +6 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |
| $\bullet$ <br> $\bullet$ |  |  |  |  | 31th unit <br> Derivative time (4 digits BCD) | 0000 to 9999 |
| +125 <br> (max.) |  |  |  |  |  |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Input Shift Value (Sequence No. 207)

Writes the input shift value.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Input shift value (4 digits BCD) | 0000 to 9999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None

## Read Parameters 1 (Sequence No. 208)

Reads the set points, alarm values 1, alarm values 2, and heater burnout alarm values for multiple units and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)



## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data
storage words


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 4+1$ |
| +1 | 1st unit Set point (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, A$ is set and when it is,$- F$ is set. |
| +2 | 1st unit Alarm value 1 (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, A$ is set and when it is $-F$ is set. |
| +3 | 1st unit <br> Alarm value 2 (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, A$ is set and when it is,$- F$ is set. |
| +4 | 1st unit Heater burnout alarm value (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, A$ is set and when it is,$- F$ is set. |
| +5 | 2nd unit <br> Set point (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, \mathrm{~A}$ is set and when it is $-F$ is set. |
|  | $\begin{aligned} & \bullet \\ & \bullet \\ & \bullet \end{aligned}$ |  |
| $\begin{aligned} & +100 \\ & \text { (max.) } \end{aligned}$ | 25th unit <br> Heater burnout alarm value <br> (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, \mathrm{~A}$ is set and when it is $-F$ is set. |

## Read Parameters 2 (Sequence No. 209)

Reads the proportional bands, integral times, and derivative times for multiple units and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| Offset | Contents (data format) | Data |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units+ 2 |  |  |  |  |  |
| +1 | Number of units (4 digits BCD) | 0001 to 0031 |  |  |  |  |  |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |
|  | $\bullet \bullet$ |  |  |  |  |  |  |
| +32 <br> (max.) | 31th unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 3+1$ |
| +1 | 1st unit Proportional band (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, A$ is set and when it is,$- F$ is set. |
| +2 | 1st unit Integral time (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, \mathrm{~A}$ is set and when it is,$- F$ is set. |
| +3 | 1st unit Derivative time (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, \mathrm{~A}$ is set and when it is,$- F$ is set. |
| +4 | 2nd unit Proportional band (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, \mathrm{~A}$ is set and when it is $-F$ is set. |
|  |  |  |
| $\begin{aligned} & \hline+93 \\ & \text { (max.) } \end{aligned}$ | 31th unit Derivative time ( 4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, \mathrm{~A}$ is set and when it is,$- F$ is set. |

## Read Input Shift Value (Sequence No. 210)

Reads the input shift value and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |
| :---: | :---: |
|  | Input shift value |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Input shift value (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, A$ is set and when <br> it is,- F is set. |

## Read Output Value (Sequence No. 211)

Reads the output value and stores the results in the specified word.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |  |
| :--- | :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |  |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |
| :---: | :---: |
| +1 | Output value |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Output value <br> $(4$ digits BCD) | 0000 to 9999 <br> When the left digit is $-1, ~ A ~ i s ~ s e t ~ a n d ~ w h e n ~$ <br> it is,- F is set. |

## Read Process Value (Sequence No. 212)

Reads the process value and status data and stores the results in the specified word.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

| Number of send data words |  |  |
| :---: | :---: | :---: |
|  | Num |  |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |
| :---: | :---: |
| +1 | Process value |
| +2 | Status data |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0003 |
| +1 | Process value (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, \mathrm{~A}$ is set and when <br> it is,- F is set. |
| +2 | Status data (4 digits Hex) | 0000 to 9999 |

## Read Set Point Limit (Sequence No. 213)

Reads the set point limits and stores the results in the specified word.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |
| :---: | :---: |
| +1 | Set point lower limit |
| +2 | Set point upper limit |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0003 |
| +1 | Set point lower limit <br> $(4$ digits BCD) | 0000 to 9999 <br> When the left digit is $-1, ~ A ~ i s ~ s e t ~ a n d ~ w h e n ~$ <br> it is,- F is set. |
| +2 | Set point upper limit <br> (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, \mathrm{~A}$ is set and when <br> it is,- F is set. |

## Read Heater Current (Sequence No. 214)

Reads the heater current and stores the results in the specified word.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  |  | Number of send data words |  |
| :---: | :---: | :---: | :---: |
|  | (Undefined) | Unit No. |  |
|  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |
| :---: | :---: |
|  | Heater current |
|  | Status data |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0003 |
| +1 | Heater current <br> $(4$ digits BCD) | 0000 to 9999 <br> When the left digit is $-1, A$ is set and when <br> it is,$- F$ is set. |
| +2 | Status data (4 digits Hex) | 0000 to 0011 |

## Read Initial Status (Sequence No. 215)

Reads the initial status and stores the results in the specified word.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
|  | (Undefined) |  | Status |  |
|  | Alarm 1 type | Alarm 2 type | Input type |  |
|  | (Undefined) |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0003 |
| +1 | Status (2 digits Hex) | 00 to 99 |
| +2 | Alarm 1 type (1 digit Hex) <br> Alarm 2 type (1 digit Hex) <br> Input type (1 digit BCD) | 0 to 9 <br> 0 to 9 <br> 0 to 9 |

## General-purpose Write (Sequence No. 216)

Writes the parameter specified by setting a header code.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send +0 data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |
|  | Header code (ASC) |  |
|  | (Undefined) | Data code |
|  | Send data |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0005 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Header code (two ASCII characters) | Header codes that can be set <br> MB, WS, W\%, WW, WB, WN, WV |
| +3 | Data code (2 digits BCD) | 01 to 02 |
| +4 | Write data (4 digits BCD) | 0000 to 9999 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## General-purpose Read (Sequence No. 217)

Reads the parameter specified by setting a header

## Send Data Word Allocation (2nd Operand of PMCR)

First word of
send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
| +2 | Header code (ASC) |  |
|  | (Undefined) | Data code |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 | Header code (two ASCll characters) | Header codes that can be set <br> RS, R\%, RW, RB, RN, RV, RO |
| +3 | Data code (2 digits BCD) | 01 to 02 |

## Receive Data Word Allocation (3rd Operand of PMCR)

|  | Number of receive data words |
| :---: | :---: |
|  | Receive data |
|  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0002 |
| +1 | Read data (4 digits BCD) | 0000 to 9999 <br> When the left digit is $-1, A$ is set and when <br> it is,- F is set. |

Note The completion code is not included in the read data.

# Appendix F ES100 $\square$ Digital Controller Protocol 

The ES100 Digital Controller Protocol controls in remote mode and reads various settings from the Controller connected to the Communications Board via RS-232C or RS-422A/485 cable.
Note Negative values cannot be written. All values must be set as unsigned BCD.

## Structure of the Protocol

The structure of the ES100 $\square$ Digital Controller Protocol is shown below.

| Sequence No. | Transmission sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 250 | Read event data | Reads events 1 to 10 in the variable area. | Yes | Yes |
| 251 | Read time signals | Reads time signals 1 to 10 in the variable area. | Yes | Yes |
| 252 | Read error detection data | Reads error groups 1 to 15 in the variable area. | Yes | Yes |
| 253 | Read heater burnout data | Reads the heater burnout alarm. | Yes | Yes |
| 254 | Read PV data | Reads PV data in the variable area. | Yes | Yes |
| 255 | Read SP data | Reads SP data in the variable area. | Yes | Yes |
| 256 | Read MV | Reads the MV in the variable area. | Yes | Yes |
| 257 | Read control monitor data | Reads control monitor data (SP, PV, and MV) in the variable area. | Yes | Yes |
| 258 | Read adjustment parameters | Reads adjustment parameters in the parameter area. | Yes | Yes |
| 259 | Write adjustment parameters | Writes adjustment parameters in the parameter area. | Yes | No |
| 260 | Read PID control parameters 1 | Reads PID parameters No. 1 to 4 from the PID control parameters in the parameter area. | Yes | Yes |
| 261 | Read PID control parameters 2 | Reads PID parameters No. 5 to 8 from the PID control parameters in the parameter area. | Yes | Yes |
| 262 | Write PID control parameters 1 | Writes PID parameters No. 1 to 4 from PID control parameters in the parameter area. | Yes | No |
| 263 | Write PID control parameters 2 | Writes PID parameters No. 5 to 8 from PID control parameters in the parameter area. | Yes | No |
| 264 | Read local SP | Reads the local SP in the program parameter area. | Yes | Yes |
| 265 | Write local SP | Writes local SP in the program parameter area. | Yes | No |
| 266 | Read program parameters | Reads local SP, step time, PID No. wait code, and events 1 to 10 set values in the program parameter area. | Yes | Yes |
| 267 | Write program parameters | Writes the local SP, step time, PID No., wait code, and event 1 to 10 set values in the program parameter area. | Yes | No |
| 268 | Remote setting mode | Switches the setting mode to remote setting. | Yes | No |
| 269 | Local setting mode | Switches the setting mode to local setting. | Yes | No |
| 270 | External setting mode | Switches the setting mode to external setting. | Yes | No |
| 271 | Run command | Starts control. | Yes | No |
| 272 | Reset (stop) | Stops control. | Yes | No |


| Sequence No. | Transmission sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 273 | Auto mode | Switches the control mode to auto. | Yes | No |
| 274 | Manual mode | Switches the control mode to a manual. | Yes | No |
| 275 | Execute A.T. | Executes A.T. | Yes | No |
| 276 | Cancel A.T. | Cancels A.T. | Yes | No |
| 277 | Change pattern No. | Changes the pattern No. | Yes | No |
| 278 | Change bank No. | Changes the bank No. | Yes | No |
| 279 | Read controller status | Reads the controller status. | Yes | Yes |
| 280 | General-purpose command | Sends specified data and stores the received data in the specified words. | Yes | Yes |

## Note Ladder Interface Settings

YES: User settings are required for the 2nd and 3rd operands of PMCR.
NO: Send word allocation:
Set a dummy word address for the 3rd operand (D). Receive word allocation: Set the constant 0000 for the 2rd operand (S).

## Connections

Connections for using the ES100 Digital Controller Protocol are shown below.

## RS-232C Connections



## RS-422A/485 Connections



- RS-422A

Communications Board


- RS-485



## Switch Settings

There are two switches located on the board on the left of the Unit. Set SW1 to the interface: RS-422A or RS-485. Set SW2 to the center on all terminating Units and to the same setting as SW1 on all other Units.


## Read Event Data (Sequence No. 250)

Reads events 1 to 10 in the variable area.

## Send Data Word Allocation (2nd Operand of PMCR)



Receive Data Word Allocation (3rd Operand of PMCR)

|  | Number of receive data words |  |
| :---: | :---: | :---: |
| +1 | Event 1 | Event 2 |
| +2 | Event 3 | Event 4 |
| +3 | Event 5 | Event 6 |
| +4 | Event 7 | Event 8 |
| +5 | Event 9 | Event 10 |

1st unit

|  |  |  |
| :--- | :--- | :--- |
|  | Event 1 | Event 2 |
| +121 | Event 3 | Event 4 |
| +123 | Event 5 | Event 6 |
| +124 | Event 7 | Event 8 |
| +125 | Event 9 | Event 10 |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 5+1$ |
| +1 | 1st unit <br> Event data 1 (2 digits Hex) <br> Event data 2 (2 digits Hex) | $\begin{aligned} & 00 \text { to FF } \\ & 00 \text { to FF } \end{aligned}$ |
| +2 | 1st unit <br> Event data 3 (2 digits Hex) <br> Event data 4 (2 digits Hex) | 00 to FF <br> 00 to FF |
| +3 | 1st unit <br> Event data 5 (2 digits Hex) <br> Event data 6 (2 digits Hex) | $\begin{aligned} & 00 \text { to } \mathrm{FF} \\ & 00 \text { to } \mathrm{FF} \end{aligned}$ |
| +4 | 1st unit <br> Event data 7 (2 digits Hex) <br> Event data 8 (2 digits Hex) | $\begin{aligned} & 00 \text { to FF } \\ & 00 \text { to } \mathrm{FF} \end{aligned}$ |
| +5 | 1st unit <br> Event data 9 (2 digits Hex) <br> Event data 10 (2 digits Hex) | 00 to FF 00 to FF |
|  |  |  |
| $\begin{aligned} & +125 \\ & \text { (max.) } \end{aligned}$ | 25th unit <br> Event data 9 (2 digits Hex) <br> Event data 10 (2 digits Hex) | 00 to FF 00 to FF |

## Read Time Signal (Sequence No. 251)

Reads time signals from 1 to 10 in the variable area.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | Number of units + 2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0025 |
| +2 | 1st unit Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 2nd unit Unit No. (2 digits BCD) | 00 to 31 |
|  | $\stackrel{-}{\bullet}$ |  |
| $\begin{aligned} & +26 \\ & (\text { max. }) \end{aligned}$ | 25th unit Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4digits BCD) | Number of units $\times 5+1$ |
| +1 | 1st unit <br> Time signal 1 data ( 2 digits Hex ) <br> Time signal 2 data (2 digits Hex) | $\begin{aligned} & 00 \text { to } \mathrm{FF} \\ & 00 \text { to } \mathrm{FF} \end{aligned}$ |
| +2 | 1st unit <br> Time signal 3 data (2 digits Hex) Time signal 4 data (2 digits Hex) | 00 to FF 00 to FF |
| +3 | 1st unit <br> Time signal 5 data ( 2 digits Hex ) Time signal 6 data (2 digits Hex) | 00 to FF 00 to FF |
| +4 | 1st unit <br> Time signal 7 data ( 2 digits Hex ) Time signal 8 data (2 digits Hex) | 00 to FF 00 to FF |
| +5 | 1st unit <br> Time signal 9 data (2 digits Hex) <br> Time signal 10 data (2 digits Hex) | 00 to FF <br> 00 to FF |
|  |  |  |
| $\begin{aligned} & +125 \\ & (\text { max. }) \end{aligned}$ | 25th unit <br> Time signal 9 data (2 digits Hex) <br> Time signal 10 data (2 digits Hex ) | 00 to FF 00 to FF |

## Read Error Detection Data (Sequence No. 252)

Reads error groups from 0 to 15 in the variable area.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  | 1st unit |
| :---: | :---: | :---: | :---: |
| +1 | Number of units |  |  |
| +2 | (Undefined) | Unit No. |  |
| +3 | (Undefined) | Unit No. | 2nd unit |
|  |  |  |  |
| +17 | (Undefined) | Unit No. | 16th unit (max.) |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | Number of units + 2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0008 |
| +2 | 1st unit Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 2nd unit Unit No. (2 digits BCD) | 00 to 31 |
|  | $\stackrel{-}{\bullet}$ |  |
| $\begin{aligned} & \hline+17 \\ & \text { (max.) } \end{aligned}$ | 16th unit Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 8+1$ |
| +1 | 1st unit <br> Error group 0 data (2 digits Hex) <br> Error group 1 data (2 digits Hex) | $\begin{aligned} & 00 \text { to } \mathrm{FF} \\ & 00 \text { to } \mathrm{FF} \end{aligned}$ |
| +2 | 1st unit <br> Error group 2 data (2 digits Hex) <br> Error group 3 data (2 digits Hex) | $\begin{aligned} & 00 \text { to } \mathrm{FF} \\ & 00 \text { to } \mathrm{FF} \end{aligned}$ |
|  |  |  |
| +7 | 1st unit <br> Error group 12 data (2 digits Hex) <br> Error group 13 data (2 digits Hex) | $\begin{aligned} & 00 \text { to } \mathrm{FF} \\ & 00 \text { to } \mathrm{FF} \end{aligned}$ |
| +8 | 1st unit <br> Error group 14 data (2 digits Hex) <br> Error group 15 data (2 digits Hex) | $\begin{aligned} & 00 \text { to FF } \\ & 00 \text { to } \mathrm{FF} \end{aligned}$ |
| +9 | 2nd unit <br> Error group 0 data (2 digits Hex) <br> Error group 1 data (2 digits Hex) | $\begin{aligned} & 00 \text { to } \mathrm{FF} \\ & 00 \text { to } \mathrm{FF} \end{aligned}$ |
|  |  |  |
| $\begin{aligned} & +128 \\ & (\text { max. }) \end{aligned}$ | 16th unit <br> Error group 14 data (2 digits Hex) <br> Error group 15 data (2 digits Hex) | 00 to FF <br> 00 to FF |

## Read Heater Burnout Data (Sequence No. 253)

Reads the heater burnout alarm in the variable area.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |  |  |  |  |  |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |  |  |  |  |  |
| +2 | 1st unit (2 digits BCD) <br> Unit No. (2 | 00 to 31 |  |  |  |  |  |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |
|  | $\bullet$ |  |  |  |  |  |  |
| +33 <br> (max.) | 32nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |  | 1st unit |
| :---: | :---: | :---: | :---: |
| +1 | (Undefined) | Heater burnout alarm |  |
| +2 | (Undefined) | Heater burnout alarm | 2nd unit |
| +3 | (Undefined) | Heater burnout alarm | 3rd unit |
| +4 | (Undefined) | Heater burnout alarm | 4th unit |
|  |  |  |  |
| +32 | (Undefined) | Heater burnout alarm | 32nd unit (max.) |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | Number of units +1 |
| +1 | 1st unit <br> Heater burnout alarm (2 digits Hex) | 00 to FF |
| +2 | 2nd unit <br> Heater burnout alarm (2 digits Hex) | 00 to FF |
| +3 | 3rd unit <br> Heater burnout alarm (2 digits Hex) | 00 to FF |
| +4 | 4th unit <br> Heater burnout alarm (2 digits Hex) | 00 to FF |
|  | $\bullet$ |  |
| +32 <br> (max.) | 32nd unit <br> Heater burnout alarm (2 digits Hex) | 00 to FF |

## Read PV Data (Sequence No. 254)

Reads the PV data for the variable type "analog data" in the variable area.

## Send Data Word Allocation (2nd Operand of PMCR)



## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4digits BCD) | Number of units $\times 2+1$ |
| +1 | 1st unit PV data (rightmost 4 digits) (4 digits BCD) | 00000000 to 09999000 <br> F indicates a negative number. |
| +2 | 1st unit <br> PV data (leftmost 4 digits) <br> (4 digits BCD) |  |
| +3 | 2nd unit <br> PV data (rightmost 4 digits) <br> (4 digits BCD) | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +4 | 2nd unit <br> PV data (leftmost 4 digits) <br> (4 digits BCD) |  |
|  |  |  |
| +63 | 32nd unit <br> PV data (rightmost 4 digits) <br> (4 digits BCD) | $\begin{aligned} & 00000000 \text { to } 09999000 \\ & \text { F indicates a negative number. } \end{aligned}$ |
| +64 | 32nd unit <br> PV data (leftmost 4 digits) <br> (4 digits BCD) |  |

## Read SP Data (Sequence No. 255)

Reads the SP data for the variable type "analog data" in the variable area.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| Offset | Contents (data format) | Data |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |  |  |  |  |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |  |  |  |  |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |
|  | $\bullet$ |  |  |  |  |  |
| +33 <br> (max.) | 32nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 2+1$ |
| +1 | 1st unit SP data (rightmost 4 digits) (4 digits BCD) | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +2 | 1st unit SP data (leftmost 4 digits) (4 digits BCD) |  |
| +3 | $\begin{aligned} & \text { 2nd unit } \\ & \text { SP data (rightmost } 4 \text { digits) } \\ & \text { (4 digits BCD) } \end{aligned}$ | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +4 | 2nd unit SP data (leftmost 4 digits) (4 digits BCD) |  |
|  |  |  |
| +63 | 32nd unit SP data (rightmost 4 digits) (4 digits BCD) (3nd | $\begin{aligned} & 00000000 \text { to } 09999000 \\ & \text { F indicates a negative number. } \end{aligned}$ |
| +64 | 32nd unit SP data (leftmost 4 digits) (4 digits BCD) |  |

## Read MV Data (Sequence No. 256)

Reads the MV for the variable type "analog data" in the variable area.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  | 1st unit |
| :---: | :---: | :---: | :---: |
| +1 | Number of units |  |  |
| +2 | (Undefined) | Unit No. |  |
| +3 | (Undefined) | Unit No. | 2nd unit |
|  |  |  |  |
| +33 | (Undefined) | Unit No. | 32nd unit (max.) |


| Offset | Contents (data format) | Data |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |  |  |  |  |  |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |  |  |  |  |  |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |
|  | $\bullet \bullet$ |  |  |  |  |  |  |
| +33 <br> (max.) | 32nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 2+1$ |
| +1 | 1st unit MV (rightmost 4 digits) (4 digits BCD) | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +2 | 1st unit MV (leftmost 4 digits) (4 digits BCD) |  |
| +3 | 2nd unit <br> MV (rightmost 4 digits) (4 digits BCD) | $\begin{aligned} & 00000000 \text { to } 09999000 \\ & \text { F indicates a negative number. } \end{aligned}$ |
| +4 | 2nd unit <br> MV (leftmost 4 digits) (4 digits BCD) |  |
|  |  |  |
| +63 | 32nd unit <br> MV (rightmost 4 digits) (4 digits BCD) | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +64 | 32nd unit <br> MV (leftmost 4 digits) (4 digits BCD) |  |

## Read Control Monitor Data (Sequence No. 257)

Reads the control monitor data (SP/PV/MV) in the variable area.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0021 |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |
|  | $\bullet$ <br> $\bullet$ |  |
| +22 <br> (max.) | 21st unit <br> Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | 1st unit <br> Number of receive data words (4 digits BCD) | Number of units $\times 6+1$ |
| +1 | 1st unit SP data (rightmost 4 digits) (4 digits BCD) | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +2 | 1st unit <br> SP data (leftmost 4 digits) <br> (4 digits BCD) |  |
| +3 | 1st unit <br> PV data (rightmost 4 digits) <br> (4 digits BCD) | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +4 | 1st unit PV data (leftmost 4 digits) (4 digits BCD) |  |
| +5 | ```1st unit MV (rightmost 4 digits) (4 digits BCD)``` | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +6 | 1st unit MV (leftmost 4 digits) ( 4 digits BCD) |  |
|  | $\stackrel{-}{\bullet}$ |  |
| +125 | 21st unit <br> MV (rightmost 4 digits) (4 digits BCD) | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +126 | 21st unit MV (leftmost 4 digits) (4 digits BCD) |  |

## Read Adjustment Parameters (Sequence No. 258)

Reads the adjustment parameters in the parameter area and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 | Number of send data words |  |
| :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |


| Offset | Contents (data format) | Data |  |
| :--- | :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |  |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |  |
| :---: | :---: | :---: |
| +1 | - Fixed SP | (rightmost 4 digits) |
| +2 | - Fixed Sp | (leftmost 4 digits) |
| +3 | - Control output 1 pulse cycle | (rightmost 4 digits) |
| +4 |  | (leftmost 4 digits) |
| +5 | Control output 2 pulse cycle | (rightmost 4 digits) |
| +6 |  | (leftmost 4 digits) |
| +7 | Fuzzy strength | (rightmost 4 digits) |
| +8 |  | (leftmost 4 digits) |
| +9 | Cooling coefficient | (rightmost 4 digits) |
| +10 |  | (leftmost 4 digits) |
| +11 | Heater burnout alarm setting | (rightmost 4 digits) |
| +12 |  | (leftmost 4 digits) |
| +13 | Position-proportional dead band | (rightmost 4 digits) |
| +14 |  | (leftmost 4 digits) |
| +15 | Switching output hysteresis | (rightmost 4 digits) |
| +16 |  | (leftmost 4 digits) |
| +17 | ON/OFF count alarm setting | (rightmost 4 digits) |
| +18 |  | (leftmost 4 digits) |
| +19 | - ON/OFF control hysteresis | (rightmost 4 digits) |
| +20 |  | (leftmost 4 digits) |
| +21 | - Manual reset | (rightmost 4 digits) |
| +22 |  | (leftmost 4 digits) |
| +23 | SP setting lower limit | (rightmost 4 digits) |
| +24 |  | (leftmost 4 digits) |
| +25 | - SP setting upper limit | (rightmost 4 digits) |
| +26 |  | (leftmost 4 digits) |
| +27 | SP rise rate limit | (rightmost 4 digits) |
| +28 |  | (leftmost 4 digits) |
| +29 | - SP fall rate limit | (rightmost 4 digits) |
| +30 |  | (leftmost 4 digits) |
| +31 | MV rate-of-change limit | (rightmost 4 digits) |
| +32 |  | (leftmost 4 digits) |
| +33 | - Secondary loop fixed SP | (rightmost 4 digits) |
| +34 |  | (leftmost 4 digits) |
| +35 | - Secondary loop P | (rightmost 4 digits) |
| +36 |  | (leftmost 4 digits) |
| +37 | Secondary loop I | (rightmost 4 digits) |
| +38 |  | (leftmost 4 digits) |
| +39 | - Secondary loop D | (rightmost 4 digits) |
| +40 |  | (leftmost 4 digits) |
| +41 | - Secondary loop manual reset | (rightmost 4 digits) |
| +42 |  | (leftmost 4 digits) |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0043 |
| +1 to 2 | Fixed SP (8 digits BCD) | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +3 to 4 | Control output 1 pulse cycle (8 digits BCD) |  |
| +5 to 6 | Control output 2 pulse cycle (8 digits BCD) |  |
| +7 to 8 | Fuzzy strength (8 digits BCD) |  |
| +9 to 10 | Cooling coefficient (8 digits BCD) |  |
| +11 to 12 | Heater burnout alarm setting (8 digits BCD) |  |
| +13 to 14 | Position-proportional dead band (8 digits BCD) |  |
| +15 to 16 | Switching output hysteresis (8 digits BCD) |  |
| +17 to 18 | ON/OFF count alarm setting (8 digits BCD) |  |
| +19 to 20 | ON/OFF control hysteresis (8 digits BCD) |  |
| +21 to 22 | Manual reset (8 digits BCD) |  |
| +23 to 24 | SP setting lower limit (8 digits BCD) |  |
| +25 to 26 | SP setting upper limit (8 digits BCD) |  |
| +27 to 28 | SP rise rate limit (8 digits BCD) |  |
| +29 to 30 | SP fall rate limit (8 digits BCD) |  |
| +31 to 32 | MV rate-of-change limit (8 digits BCD) |  |
| +33 to 34 | Secondary loop fixed SP (8 digits BCD) |  |
| +35 to 36 | Secondary loop P (8 digits BCD) |  |
| +37 to 38 | Secondary loop I (8 digits BCD) |  |
| +39 to 40 | Secondary loop D (8 digits BCD) |  |
| +41 to 42 | Secondary loop manual reset (8 digits BCD) |  |

## Write Adjustment Parameters (Sequence No. 259)

Writes the adjust parameters in the parameter area.
Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |
| +2 | Fixed SP | (rightmost 4 digits) |
| +3 |  | (leftmost 4 digits) |
| +4 | Control output 1 pulse cycle | (rightmost 4 digits) |
| +5 |  | (leftmost 4 digits) |
| +6 | Control output 2 pulse cycle | (rightmost 4 digits) |
| +7 |  | (leftmost 4 digits) |
| +8 | Fuzzy strength | (rightmost 4 digits) |
| +9 |  | (leftmost 4 digits) |
| +10 | Cooling coefficient | (rightmost 4 digits) |
| +11 |  | (leftmost 4 digits) |
| +12 | Heater burnout alarm setting | (rightmost 4 digits) |
| +13 |  | (leftmost 4 digits) |
| +14 | Position-proportional dead band | (rightmost 4 digits) |
| +15 |  | (leftmost 4 digits) |
| +16 | Switching output hysteresis | (rightmost 4 digits) |
| +17 |  | (leftmost 4 digits) |
| +18 | ON/OFF count alarm setting | (rightmost 4 digits) |
| +19 |  | (leftmost 4 digits) |
| +20 | ON/OFF control hysteresis | (rightmost 4 digits) |
| +21 |  | (leftmost 4 digits) |
| +22 | Manual reset | (rightmost 4 digits) |
| +23 |  | (leftmost 4 digits) |
| +24 | SP setting lower limit | (rightmost 4 digits) |
| +25 |  | (leftmost 4 digits) |
| +26 | SP setting upper limit | (rightmost 4 digits) |
| +27 |  | (leftmost 4 digits) |
| +28 | SP rise rate limit | (rightmost 4 digits) |
| +29 |  | (leftmost 4 digits) |
| +30 | SP fall rate limit | (rightmost 4 digits) |
| +31 |  | (leftmost 4 digits) |
| +32 | MV change rate limit | (rightmost 4 digits) |
| +33 |  | (leftmost 4 digits) |
| +34 | Secondary loop fixed SP | (rightmost 4 digits) |
| +35 |  | (leftmost 4 digits) |
| +36 | Secondary loop P | (rightmost 4 digits) |
| +37 |  | (leftmost 4 digits) |
| +38 | Secondary loop I | (rightmost 4 digits) |
| +39 |  | (leftmost 4 digits) |
| +40 | Secondary loop D | (rightmost 4 digits) |
| +41 |  | (leftmost 4 digits) |
| +42 | Secondary loop manual reset | (rightmost 4 digits) |
| +43 |  | (leftmost 4 digits) |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0044 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 to 3 | Fixed SP (8 digits BCD) | 00000000 to 09999000 |
| +4 to 5 | Control output 1 pulse cycle (8 digits BCD) |  |
| +6 to 7 | Control output 2 pulse cycle (8 digits BCD) |  |
| +8 to 9 | Fuzzy strength (8 digits BCD) |  |
| +10 to 11 | Cooling coefficient (8 digits BCD) |  |
| +12 to 13 | Heater burnout alarm setting (8 digits BCD) |  |
| +14 to 15 | Position-proportional dead band (8 digits BCD) |  |
| +16 to 17 | Switching output hysteresis (8 digits BCD) |  |
| +18 to 19 | ON/OFF count alarm setting (8 digits BCD) value |  |
| +20 to 21 | ON/OFF control hysteresis (8 digits BCD) |  |
| +22 to 23 | Manual reset (8 digits BCD) |  |
| +24 to 25 | SP setting lower limit (8 digits BCD) |  |
| +26 to 27 | SP setting upper limit (8 digits BCD) |  |
| +28 to 29 | SP rise rate limit (8 digits BCD) |  |
| +30 to 31 | SP fall rate limit (8 digits BCD) |  |
| +32 to 33 | MV rate-of-change limit (8 digits BCD) |  |
| +34 to 35 | Secondary loop fixed SP (8 digits BCD) |  |
| +36 to 37 | Secondary loop P (8 digits BCD) |  |
| +38 to 39 | Secondary loop I (8 digits BCD) |  |
| +40 to 41 | Secondary loop D (8 digits BCD) |  |
| +42 to 43 | Secondary loop manual reset (8 digits BCD) |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Read PID Control Parameters 1 (Sequence No. 260)

Reads PID parameters No. 1 to 4 from PID control parameters in the parameter area and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)

| Receive data storage words | +0 | Number of receive data words | (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) |
| :---: | :---: | :---: | :---: |
|  | +1 | PID No. 1 P |  |
|  | +2 | PID No. 1 P |  |
|  | +3 | PID No. 11 |  |
|  | +4 | PID No. 11 |  |
|  | +5 | PID No. 1 D |  |
|  | +6 | PID No. 1 D |  |
|  | +7 | PID No. 1 MV lower limit |  |
|  | +8 | PID No. 1 MV lower limit |  |
|  | +9 | PID No. 1 MV upper limit |  |
|  | +10 | PID No. 1 MV upper limit |  |
|  | +11 | PID No. 1 PV bias value |  |
|  | +12 | PID No. 1 PV bias value |  |
|  | +13 | PID No. 1 Automatic selection range upper limit |  |
|  | +14 | PID No. 1 Automatic selection range upper limit |  |
|  |  | ! |  |
|  | +51 | PID No. 4 MV upper limit |  |
|  | +52 | PID No. 4 MV upper limit |  |
|  | +53 | PID No. 4 PV bias value |  |
|  | +54 | PID No. 4 PV bias value |  |
|  | +55 | PID No. 4 Automatic selection range upper limit |  |
|  | +56 | PID No. 4 Automatic selection range upper limit |  |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0057 |
| +1 to 2 | PID No. 1 P (8 digits BCD) | 00000000 to 09999000 |
| +3 to 4 | PID No. 1 I (8 digits BCD) |  |
| +5 to 6 | PID No. 1 D (8 digits BCD) |  |
| +7 to 8 | PID No. 1 MV lower limit ( 8 digits BCD) |  |
| +9 to 10 | PID No. 1 MV upper limit (8 digits BCD) |  |
| +11 to 12 | PID No. 1 PV bias value ( 8 digits BCD) |  |
| +13 to 14 | PID No. 1 Automatic selection range upper limit ( 8 digits BCD) |  |
|  |  |  |
| +43 to 44 | PID No. 4 P (8 digits BCD) |  |
| +45 to 46 | PID No. 4 I (8 digits BCD) |  |
| +47 to 48 | PID No. 4 D (8 digits BCD) |  |
| +49 to 50 | PID No. 4 MV lower limit ( 8 digits BCD) |  |
| +51 to 52 | PID No. 4 MV upper limit ( 8 digits BCD) |  |
| +53 to 54 | PID No. 4 PV bias value (8 digits BCD) |  |
| +55 to 56 | PID No. 4 Automatic selection range upper limit ( 8 digits BCD) |  |

## Read PID Control Parameters 2 (Sequence No. 261)

Reads PID parameters No. 5 to 8 from the PID control parameters in the parameter area and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)

| Receive data storage words | +0 | Number of receive data words | (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) <br> (rightmost 4 digits) <br> (leftmost 4 digits) |
| :---: | :---: | :---: | :---: |
|  | +1 | PID No. 5 P |  |
|  | +2 | PID No. 5 P |  |
|  | +3 | PID No. 51 |  |
|  | +4 | PID No. 51 |  |
|  | +5 | PID No. 5 D |  |
|  | +6 | PID No. 5 D |  |
|  | +7 | PID No. 5 MV lower limit |  |
|  | +8 | PID No. 5 MV lower limit |  |
|  | +9 | PID No. 5 MV upper limit |  |
|  | +10 | PID No. 5 MV upper limit |  |
|  | +11 | PID No. 5 PV bias value |  |
|  | +12 | PID No. 5 PV bias value |  |
|  | +13 | PID No. 5 Automatic selection range upper limit |  |
|  | +14 | PID No. 5 Automatic selection range upper limit |  |
|  |  |  |  |
|  | +51 | PID No. 8 MV upper limit |  |
|  | +52 | PID No. 8 MV upper limit |  |
|  | +53 | PID No. 8 PV bias value |  |
|  | +54 | PID No. 8 PV bias value |  |
|  | +55 | PID No. 8 Automatic selection range upper limit |  |
|  | +56 | PID No. 8 Automatic selection range upper limit |  |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0057 |
| +1 to 2 | PID No. 5 P (8 digits BCD) | 00000000 to 09999000 |
| +3 to 4 | PID No. 5 I (8 digits BCD) |  |
| +5 to 6 | PID No. 5 D (8 digits BCD) |  |
| +7 to 8 | PID No. 5 MV lower limit (8 digits BCD) |  |
| +9 to 10 | PID No. 5 MV upper limit (8 digits BCD) |  |
| +11 to 12 | PID No. 5 PV bias value (8 digits BCD) |  |
| +13 to 14 | PID No. 5 Automatic selection range upper limit (8 digits BCD) |  |
|  |  |  |
| +43 to 44 | PID No. 8 P (8 digits BCD) |  |
| +45 to 46 | PID No. 81 (8 digits BCD) |  |
| +47 to 48 | PID No. 8 D (8 digits BCD) |  |
| +49 to 50 | PID No. 8 MV lower limit (8 digits BCD) |  |
| +51 to 52 | PID No. 8 MV upper limit ( 8 digits BCD) |  |
| +53 to 54 | PID No. 8 PV bias value ( 8 digits BCD) |  |
| +55 to 56 | PID No. 8 Automatic selection range upper limit (8 digits BCD) |  |

## Write PID Control Parameters 1 (Sequence No. 262)

Writes PID parameters No. 1 to 4 to the PID control parameters in the parameter area.
Send Data Word Allocation (2nd Operand of PMCR)
First word of
send data

| +0 | Number of send data words |  | (rightmost 4 digits) |
| :---: | :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |  |
| +2 | PID No. 1 P |  |  |
| +3 | PID No. 1 P |  | (leftmost 4 digits) |
| +4 | PID No. 11 |  | (rightmost 4 digits) |
| +5 | PID No. 11 |  | (leftmost 4 digits) |
| +6 | PID No. 1 D |  | (rightmost 4 digits) |
| +7 | PID No. 1 D |  | (leftmost 4 digits) |
| +8 | PID No. 1 MV lower limit |  | (rightmost 4 digits) |
| +9 | PID No. 1 MV lower limit |  | (leftmost 4 digits) |
| +10 | PID No. 1 MV upper limit |  | (rightmost 4 digits) |
| +11 | PID No. 1 MV upper limit |  | (leftmost 4 digits) |
| +12 | PID No. 1 PV bias value |  | (rightmost 4 digits) |
| +13 | PID No. 1 PV bias value |  | (leftmost 4 digits) |
| +14 | PID No. 1 Automatic selection range upper limit |  | (rightmost 4 digits) |
| +15 | PID No. 1 Automatic selection range upper limit |  | (leftmost 4 digits) |
|  |  |  |  |
| +52 | PID No. 4 MV upper limit |  | (rightmost 4 digits) |
| +53 | PID No. 4 MV upper limit |  | (leftmost 4 digits) |
| +54 | PID No. 4 PV bias value |  | (rightmost 4 digits) |
| +55 | PID No. 4 PV bias value |  | (leftmost 4 digits) |
| +56 | PID No. 4 Automatic selection range upper limit |  | (rightmost 4 digits) |
| +57 | PID No. 4 Automatic selection range upper limit |  | (leftmost 4 digits) |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0058 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 to 3 | PID No. 1 P (8 digits BCD) | 00000000 to 09999000 |
| +4 to 5 | PID No. 1 I (8 digits BCD) |  |
| +6 to 7 | PID No. 1 D (8 digits BCD) |  |
| +8 to 9 | PID No. 1 MV lower limit (8 digits BCD) |  |
| +10 to 11 | PID No. 1 MV upper limit (8 digits BCD) |  |
| +12 to 13 | PID No. 1 PV bias value (8 digits BCD) |  |
| +14 to 15 | PID No. 1 Automatic selection range upper limit <br> (8 digits BCD) |  |
|  |  |  |
| +44 to 45 | PID No. 4 P (8 digits BCD) |  |
| +46 to 47 | PID No. 41 (8 digits BCD) |  |
| +48 to 49 | PID No. 4 D (8 digits BCD) |  |
| +50 to 51 | PID No. 4 MV lower limit (8 digits BCD) |  |
| +52 to 53 | PID No. 4 MV upper limit (8 digits BCD) |  |
| +54 to 55 | PID No. 4 PV bias value (8 digits BCD) |  |
| +56 to 57 | PID No. 4 Automatic selection range upper limit (8 digits BCD) |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write PID Control Parameters 2 (Sequence No. 263)

Writes the PID parameters No. 5 to 8 to the PID control parameters in the parameter area.
Send Data Word Allocation (2nd Operand of PMCR)

| First word of send data | $\begin{aligned} & +0 \\ & +1 \end{aligned}$ | Number of send data words |  | (rightmost 4 digits) (leftmost 4 digits) |
| :---: | :---: | :---: | :---: | :---: |
|  |  | (Undefined) | Unit No. |  |
|  | +2 | PID No. 5 P |  |  |
|  | +3 | PID No. 5 P |  |  |
|  | +4 | PID No. 51 |  | (rightmost 4 digits) |
|  | +5 | PID No. 51 |  | (leftmost 4 digits) |
|  | +6 | PID No. 5 D |  | (rightmost 4 digits) |
|  | +7 | PID No. 5 D |  | (leftmost 4 digits) |
|  | +8 | PID No. 5 MV lower limit |  | (rightmost 4 digits) |
|  | +9 | PID No. 5 MV lower limit |  | (leftmost 4 digits) |
|  | +10 | PID No. 5 MV upper limit |  | (rightmost 4 digits) |
|  | +11 | PID No. 5 MV upper limit |  | (leftmost 4 digits) |
|  | +12 | PID No. 5 PV bias value |  | (rightmost 4 digits) |
|  | +13 | PID No. 5 PV bias value |  | (leftmost 4 digits) |
|  | +14 | PID No. 5 Automatic selection range upper limit |  | (rightmost 4 digits) |
|  | +15 | PID No. 5 Automatic selection range upper limit |  | (leftmost 4 digits) |
|  |  |  |  | (rightmost 4 digits) |
|  | +52 | PID No. 8 MV upper limit |  |  |
|  | +53 | PID No. 8 MV upper limit |  | (leftmost 4 digits) |
|  | +54 | PID No. 8 PV bias value |  | (rightmost 4 digits) |
|  | +55 | PID No. 8 PV bias value |  | (leftmost 4 digits) |
|  | +56 | PID No. 8 Automatic selection range upper limit |  | (rightmost 4 digits) |
|  | +57 | PID No. 8 Automatic selection range upper limit |  | (leftmost 4 digits) |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0058 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 31 |
| +2 to 3 | PID No. 5 P (8 digits BCD) | 00000000 to 09999000 |
| +4 to 5 | PID No. 5 I (8 digits BCD) |  |
| +6 to 7 | PID No. 5 D (8 digits BCD) |  |
| +8 to 9 | PID No. 5 MV lower limit (8 digits BCD) |  |
| +10 to 11 | PID No. 5 MV upper limit (8 digits BCD) |  |
| +12 to 13 | PID No. 5 PV bias value (8 digits BCD) |  |
| +14 to 15 | PID No. 5 Automatic selection range upper limit (8 digits BCD) |  |
|  |  |  |
| +44 to 45 | PID No. 8 P (8 digits BCD) |  |
| +46 to 47 | PID No. 81 (8 digits BCD) |  |
| +48 to 49 | PID No. 8 D (8 digits BCD) |  |
| +50 to 51 | PID No. 8 MV lower limit ( 8 digits BCD) |  |
| +52 to 53 | PID No. 8 MV upper limit ( 8 digits BCD) |  |
| +54 to 55 | PID No. 8 PV bias value (8 digits BCD) |  |
| +56 to 57 | PID No. 8 Automatic selection range upper limit <br> (8 digits BCD) |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Read Local SP (Sequence No. 264)

Reads the local SP in the program parameter area.
Send Data Word Allocation (2nd Operand of PMCR)

| First word of send data | +0 <br> +1 <br> +2 <br> +3 <br> +4 $+5$ | Number of send data words <br> Number of units |  | 1st unit |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |
|  |  | (Undefined) | Unit No. |  |
|  |  | Pattern No. | Step No. |  |
|  |  | (Undefined) | Unit No. |  |
|  |  | Pattern No. | Step No. | 2nd unit |
|  |  |  |  |  |
|  | +64 | (Undefined) | Unit No. |  |
|  | +65 | Pattern No. | Step No. | 32nd unit |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | Number of units $\times 2+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |
| +2 | 1st unit Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit <br> Pattern No. (2 digits BCD) <br> Step No. (2 digits BCD) | 00 to 63 <br> 00 to 63 |
|  |  |  |
| +64 | 32nd unit Unit No. (2 digits BCD) | 00 to 31 |
| $\begin{aligned} & +65 \\ & \text { (max.) } \end{aligned}$ | 32nd unit <br> Pattern No. (2 digits BCD) <br> Step No. (2 digits BCD) | 00 to 63 <br> 00 to 63 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 2+1$ |
| +1 | 1st unit Local SP (rightmost 4 digits) (4 digits BCD) | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +2 | 1st unit <br> Local SP (leftmost 4 digits) <br> (4 digits BCD) |  |
| +3 | 2nd unit <br> Local SP (rightmost 4 digits) <br> (4 digits BCD) | 00000000 to 09999000 |
| +4 | 2nd unit <br> Local SP (leftmost 4 digits) <br> (4 digits BCD) |  |
|  | $\begin{aligned} & \bullet \\ & \bullet \\ & \bullet \end{aligned}$ |  |
| +63 | 32nd unit Local SP (rightmost 4 digits) (4 digits BCD) | 00000000 to 09999000 |
| +64 | 32nd unit <br> Local SP (leftmost 4 digits) <br> (4 digits BCD) |  |

## Write Local SP (Sequence No. 265)

Writes the local SP to the program parameter area.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units $\times 4+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0031 |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit <br> Pattern No. (2 digits BCD) <br> Step No. (2 digits BCD) | 00 to 63 <br> 00 to 63 |
| +4 | 1st unit (rightmost 4 digits) <br> Local SP <br> (4 digits BCD) | 00000000 to 09999000 |
| +5 | 1st unit <br> Local SP (leftmost 4 digits) <br> (4 digits BCD) | $\bullet$ |
| +122 | 31st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| +123 | 31st unit <br> Pattern No. (2 digits BCD) <br> Step No. (2 digits BCD) | 00 to 63 |
| +124 | 31st unit <br> Local SP (rightmost 4 digits) <br> (4 digits BCD) | 00000000 to 09999000 |
| +125 | 31st unit <br> Local SP (leftmost 4 digits) <br> (4 digits BCD) | • |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Read Program Parameters (Sequence No. 266)

Reads the local SP, step time, PID set No., wait code, and events from 1 to 10 set values in the program parameter area.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of
send data

| +0 | Number of send data words |  |  |
| :---: | :---: | :---: | :---: |
| +1 | Number of units |  |  |
| +2 | (Undefined) | Unit No. | 1st unit |
| +3 | Pattern No. | Step No. |  |
| +4 | (Undefined) | Unit No. | 2nd unit |
| +5 | Pattern No. | Step No. |  |
| +6 | (Undefined) | Unit No. | 3rd unit |
| +7 | Pattern No. | Step No. |  |
| +8 | (Undefined) | Unit No. | 4th unit |
| +9 | Pattern No. | Step No. |  |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | Number of units $\times 2+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0004 |
| +2 | 1st unit Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit <br> Pattern No. (2 digits BCD) <br> Step No. (2 digits BCD) | $\begin{aligned} & 00 \text { to } 63 \\ & 00 \text { to } 63 \end{aligned}$ |
|  |  |  |
| +8 | 4th unit Unit No. (2 digits BCD) | 00 to 31 |
| $\begin{aligned} & +9 \\ & (\text { max. }) \end{aligned}$ | 4th unit <br> Pattern No. (2 digits BCD) <br> Step No. (2 digits BCD) | $\begin{aligned} & 00 \text { to } 63 \\ & 00 \text { to } 63 \end{aligned}$ |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


1st unit

| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4digits BCD) | Number of units $\times 28+1$ |
| +1 to 2 | 1st unit Local SP (8 digits BCD) | 00000000 to 09999000 <br> $F$ indicates a negative number. |
| +3 to 4 | 1st unit Step time) (8 digits BCD) |  |
| +5 to 6 | 1st unit PID set No. (8 digits BCD) |  |
| +7 to 8 | 1st unit Wait code (8 digits BCD) |  |
| +9 to 10 | 1st unit Event 1 setting (8 digits BCD) |  |
| +11 to 12 | 1st unit Event 2 setting (8 digits BCD) |  |
|  | $\bullet$ |  |
| +27 to 28 | 1st unit Event 10 setting ( 8 digits BCD) |  |
| +29 to 30 | 1st unit Local SP (8 digits BCD) |  |
|  | $\bullet$ |  |
| +109 to 110 | 4th unit Event 9 setting (8 digits BCD) |  |
| $\begin{aligned} & +111 \text { to } 112 \\ & \text { (max.) } \end{aligned}$ | 4th unit Event 10 setting ( 8 digits BCD) |  |

## Write Program Parameters (Sequence No. 267)

Writes the local SP, step time, PID set No., wait code, and events from 1 to 10 settings in the program parameter area.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | Number of units $\times 30+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0004 |
| +2 | 1st unit Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit <br> Pattern No. (2 digits BCD) <br> Step No. (2 digits BCD) | $\begin{aligned} & 00 \text { to } 63 \\ & 00 \text { to } 63 \end{aligned}$ |
| +4 to 5 | 1st unit Local SP (8 digits BCD) | 00000000 to 09999000 |
| +6 to 7 | 1st unit Step time (8 digits BCD) |  |
| +8 to 9 | 1st unit PID set No. (8 digits BCD) |  |
| +10 to 11 | 1st unit Wait code (8 digits BCD) |  |
| +12 to 13 | 1st unit Event 1 setting (8 digits BCD) |  |
| +14 to 15 | 1st unit Event 2 setting (8 digits BCD) |  |
|  | $\bullet$ |  |
| +30 to 31 | 1st unit Event 10 setting ( 8 digits BCD) |  |
| +32 to 33 | 2nd unit Local SP (8 digits BCD) |  |
|  | $\bullet$ |  |
| +111 to 112 | 4th unit Event 9 setting (8 digits BCD) |  |
| $\begin{aligned} & +120 \text { to } 121 \\ & \text { (max.) } \end{aligned}$ | 4th unit Event 10 setting ( 8 digits BCD) |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Remote Setting Mode (Sequence No. 268)

Switches the setting mode to the remote setting mode.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  | 1st unit |
| :---: | :---: | :---: | :---: |
| +1 | Number of units |  |  |
| +2 | (Undefined) | Unit No. |  |
| +3 | (Undefined) | Unit No. | 2nd unit |
|  |  |  |  |
| +33 | (Undefined) | Unit No. | 32nd unit (max.) |


| Offset | Contents (data format) | Data |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |  |  |  |  |  |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |  |  |  |  |  |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |
|  | $\bullet \bullet$ |  |  |  |  |  |  |
| +33 <br> (max.) | 32nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Local Setting Mode (Sequence No. 269)

Switches the setting mode to the local setting mode.
Send Data Word Allocation (2nd Operand of PMCR)
First word of
send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |
|  | $\bullet$ <br> $\bullet$ |  |
| +33 | 32nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## External Setting Mode (Sequence No. 270)

Switches the setting mode to the external setting mode.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

| +0 | Number of send data words |  | 1st unit |
| :---: | :---: | :---: | :---: |
| +1 | Number of units |  |  |
| +2 | (Undefined) | Unit No. |  |
| +3 | (Undefined) | Unit No. | 2nd unit |
|  |  |  |  |
| +33 | (Undefined) | Unit No. | 32nd unit (max.) |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |
|  | • |  |
| +33 <br> (max.) | 32nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Run Command (Sequence No. 271)

Starts control.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units $\times 2+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit <br> Pattern No./Bank No. <br> (4 digits BCD) | 0000 to 0063 |
| +24 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| $\bullet$ | $\bullet$ | 00 to 31 |
| +64 | 32nd unit <br> Unit No. (2 digits BCD) | 0000 to 0063 |
| +65 | 32nd unit <br> Pattern No./Bank No. <br> (4 digits BCD) |  |
| (max.) |  |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Reset (Stop) (Sequence No. 272)

Stops control.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of
send data



| Offset | Contents (data format) | Data |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |  |  |  |  |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |  |  |  |  |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |
|  | $\bullet$ |  |  |  |  |  |
| +33 <br> (max.) | 32nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Auto Mode (Sequence No. 273)

Switches the control mode to the auto mode.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |
|  | $\bullet \bullet$ |  |
| +33 <br> (max.) | 32nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Manual Mode (Sequence No. 274)

Switches the control mode to the manual mode.

## Send Data Word Allocation (2nd Operand of PMCR)



Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Execute A.T. (Sequence No. 275)

## Executes A.T.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units $\times 2+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit <br> PID set No. (4 digits BCD) | 0000 to 0008 |
| +4 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| $\bullet$ | $\bullet$ | 00 to 31 |
| +64 | 32nd unit <br> Unit No. (2 digits BCD) | 32nd unit <br> PID set No. (4 digits BCD) |
| +65 |  |  |
| (max.) | 0000 to 0008 |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Cancel A.T. (Sequence No. 276)

Cancels A.T.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of
send data


| Offset | Contents (data format) | Data |  |  |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |  |  |  |  |  |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |  |  |  |  |  |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |
| +3 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |
|  | $\bullet \bullet$ |  |  |  |  |  |  |
| +33 <br> (max.) | 32nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |  |  |  |  |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Change Pattern No. (Sequence No. 277)

Changes the pattern number.

## Send Data Word Allocation (2nd Operand of PMCR)



## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Change Bank No. (Sequence No. 278)

Changes the bank number.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of
send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units $\times 2+2$ |
| +1 | Number of units (4 digits BCD) | 0001 to 0032 |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| +3 | 1st unit <br> Bank No. (4 digits BCD) | 0000 to 0007 |
| +4 | 2nd unit <br> Unit No. (2 digits BCD) | 00 to 31 |
| $\bullet$ | 0 |  |
| +64 | 32nd unit <br> Unit No. (2 digits BCD) | 32nd unit <br> Bank No. (4 digits BCD) |
| +65 <br> (max. | 0000 to 0007 |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Read Controller Status (Sequence No. 279)

Reads the Controller status.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | Number of units + 2 |
| +1 | Number of units (4 digits BCD) | 0001 to 0025 |
| +2 | 1st unit <br> Unit No. (2 digits BCD) | 00 to 31 |
|  | $\bullet$ <br> $\bullet$ <br> $\bullet$ |  |
| +26 <br> (max.) | 25th unit <br> Unit No. (2 digits BCD) | 00 to 31 |

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | Number of units $\times 5+1$ |
| +1 | 1st unit Operation status (2 digits BCD) <br> Hold (2 digits BCD) | 00: Reset <br> 01: Run <br> 00: Not hold <br> 01: Hold |
| +2 | 1st unit Auto/manual (2 digits BCD) <br> SP mode (2 digits BCD) | 00: Auto mode <br> 01: Manual mode <br> 00: Local SP mode <br> 01: Remote SP mode <br> 02: Fixed SP mode |
| +3 | 1st unit Setting mode (2 digits BCD) <br> Valid pattern No. (2 digits BCD) | 00: Local setting mode <br> 01: Remote setting mode <br> 02: External setting mode 00 to 63 |
| +4 | 1st unit <br> A.T. (2 digits BCD) <br> Valid PD set No. (2 digits Hex) | 00: Not A.T. <br> 01: A.T. <br> 01 to 08 |
| +5 | 1st unit <br> Wait (2 digits BCD) <br> Operation mode (2 digits BCD) | 00: Not waiting <br> 01: Waiting <br> 02: Wait alarm output <br> 00: Setting level 1 (without technical mode) <br> 01: Setting level 1 (with technical mode) <br> 02: Setting level 2 (without technical mode) <br> 03: Setting level 2 (with technical mode) |
|  |  |  |
| $\begin{aligned} & +125 \\ & \text { (max.) } \end{aligned}$ | 25th unit <br> Wait (2 digits BCD) <br> Operation mode (2 digits BCD) | 00: Not waiting <br> 01: Waiting <br> 02: Wait alarm output <br> 00: Setting level 1 (without technical mode) <br> 01: Setting level 1 (with technical mode) <br> 02: Setting level 2 (without technical mode) <br> 03: Setting level 2 (with technical mode) |

## General-purpose Command (Sequence No. 280)

Sends the specified data and stores the received data in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0001 to 0128 |
| +1 | Number of send data bytes | 0001 to 0251 <br> The number of send bytes not including @, the FCS, or the terminator. |
| +2 | Send data (ASCII 2 characters) | Refer to the manual for the ES100■. |
|  | - | Use ASCII (Up to 251 characters total.) |
| $\begin{aligned} & +127 \\ & (\text { max. }) \end{aligned}$ | Send data (ASCII 1 characters) |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

| Receive data storage words | Num <br> $R$ <br> $R$ <br> Rece <br> Rece | meceive dat receive da | data words | 51 characters) |
| :---: | :---: | :---: | :---: | :---: |
|  | Offset |  | ts (data format) | Data |
|  | +0 | Numb (4 digit | ceive data words | 0001 to 0127 |
|  | +1 | Receive (ASCII | cters) | Refer to the manual for the ES100■. <br> Returned as ASCII (Up to 251 characters |
|  |  |  | $\bullet \bullet$ | total.) |
|  | $\begin{aligned} & +126 \\ & \text { (max.) } \end{aligned}$ | Receive (ASCII | cters) |  |

Note 1. At transmission, a header code "@" is attached before the data and the FCS and a terminator "*"CR are attached following the send data.

2. At reception, data excluding the header code "@" at the beginning of the receive data and the FCS and terminator "*"CR at the end of the data is stored in the receive data storage words.

| First word of sen data <br> @ABCDEFG[FCS]**R 2 bytes | 0006 |
| :---: | :---: |
|  | 0007 |
|  | "AB" |
|  | "CD" |
|  | "EF" |
|  | "G" |

3. Refer to the manual for the ES100 $\square$ for the contents of send data and receive data.

# Appendix G <br> K3T $\square$ Intelligent Signal Processor Protocol 

The K3T $\square$ Intelligent Signal Processor Protocol is used to make various settings or control remotely the Intelligent Signal Processor connected to the Communications Board via RS-232C or RS-422A/485 cable.

## Protocol Configuration

The configuration of the K3T $\square$ Intelligent Signal Processor Protocol is shown as follows:

| Sequence No. | Communications sequence name | Function | Ladder interface |  | Notes |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |  |
| 300 | Reset (by unit number) | Performs the same processing as when an input is received on the reset terminal. | Yes | No |  |
| 301 | Reset (continuous units) | Performs the same processing as when an input is received on the reset terminal. | Yes | No |  |
| 302 | Write set value (by unit number) | Writes the set value HH, H, L, or LL. | Yes | No | See Note1 |
| 303 | Write set value HH (continuous units) | Writes the set value HH. | Yes | No | See Note1 |
| 304 | Write set value H (continuous units) | Writes the set value H . | Yes | No | See Note1 |
| 305 | Write set value L (continuous units) | Writes the set value L. | Yes | No | See Note1 |
| 306 | Write set value LL (continuous units) | Writes the set value LL. | Yes | No | See Note1 |
| 307 | Write set value with bank (by unit number) | Writes the set value to a bank which is not in use (K3TR: HH to LL, K3TC: O1 to O5). | Yes | No | See Note2 |
| 308 | Write set value HH with bank (continuous units) | Writes the set value HH to a bank which is not in use. | Yes | No | See Note1 |
| 309 | Write set value H with bank (continuous units) | Writes the set value H to a bank which is not in use. | Yes | No | See Note1 |
| 310 | Write set value $L$ with bank (continuous units) | Writes the set value $L$ to a bank which is not in use. | Yes | No | See Note1 |
| 311 | Write set value LL with bank (continuous units) | Writes the set value LL to a bank which is not in use. | Yes | No | See <br> Note1 |
| 312 | Write set value O5 with bank (continuous units) | Writes the set value O5 to a bank which is not in use. | Yes | No | See Note1 |
| 313 | Write set value O4 with bank (continuous units) | Writes the set value O4 to a bank which is not in use. | Yes | No | See Note1 |
| 314 | Write set value O 3 with bank (continuous units) | Writes the set value O3 to a bank which is not in use. | Yes | No | See Note1 |
| 315 | Write set value O2 with bank (continuous units) | Writes the set value O2 to a bank which is not in use. | Yes | No | See Note1 |
| 316 | Write set value O1 with bank (continuous units) | Writes the set value O1 to a bank which is not in use. | Yes | No | See Note1 |
| 317 | Read set value (by unit number) | Reads the set value $\mathrm{HH}, \mathrm{H}, \mathrm{L}$, or LL. | Yes | Yes | See Note1 |
| 318 | Read set value HH (continuous units) | Reads the set value HH . | Yes | Yes | See Note1 |
| 319 | Read set value H (continuous units) | Reads the set value H . | Yes | Yes | See Note1 |


| Sequence No. | Communications sequence name | Function | Ladder interface |  | Notes |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |  |
| 320 | Read set value L (continuous units) | Reads the set value L. | Yes | Yes | See Note1 |
| 321 | Read set value LL (continuous units) | Reads the set value LL. | Yes | Yes | See Note1 |
| 322 | Read set value with bank (by unit number) | Reads set value of a bank which is not in use (K3TR: HH to LL, K3TC: O1 to O5). | Yes | Yes | See Note2 |
| 323 | Read set value HH with bank (continuous units) | Reads the set value HH of a bank which is not in use. | Yes | Yes | See Note1 |
| 324 | Read set value H with bank (continuous units) | Reads the set value H of a bank which is not in use. | Yes | Yes | See Note1 |
| 325 | Read set value $L$ with bank (continuous units) | Reads the set value $L$ of a bank which is not in use. | Yes | Yes | See Note1 |
| 326 | Read set value LL with bank (continuous units) | Reads the set value LL of a bank which is not in use. | Yes | Yes | See Note1 |
| 327 | Read set value O5 with bank (continuous units) | Reads the set value O5 of a bank which is not in use. | Yes | Yes | See Note1 |
| 328 | Read set value O4 with bank (continuous units) | Reads the set value O4 of a bank which is not in use. | Yes | Yes | See <br> Note1 |
| 329 | Read set value O3 with bank (continuous units) | Reads the set value O3 of a bank which is not in use. | Yes | Yes | See Note1 |
| 330 | Read set value O2 with bank (continuous units) | Reads the set value O2 of a bank which is not in use. | Yes | Yes | See Note1 |
| 331 | Read set value O1 with bank (continuous units) | Reads the set value O1 of a bank which is not in use. | Yes | Yes | See Note1 |
| 332 | Read holding data (by unit number) | Reads the peak/bottom data (maximum, minimum). | Yes | Yes | See Note3 |
| 333 | Read holding data PH (continuous units) | Reads the peak data (maximum). | Yes | Yes | See Note3 |
| 334 | Read holding data BH (continuous units) | Reads the bottom data (minimum). | Yes | Yes | See Note3 |
| 335 | Read display value (PV) (by unit number) | Reads the display value (PV). | Yes | Yes |  |
| 336 | Read display value (PV ) (continuous units) | Reads the display value (PV). | Yes | Yes |  |
| 337 | Read model (by unit number) | Reads the model data. | Yes | Yes |  |
| 338 | Read model (continuous units) | Reads the model data. | Yes | Yes |  |
| 339 | General-purpose command | Send specified data or receives specified data and writes it to the receive data words. | Yes | Yes |  |

Note 1. Special specifications are required to use communications + comparison output.
2. Special specifications are required to use communications + comparison output for the K3TR and K3TC. The operands HH, H, L, and LL are for the K3TR, and the operands O5, O4, O3, O2, and O1 are for the K3TC.
3. Not available for the K3TC.
4. Ladder Interface Settings

YES: User settings are required for the 2nd and 3rd operands of PMCR.
NO: Send word allocation: Set a dummy word address for the 3rd operand (D).
Receive word allocation: Set the constant 0000 for the 2rd operand (S).

## Connections

The connections used for the K3T $\square$ Intelligent Signal Processor Protocol are shown below.

## RS-232C Connections



| Signal name | Abbreviation | Signal <br> direction | Pin No. |
| :--- | :--- | :--- | :--- |
| Protective ground or earth | FG | - | 1 |
| Signal ground or common return line | SG | - | 7 |
| Send data | SD | Output | 2 |
| Receive data | RD | Input | 3 |
| Request to send | RS | Output | 4 |
| Clear to send | CS | Input | 5 |
| Data set ready | DR | Input | 6 |
| Data terminal ready | ER | Output | 20 |



Note 1. The connection configuration is a one-to-one configuration and the maximum cable length is 15 m .
2. Use shielded twisted-pair cable (AWG28i or greater).

## RS-422A/485 Connections

C200HX/HG/HE


- RS-422A


| Signal name | Abbreviation | Signal direction | Pin No. |
| :--- | :--- | :--- | :--- |
| Send data A | SDA | Output | 9 |
| Send data B | SDB | Output | 5 |
| Receive data A | RDA | Output | 6 |
| Receive data B | RDB | Input | 1 |
| Signal ground | SG | - | 3 |
| Protective ground | FG | - | 7 |



## - RS-485



Note 1. The connection configuration is a one-to-one or a 1-to- N configuration. For 1 -to- N connections, up to 32 units can be connected. (With 2-wire communications, this figure includes the Communications Board whereas with 4 -wire communications it does not.)
2. The maximum cable length is 500 m . Use shielded twisted-pair cables (AWG28i or greater).
3. Connect termination resistance at both ends of the transmission path.
4. Turn the terminal block switch ON at the terminators.
5. Turn the terminal block switches OFF for units that are not terminators.

## Reset (by Unit Number) (Sequence No. 300)

This sequence performs the same processing as when an input is received on the reset terminal.
Send Data Word Allocation (2nd Operand of PMCR)


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0003 to 0034 |
| +1 | Number of units (2 digits BCD) | 01 to 32 |
| +2 | Relevant unit No. (2 digits BCD) | 00 to 99 |
|  | $\stackrel{-}{\bullet}$ |  |
| +33 | Relevant unit No. (2 digits BCD) | 00 to 99 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Reset Control (Continuous Units) (Sequence No. 301)

This sequence performs reset control for continuous units.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Number of units |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 |
| +1 | Number of units <br> (2 digits BCD) | 01 to 32 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Set Value (by Unit Number) (Sequence No. 302)

This sequence writes each set value (HH, H, L, LL).

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) |  | Data |
| :---: | :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0006 to 0126 |  |
| +1 | Number of units (2 digits BCD) | 01 to 31 |  |
| +2 | Relevant unit No. (2 digits BCD) | 00 to 99 |  |
| +3 | Operand <br> (ASCII 2 characters) | 4848 ("HH"), 4C4C ("LL") <br> 4820 ("H"), 4 C 20 ("L") |  |
| $\begin{aligned} & +4 \text { to } \\ & +5 \end{aligned}$ | Set value <br> (5 digits BCD) | 00000 to 99999 Negative sign: F ( Example 12345 | BCD digit) <br> Example-1234 |
|  | $\bullet$ |  |  |
| $\begin{aligned} & +124 \text { to } \\ & +125 \end{aligned}$ | Set value <br> (5 digits BCD) | Same as above |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Set Value HH (Continuous Units) (Sequence No. 303)

This sequence writes set value HH for continuous units.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) |  | Data |
| :---: | :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0004 to 0066 |  |
| +1 | Number of units (2 digits BCD) | 01 to 32 |  |
| $\begin{aligned} & +2 \text { to } \\ & +3 \end{aligned}$ | Set value <br> (5 digits BCD) | 00000 to 99999 Negative sign: F (5 Example 12345 | CD digit) <br> Example-1234 <br>  1234 <br>  1200 F |
|  | $\stackrel{-}{\bullet}$ |  |  |
| $\begin{array}{\|l\|} \hline+64 \text { to } \\ +65 \end{array}$ | Set value (5 digits BCD) | Same as above |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Write Set Value H (Continuous Units) (Sequence No. 304)

This sequence writes set value H for continuous units. The word allocation is identical to that of sequence No. 303 (Write Set Value HH (Continuous Units)).

## Write Set Value L (Continuous Units) (Sequence No. 305)

This sequence writes set value $L$ for continuous units. The word allocation is identical to that of sequence No. 303 (Write Set Value HH (Continuous Units)).

## Write Set Value LL (Continuous Units) (Sequence No. 306)

This sequence writes set value LL for continuous units. The word allocation is identical to that of sequence No. 303 (Write Set Value HH (Continuous Units)).

## Write Set Value with Bank (by Unit Number) (Sequence No. 307)

This sequence writes set value of a bank which is not in use (K3TR: HH to LL, K3TC:O1 to O5).

## Send Data Word Allocation (2nd Operand of PMCR)




## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Set Value HH with Bank (Continuous Units) (Sequence No. 308)

This sequence writes set value HH of a bank not in use for continuous units.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) |  | Data |
| :---: | :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0004 to 0098 |  |
| +1 | Number of units (2 digits BCD) | 01 to 32 |  |
| +2 | Bank No. (2 digits BCD) | 01 to 04 |  |
| $\begin{aligned} & +3 \text { to } \\ & +4 \end{aligned}$ | Set value (5 digits BCD) | 00000 to 99999 Negative sign: F (5 Example 12345 | CD digit) <br> Example - 1234 |
|  | $\stackrel{-}{\bullet}$ |  |  |
| $\begin{aligned} & +96 \text { to } \\ & +97 \end{aligned}$ | Set value (5 digits BCD) | Same as above |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Write Set Value H with Bank (Continuous Units) (Sequence No. 309)

This sequence writes set value H of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 308 (Write Set Value HH with Bank (Continuous Units)).

## Write Set Value L with Bank (Continuous Units) (Sequence No. 310)

This sequence writes set value $L$ of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 308 (Write Set Value HH with Bank (Continuous Units)).

## Write Set Value LL with Bank (Continuous Units) (Sequence No. 311)

This sequence writes set value LL of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 308 (Write Set Value HH with Bank (Continuous Units)).

## Write Set Value O5 with Bank (Continuous Units) (Sequence No. 312)

This sequence writes set value O 5 of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 308 (Write Set Value HH with Bank (Continuous Units)).

## Write Set Value O4 with Bank (Continuous Units) (Sequence No. 313)

This sequence writes set value O 4 of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 308 (Write Set Value HH with Bank (Continuous Units)).

## Write Set Value O 3 with Bank (Continuous Units) (Sequence No. 314)

This sequence writes set value O 3 of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 308 (Write Set Value HH with Bank (Continuous Units)).

## Write Set Value O2 with Bank (Continuous Units) (Sequence No. 315)

This sequence writes set value O 2 of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 308 (Write Set Value HH with Bank (Continuous Units)).

## Write Set Value 01 with Bank (Continuous Units) (Sequence No. 316)

This sequence writes set value O1 of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 308 (Write Set Value HH with Bank (Continuous Units)).

## Read Set Value (by Unit Number) (Sequence No. 317)

Reads set value HH, H, L, or LL.

## Send Data Word Allocation (2nd Operand of PMCR)



## Receive Data Word Allocation (3rd Operand of PMCR))



## Read Set Value HH (Continuous Units) (Sequence No. 318)

This sequence reads set value HH for continuous units.
Send Data Word Allocation (2nd Operand of PMCR)

| First | word |  | of |  |
| :--- | :--- | :--- | :--- | :--- |
|  |  | Number of send data words |  |  |
| send data | +1 |  | (Undefined) | Number of units |
|  |  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 |
| +1 | Number of units (2 digits BCD) | 01 to 32 |

## Receive Data Word Allocation (3rd Operand of PMCR)

This sequence is similar to sequence No. 317 (Read Set Value (by Unit Number)).

## Read Set Value H (Continuous Units) (Sequence No. 319)

This sequence reads set value H for continuous units. The word allocation is identical to that of sequence No. 318 (Read Set Value HH (Continuous Units)).

## Read Set Value L (Continuous Units) (Sequence No. 320)

This sequence reads set value $L$ for continuous units. The word allocation is identical to that of sequence No. 318 (Read Set Value HH (Continuous Units)).

## Read Set Value LL (Continuous Units) (Sequence No. 321)

This sequence reads set value LL for continuous units. The word allocation is identical to that of sequence No. 318 (Read Set Value HH (Continuous Units)).

## Read Set Value with Bank (by Unit Number) (Sequence No. 322)

Reads the set value of a bank which is not in use (K3TR: HH to LL, K3TC:01 to 05) and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)



Receive Data Word Allocation (3rd Operand of PMCR)
Receive data storage words


| Offset | Contents (data format) | Data |  |
| :---: | :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0003 to 0065 |  |
| $\begin{aligned} & +1 \text { to } \\ & +2 \end{aligned}$ | Set value ( 5 digits BCD) | 00000 to 99999 Negative sign: F (5 Example 12345 | $B C D$ digit) <br> Example-1234 |
|  | $\stackrel{-}{\bullet}$ |  |  |
| $\begin{aligned} & +63 \text { to } \\ & +64 \end{aligned}$ | Set value (5 digits BCD) | Same as above |  |

## Read Set Value HH with Bank (Continuous Units) (Sequence No. 323)

This sequence reads set value HH of a bank not in use for continuous units.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0003 to 0034 |
| +1 | Number of units (2 digits BCD) | 01 to 32 |
| +2 | Bank No. (2 digits BCD) | 01 to 04 |
|  | $\bullet$ |  |
|  | $\bullet$ |  |
| +33 | Bank No. (2 digits BCD) | Same as above |

## Receive Data Word Allocation (3rd Operand of PMCR)

The word allocation is similar to sequence No. 322 (Read Set Value with Bank (by Unit Number)).

## Read Set Value H with Bank (Continuous Units) (Sequence No. 324)

This sequence reads set value H of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 323 (Read Set Value HH with Bank (Continuous Units)).

## Read Set Value L with Bank (Continuous Units) (Sequence No. 325)

This sequence reads set value $L$ of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 323 (Read Set Value HH with Bank (Continuous Units)).

## Read Set Value LL with Bank (Continuous Units) (Sequence No. 326)

This sequence reads set value LL of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 323 (Read Set Value HH with Bank (Continuous Units)).

## Read Set Value O5 with Bank (Continuous Units) (Sequence No. 327)

This sequence reads set value O 5 of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 323 (Read Set Value HH with Bank (Continuous Units)).

## Read Set Value 04 with Bank (Continuous Units) (Sequence No. 328)

This sequence reads set value O 4 of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 323 (Read Set Value HH with Bank (Continuous Units)).

## Read Set Value O3 with Bank (Continuous Units) (Sequence No. 329)

This sequence reads set value O 3 of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 323 (Read Set Value HH with Bank (Continuous Units)).

## Read Set Value O 2 with Bank (Continuous Units) (Sequence No. 330)

This sequence reads set value O 2 of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 323 (Read Set Value HH with Bank (Continuous Units)).

## Read Set Value 01 with Bank (Continuous Units) (Sequence No. 331)

This sequence reads set value O1 of a bank not in use for continuous units. The word allocation is identical to that of sequence No. 323 (Read Set Value HH with Bank (Continuous Units)).

## Read Holding Data (Sequence No. 332)

Reads the peak/bottom data (maximum, minimum) and stores the results in the specified words.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data


| Offset | Contents (data format) | Data |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 to 0066 |  |  |  |
| +1 | Number of units (2 digits BCD) | 01 to 32 |  |  |  |
| +2 | Relevant unit No. (2 digits BCD) | 00 to 99 |  |  |  |
| +3 | Operand (ASCII 2 characters) | 5048 ("PH") <br> 4248 ("BH") |  |  |  |
|  | $\bullet$ |  |  |  |  |
|  | $\bullet$ |  |  |  |  |
| +65 | Operand (ASCII 2 characters) | Same as above |  |  |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Contents (data format) | Data |  |
| :---: | :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0004 to 0097 |  |
| $\begin{aligned} & +1 \text { to } \\ & +2 \end{aligned}$ | Peak/bottom data ( 5 digits BCD) | 00000 to 99999 <br> Negative sign: F (5th BCD digit) Example 12345 Example $\begin{array}{l\|l\|}  & 2345 \\ & 0001 \\ \hline \end{array}$ $\begin{aligned} & +1 \\ & +2 \\ & \hline \end{aligned}$ | $\frac{e-1234}{1234} \frac{000 F}{}$ |
| +3 | Status <br> (2 digits Hex) | d0 bit: <br> If overflow: 1 <br> Others: 0 |  |
|  |  | If underflow: $1 \quad$ Others: 0 |  |
|  |  | d2 bit: Not used |  |
|  |  | d3 bit:During forced zero operation: $1 \quad$ Others: 0(K3TH,K3TR: 0) |  |
|  |  | d4 bit: Not used |  |
|  |  | d5 bit: <br> During hold input: 1 | Others: 0 |
|  |  | d6 bit: <br> Bank input 1: 1 <br> (K3TH, K3TX: 0) | Others: 0 |
|  |  | d7 bit: <br> Bank input 2: 1 <br> (K3TH, K3TX: 0) | Others: 0 |
|  | $\stackrel{-}{\bullet}$ |  |  |
| +96 | Status | Same as above |  |

## Read Holding Data PH (Continuous Units) (Sequence No. 333)

This sequence reads peak holding data for continuous units.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of | +0 | Number of send data words |  |  |
| :--- | :--- | :--- | :--- | :--- |
| send data | +1 | (Undefined) | Number of units |  |
|  |  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 |
| +1 | Number of units (2 digits BCD) | 01 to 32 |

## Receive Data Word Allocation (3rd Operand of PMCR)

The data allocation is similar to sequence No. 332 (Read Holding Data (by Unit Number)).

## Read Holding Data BH (Continuous Units) (Sequence No. 334)

This sequence reads bottom holding data for continuous units. The word allocation is identical to that of sequence No. 333 (Read Holding Data PH (Continuous Units)).

## Read Display Value (PV) (by Unit Number) (Sequence No. 335)

Reads the display value (PV) and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send data | Number of send data words |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | (Undefined) |  | Number of units |  |
|  | (Undefined) |  | Relevant unit No. |  |
|  | $\sim$ |  |  |  |
|  | (Undefined) |  | Relevant unit No. |  |
|  | Offset | Contents (data format) |  | Data |
|  | +0 | Numb (4 digit | send data words CD) | 0003 to 0034 |
|  | +1 | Numb (2 digit | units <br> CD) | 01 to 32 |
|  | +2 | Releva <br> (2 digi | nit No. <br> CD) | 00 to 99 |
|  |  |  | - |  |
|  | + 33 | Releva (2 digi | nit No. CD) | 00 to 99 |

Receive Data Word Allocation (3rd Operand of PMCR)



## Read Display Value (PV) (Continuous Units) (Sequence No. 336)

This sequence reads display value (PV) for continuous units.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of +0 | Number of | d data words |
| :---: | :---: | :---: |
| send data +1 | (Undefined) | Number of units |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 |
| +1 | Number of units <br> $(2$ digits BCD) | 01 to 32 |

## Receive Data Word Allocation (3rd Operand of PMCR)

This sequence is similar to sequence No. 335 (Read Display Value (PV) (Continuous Units)).

## Model Data Read (by Unit Number) (Sequence No. 337)

Reads model data and stores the results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |  |  |  |
| :--- | :--- | :--- | :---: | :---: | :---: |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 to 0027 |  |  |  |
| +1 | Number of units <br> (2 digits BCD) | 01 to 25 |  |  |  |
| +2 | Relevant unit No. <br> $(2$ digits BCD) | 00 to 99 |  |  |  |
|  |  |  |  |  |  |
| +26 | Relevant unit No. <br> $(2$ digits BCD) | Same as above |  |  |  |

Note The number of Units can be up to 25 maximum.
Receive Data Word Allocation (3rd Operand of PMCR)

| Receive data storage words | $\begin{array}{r} +0 \\ +1 \\ +2 \\ +3 \\ +4 \\ +5 \\ + \\ +121 \\ +122 \\ +123 \\ +124 \\ +125 \end{array}$ | Number of receive data words |  |
| :---: | :---: | :---: | :---: |
|  |  | Input specifications |  |
|  |  | Input specifications | Display specifications |
|  |  | Output specifications |  |
|  |  | Input contents |  |
|  |  | Operation mode |  |
|  |  |  | $\sim$ |
|  |  | Input specifications |  |
|  |  | Input specifications | Display specifications |
|  |  | Output specifications |  |
|  |  | Input contents |  |
|  |  | Operation mode |  |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0006 to 0126 |
| $\begin{aligned} & +1 \text { to } \\ & +2 \end{aligned}$ | Input specifications (ASCII 3 characters) | 544131 ("TA1") (K3TH) 544231 ("TB1") (K3TH) 564432 ("VD2") (K3TX) 414432 ("AD2") (K3TX) 564132 ("VA2") (K3TX) 414132 ("AA2") (K3TX) 524231 ("RB1") (K3TR, K3TC) |
| +2 | Display specifications (ASCII 1 character) | 41 ("A") (common) <br> 42 ("B") (K3TH, K3TX) <br> 43 ("C") (K3TR, K3TC) |
| +3 | Output specifications (ASCII 2 characters) | 5331 ("S1") (RS-232C) 5332 ("S2") (RS-485) 5333 ("S3") (RS-422A) 5335 ("S5") (RS-485 + comparison output) 5336 ("S6") (RS-422A + comparison output) |
| +4 | Input contents (ASCII 2 characters) | Leftmost digit: 30 ("0") to 31 ("1") |
|  |  | Rightmost digit: 31 ("1") to 45 ("E") |
| +5 | Operation mode (ASCII 2 characters) | 3030 ("00") (K3TH, K3TX) 3031 ("00") to 3133 ("12") (K3TR) 5542 ("UB") (K3TC) 5543 ("UC") (K3TC) |
|  |  |  |
| +125 | Operation mode <br> (ASCII 2 characters) | Same as above |

## Model Data Read (Continuous Units) (Sequence No. 338)

This sequence reads model data for continuous units.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word | of |  | +0 | Number of send data words |  |
| :--- | :--- | :--- | :--- | :--- | :---: |
| send data | +1 | (Undefined) | Number of units |  |  |
|  |  |  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 |
| +1 | Number of units <br> $(2$ digits BCD) | 01 to 25 |

Note The number of Units can be up to 25 maximum.

## Receive Data Word Allocation (3rd Operand of PMCR)

The work allocation is similar to sequence No. 337 (Model Data Read (by Unit Number)).

## General-purpose Command (Sequence No. 339)

Sends the specified data and writes the receive data to the receive data words. The characters such as "@", FCS, terminators need not be set in the send and receive data words. These characters will be automatically added for transmission and automatically removed before saving data.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word send data | N | Send data byte length <br> Send data <br> Send data <br> Send data |  |
| :---: | :---: | :---: | :---: |
|  | Offset | Contents (data format) | Data |
|  | +0 | Number of send data words (4 digits BCD) | 0003 to 0128 |
|  | +1 | Send data byte length (4 digits BCD) | $0001 \text { to } 0251$ <br> Number of bytes of send data not including @, the FCS, and the terminator. |
|  | $\begin{aligned} & +2 \mathrm{to} \\ & +127 \end{aligned}$ | Send data (ASCII) | ASCII code Send data: 251 characters max. |

Receive Data Word Allocation (3rd Operand of PMCR)
Receive data
storage words

| Number of receive data words |  |  |
| :---: | :---: | :---: |
| +1 | Receive data |  |
| +2 | Receive data |  |
| +3 | Receive data |  |
| $\sim$ |  |  |
| +126 | Receive data |  |
| Offset | Contents (data format) | Data |
| +0 | Number of receive data words (4 digits BCD) | 0001 to 0127 |
| $\begin{aligned} & +1 \text { to } \\ & +126 \\ & \hline \end{aligned}$ | Receive data (ASCII) | ASCII code Receive data: 251 characters max. |

## Appendix H <br> V500/V520 Bar Code Reader Protocol

The V500/V520 Bar Code Reader Protocol is used to make various settings or control remotely the Bar Code Reader connected the Communications Board via RS-232C cable.

## Protocol Configuration

The configuration of the V500/V520 Bar Code Reader Protocol is shown below.

| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 350 | BCR read start | Instructs the Reader to start a BCR read. | No | No |
| 351 | BCR read stop | Instructs the Reader to stop a BCR read. | No | No |
| 352 | Data read | Data read by the Reader is received and saved in the receive words. | No | Yes |
| 353 | Complete data read | Instructs the Reader to start a read. After the data read by the Reader is received and saved to the receive words, reading is stopped. | No | Yes |
| 354 | $\begin{aligned} & \hline \text { BCR function write } \\ & \text { (V500) } \end{aligned}$ | Writes the operation mode and read functions. | Yes | No |
| 355 | $\begin{aligned} & \text { BCR function read } \\ & \text { (V500) } \end{aligned}$ | Reads the operation mode and read functions. | No | Yes |
| 356 | Log data output request (V500) | Requests output of log data sent to host. | Yes | Yes |
| 357 | Preset data set (V500) | Writes preset data. | Yes | No |
| 358 | BCR connection confirmation (V500) | Confirms if the Reader is correctly set. | No | No |
| 359 | Log data clear (V500) | Clear log data. | No | No |
| 360 | Continuous data read (scan) (V500) | Performs the following operations repeatedly: starts reading, receives data read by the Reader, saves the data to the receive words by the scan method. | No | Yes |
| 361 | Continuous data read (interrupt) (V500) | Performs the following operations repeatedly: starts reading, receives data read by the Reader, saves the data to the receive words by the interrupt method (interrupt No.100). | No | Yes |
| 362 | BCR initialize | Clears the log, confirms BCR connection, and sets BCRs. | Yes | No |
| 363 | Continuous data read (scan) (V520) | Performs the following operations repeatedly: starts reading, receives data read by the Reader, saves the data to the receive words by the scan method. | No | Yes |
| 364 | Continuous data read (interrupt) (V520) | Performing the following operations repeatedly: starts reading, receives data read by the Reader, saves the data to the receive words by the interrupt method (interrupt No.100). | No | Yes |
| 365 | General-purpose command 1 | Used to send data of a specified data length, and receive only ACK as the receive data. | Yes | No |
| 366 | General-purpose command 2 | Used to send data of a specified data length, and receive ACK together with the return of other receive data. The frame format of the receive data, however, has to contain STX and ETX. | Yes | Yes |

## Note Ladder Interface Settings

YES: User settings are required for the 2nd and 3rd operands of PMCR.
NO: Send word allocation: Set a dummy word address for the 3rd operand (D). Receive word allocation: Set the constant 0000 for the 2rd operand (S).

## Connections

The connections for using the V500/V520 Bar Code Reader Protocol are shown below.

## V500 Connections



V520 Connections


Communications Board:
D-sub 9 pin female


V520-R121:
D-sub 9 pin female

| Pin No. | Signal <br> Name |
| :---: | :---: |
| 1 | SD |
| 2 | RD |
| 3 | RS |
| 4 | CS |
| 6 | ER |
| 7 | SG |

## System Setting

Shown below are the system settings of the V500-C11 and V520-R121 when this protocol is used.
Note The portions enclosed by in boxes are used for this protocol.

## V500-C11

- BCR Functions

| Read trigger | "READ SIGNAL INPUT","ONLINE READ COMMAND" |
| :--- | :--- |
| Read control method | "SINGLE READ", "CONTINUOUS READ" |

- Host Interface

| Prefix | NONE,"STX" |
| :--- | :--- |
| Suffix | "ETX", "CR" |
| Bar code output | "OUTPUT", "NO OUTPUT" |

## V520-R121

| Start code | NONE, "STX" |
| :--- | :--- |
| Stop code | "ETX", "CR" |
| Operation mode | External trigger, host trigger |
| Data output mode | 1 -shot, continuous |

## BCR Read Start (Sequence No. 350)

This sequence instructs the Bar Code Reader to start reading.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## BCR Read Stop (Sequence No. 351)

This sequence instructs the Bar Code Reader to stop reading.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Data Read (Sequence No. 352)

This sequence receives read data and saves it to the receive data storage words.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0002 to 0017 |
| +1 to <br> +16 | Read data (ASCII) | 30 ('0') to 39 ('9'), 41 ('A') to 5A ('Z'), 3F ('?') <br> Up to 32 characters in ASCII |

Note The reception wait time is not set for this sequence.

## Complete Data Read (Sequence No. 353)

This sequence instructs the Bar Code Reader to start reading, receives the data read by the Bar Code Reader, stores the data in the receive data storage words, and then instructs the Reader to stop reading.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
It is similar to sequence No. 352 (Data read).
Note The reception wait time is not set for this sequence.

## BCR Function Write (V500) (Sequence No. 354)

This sequence sets the operation mode and read functions in the Bar Code Reader.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of
send data

| +0 | Number of send data words |  |  |
| :---: | :---: | :---: | :---: |
|  | Operation mode | In-zone control |  |
| +2 | Types of bar code | (Undefined) |  |
|  | (Undefined) | Number of digits |  |
| +4 | Modulus check | (Undefined) |  |
| +5 | (Undefined) | Number of <br> matches |  |
| Multistep <br> labels |  |  |  |
|  | Buzzer | Horizontal control |  |
|  |  |  |  |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0007 (fixed) |
| +1 | Operation mode (ASCII 1 character) | 41 ('A') : $* 42$ ('B') : ONLINE ONLINE CONTROL |
|  | In-zone control (ASCII 1 character) | $\begin{array}{ll} * 41\left({ }^{*} A^{\prime}\right): & \text { ON } \\ 42\left(B^{\prime}\right): & \text { OFF } \end{array}$ |
| +2 | Bar code type (ASCII 1 character) | ```41 ('A') : JAN 42 ('B') : NW7 NORMAL 43 ('C') : NW7 SMALL 44 ('D') : NW7 HEX 45 ('E') : CODE39 NORMAL 46 ('F') : CODE39 ST/SP OUTPUT 47 ('G') : 2 of 5 (ITF) 48 ('H') : CODE128 49 ('l') : CODE93 4A ('J') : 2 of 5 (3BAR) 4B ('K') : 2 of 5 (5BAR)``` |
| +3 | Number of digits (2 digits BCD) | 00 to 32 <br> 00: Any number of digits allowed. |
| +4 | Modulus check (ASCII 1 character) | 41 ('A') : No-check <br> 42 ('B') : Modulus 10 (all bar codes) <br> 43 ('C') : Modulus 11 (except JAN) <br> 44 ('D') : Modulus 16 (NW7 only) <br> 45 ('E') : Modulus 43 (CODE39 only) <br> 46 ('F') : Modulus 47 (CODE93 only) <br> 47 ('G') : Modulus 103 (CODE128 only) |
| +5 | Number of matches (1 digit BCD) | 1 to 5 |
|  | Multistep labels (1 digit BCD) | 1 to 4 |
| +6 | Buzzer (ASCII 1 character) | 41 ('A') : ON for normal read <br> 42 ('B') : ON for no-read <br> 43 ('C') : OFF |
|  | Horizontal control mode (ASCII 1 character) | 41 ('A') : Normal (continuous rotating) <br> 42 ('B') : In-zone startup |

Note Selecting the values marked with asterisks is required for this protocol.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## BCR Function Read (V500) (Sequence No. 355)

This sequence reads the settings of functions in the Bar Code Reader.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |  |  |
| :---: | :---: | :---: | :---: |
|  | Operation mode | In-zone control |  |
| +2 | Types of bar code | (Undefined) |  |
| +3 | (Undefined) | Number of digits |  |
| +4 | Modulus check | (Undefined) |  |
|  | (Undefined) | Number of <br> matches. |  |
| Multistep <br> labels. |  |  |  |
|  | Buzzer | Horizontal control |  |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0007 (fixed) |
| +1 | Operation mode <br> (ASCII 1 character) | 41 ('A'): ONLINE <br> 42 ('B'): ONLINE CONTROL |
|  | In-zone control (ASCII 1 character) | $\begin{array}{ll} \hline 41 \text { ('A') }: ~ O N \\ 42 \text { ('B') }: ~ O F F ~ \end{array}$ |
| +2 | Bar code type <br> (ASCII 1 character) | 41 ('A') : JAN <br> 42 ('B') : NW7 NORMAL <br> 43 ('C') : NW7 SMALL <br> 44 ('D') : NW7 HEX <br> 45 ('E') : CODE39 NORMAL <br> 46 ('F'): CODE39 ST/SP Output <br> 47 ('G') : 2 of 5 (ITF) <br> 48 ('H') : CODE128 <br> 49 ('l'): CODE93 <br> 4A ('J') : 2 of 5 (3BAR) <br> 4B ('K') : 2 of 5 (5BAR) |
| +3 | Number of digits (2 digits BCD) | 00 to 32 |
| +4 | Modulus check (ASCII 1 character) |  |
| +5 | Number of matches (1 digit BCD) | 1 to 5 |
|  | Multistep labels (1 digit BCD) | 1 to 4 |
| +6 | Buzzer (ASCII 1 character) | 41 ('A'): ON for normal read 42 ('B') $:$ ON for no-read 43 ('C') : OFF |
|  | Horizontal control mode (ASCII 1 character) | 41 ('A') : Normal (continuous rotating) <br> 42 ('B') : In-zone startup |

## Log Data Output Request (V500) (Sequence No. 356)

This sequence requests output of the log data sent to host.

## Send Data Word Allocation (2nd Operand of PMCR)

| First | word | of | +0 | Number of send data words |  |
| :--- | :--- | :--- | :--- | :--- | :---: |
|  |  |  | (Undefined) | Number of units |  |
|  |  |  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Number of units <br> $(2$ digits BCD) | 01 to 99 |

Receive Data Word Allocation (3rd Operand of PMCR)

| Receive data storage words | +0 | Number of receive data words |
| :---: | :---: | :---: |
|  | +1 | Log data |
|  | +2 | Log data |
|  |  | ' |
|  | +125 | Log data |
|  | +126 | Log data |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0001 to 0127 |
| +1 to | Log data (ASCII) | Log data with the number of designated data is stored <br> including the separator GS (1D). <br> If the log data (including separator) exceeds 251 <br> bytes, only 251 bytes are stored. |

Note No retries are performed for this sequence.

## Preset Data Set (V500) (Sequence No. 357)

This sequence sets preset data.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | $18 \mathrm{~N}+2$ (N is number of presets 1 to 5) |
| +1 | Number of presets <br> (1 digit BCD) | 1 to 5 |
| +2 | Preset data No. <br> (1 digit BCD) | 1 to 5 |
| +3 | Data length <br> (2 digits BCD) | 01 to 32 |
| +4 to | Preset data (ASCII) | Combination of the following ASCII characters and up <br> to 32 characters maximum: <br> $30 ~(' 0 ') ~ t o ~ 39 ~(' 9 ') ~$ |
| +19 |  | 41 ('A') to 5A ('Z'), 3F ('?') <br> The area that is not used is undefined |
| +20 to |  | Store repeatedly the contents of words with offsets +2 <br> to +19 the same number of times as the number of <br> presets (N) |
| +91 |  |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## BCR Connection Confirmation (V500) (Sequence No. 358)

This sequence confirms whether the Bar Code Reader is connected correctly or not.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Log Data Clear (V500) (Sequence No. 359)

This sequence clears the log data.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Data Continuous Read (Scan) (V500) (Sequence No. 360)

This sequence performs the following operations repeatedly: Instructs the Bar Code Reader to start reading and receives the data read by the Bar Code Reader. The scan notification method is used for the receive data.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data word allocation is similar to that of sequence No. 352 (Data read).
Note 1. Since this sequence repeats itself within the sequence, once it is executed, it remains in the execution state until cancelled.
2. Even if execution is cancelled, the Bar Code Reader still keeps reading. Execute sequence No. 351 (BCR read stop) to end the sequence.
Note The reception wait time is not set for this sequence.

## Data Continuous Read (Interrupt) (V500) (Sequence No. 361)

This sequence performs the following operations repeatedly: Instruct the Bar Code Reader to start reading and receives the data read by the Bar Code Reader. The interrupt notification method is used for the receive data and the interrupt No. is 100.

## Send Data Word Allocation (2nd Operand of PMCR)

## None.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation similar to that of sequence No. 352 (data read).
Note 1. Since this sequence repeats itself within the sequence, once it is executed, it remains in the execution state until cancelled.
2. Even if execution is cancelled, the Bar Code Reader keeps reading. Execute sequence No. 351 (BCR read stop) to end the sequence.

Note The reception wait time is not set for this sequence.

## BCR Initialize (V500) (Sequence No. 362)

This sequence clears the log data, confirms BCR connection and sets the BCR functions.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of sequence No. 354 (BCR Function Set).

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Data Continuous Read (Scan) (V520) (Sequence No. 363)

This sequence performs the following operations repeatedly: instructs the Bar Code Reader to start reading and receives the data read by the Bar Code Reader. The scan notification method is used for the receive data.

## Send Data Word Allocation (2nd Operand of PMCR) <br> None.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of sequence No. 352 (Data Read).
Note 1. Since this sequence repeats itself within the sequence, once it is executed, it remains in the execution state until cancelled.
2. Even if execution is cancelled, the bar code still keeps reading. Execute sequence No. 351 (BCR Read Stop) to end the sequence.
3. The reception wait time is not set for this sequence.

## Data Continuous Read (Interrupt) (V520) (Sequence No. 364)

This sequence performs the following operations repeatedly: Instructs the Bar Code Reader to start reading and receives the data read by the Bar Code Reader. The interrupt notification method is used for the receive data and the interrupt No. is 100.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

The send data word allocation is similar to that of sequence No. 352 (Data Read).
Note 1. Since this sequence repeats itself within the sequence, once it is executed, it remains in the execution state until cancelled.
2. Even if execution is cancelled, the bar code still keeps reading. Execute sequence No. 351 (BCR Read Stop) to end the sequence.
3. The reception wait time is not set for this sequence.

## General-purpose Command 1 (Sequence No. 365)

This general-purpose command is used to send data with a specified data length, and receive back only ACK. STX and ETX are automatically attached to the send data.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0003 to 0129 |
| +1 | Send data byte length <br> (4 digits BCD) | 0001 to 0254 <br> The byte length of the send data excluding STX and <br> ETX. |
| +2 to <br> +128 | Send data (ASCII) | Inscribe send data up to 254 bytes (max.) by ASCII. |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## General-purpose Command 2 (Sequence No. 366)

This general-purpose command is used to send data with a specified data length, and receive back ACK in addition to other receive data. The frame format of the receive data, however, has to contain STX and ETX. STX and ETX are automatically attached to the send data.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |
| :--- | :---: |
|  | Send data byte length |
|  | Send data |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 to 0129 |
| +1 | Send data byte length <br> (3 digits BCD) | 1 to 254 <br> The byte length of the send data excluding STX and <br> ETX. |
| +2 to <br> +128 | Send data (ASCII) | Set send data up to 254 bytes (max.) by ASCII. |

## Receive Data Storage Word Allocation (3rd Operand of PMCR)

| Receive data storage words |  <br>  <br>  <br>  <br>  | ber of receive data words | $\sim$ |
| :---: | :---: | :---: | :---: |
|  | Offset | Contents (data format) | Data |
|  | +0 | Number of receive data words (4 digits BCD) | 0001 to 0128 |
|  | $\begin{aligned} & +1 \text { to } \\ & +127 \end{aligned}$ | Receive data (ASCII) | If the receive data exceed 253 bytes, only 253 bytes are stored. |

Note Shown below is the receive data frame format. The reception data without ACK, STX, and ETX is stored.


# Appendix I 3Z4L Laser Micrometer Protocol 

The 3Z4L Laser Micrometer Protocol is used to make various settings or control remotely the Laser Micrometer connected to the Communications Board via RS-232C cable.

## Protocol Configuration

The configuration of the 3Z4L Laser Micrometer Protocol is shown below.

| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 400 | 3Z4L clear | Resets errors, data, analog output, decision result and places the Laser Micrometer into standby. | No | No |
| 401 | Memory switch set | Sets memory switches and the area for the work position LED. | Yes | No |
| 402 | mm unit set | Sets the display unit to mm. | No | No |
| 403 | E unit set | Sets the display unit to E. | No | No |
| 404 | Calibration set | Calibrates the Laser Micrometer. Calibration setting release. | Yes | No |
| 405 | Calibration release | Releases the calibration of the Laser Micrometer. | No | No |
| 406 | Program number set (3000-series) | Switches the program number to a specified number. | Yes | No |
| 407 | Measurement condition set (3000-series) | Sets measurement conditions. | Yes | No |
| 408 | Measurement condition release (3000-series) | Releases measurement conditions that have been set. | Yes | No |
| 409 | Measurement condition list request (3000-series) | Requests the measurement conditions that have been set and other settings. | No | Yes |
| 410 | Single run measurement start (3000-series) | When the sample measurement condition is from 1 to 999, performs a single run measurement and requests the measurement results. | No | Yes |
| 411 | Zero run measurement start (3000-series) | If the sample measurement condition is zero, starts a zero run measurement. | No | No |
| 412 | Continuous measurement start (scan) (3000-series) | Starts a continuous measurement. The scan notification method is used for receive data. | No | Yes |
| 413 | Continuous measurement start (interrupt) (3000-series) | Starts a continuous measurement. The interrupt notification method is used for receive data. <br> Measurement termination (3000-series) | No | Yes |
| 414 | Measurement termination (3000-series) | Terminates a continuous measurement. | No | No* ${ }^{*}$ |
| 415 | Data request (3000-series) | Requests display data in the idle measurement status or the latch data generated by the measurement command. | No | Yes |
| 416 | Statistic processing execution (3000-series) | Lights the statistic processing LED and processes the statistics. | No | No |
| 417 | Statistic processing nonexecution (3000-series) | Turns OFF the statistic processing LED. Statistics are not processed. | No | No |


| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 418 | All statistic memory clear (3000-series) | Clears statistic processing memories of all programs. | No | No |
| 419 | Statistic memory clear (3000-series) | Clears statistic processing memories of program under display. | No | No |
| 420 | Statistic result request (3000-series) | Requests statistic processing result. | No | Yes |
| 421 | Memory switch set 1 (3000-series) | Sets memory switches. | Yes | No |
| 422 | Memory switch set 2 (3000-series) | Sets memory switches. | Yes | No |
| 423 | Simple AVG times set (3000-series) | Taking the simple average as the averaging method, sets the averaging times per measurement interval 4. | Yes | No |
| 424 | AVG move interval set (3000-series) | Taking the average move as the averaging method, sets the measurement interval number. | Yes | No |
| 425 | AVG move (H) times set (3000-series) | Taking the average move and high-speed data output as the averaging method, sets the averaging times per measurement interval 4. | Yes | No |
| 426 | AVG move (L) times set (3000-series) | Taking the average move and low-speed data output as the averaging method, sets the averaging times per measurement interval 4. | Yes | No |
| 427 | Automatic detection set (3000-series) | Sets work automatic detection function. | Yes | No |
| 428 | Automatic detection release (3000-series) | Releases the settings of work automatic detection function. | No | No |
| 429 | Automatic detection list request (3000-series) | Requests the settings of work automatic detection function. | No | Yes |
| 430 | 3Z4L initialize (3000-series) | Clears the $3 Z 4 \mathrm{~L}$, sets the mm unit, sets the memory unit, does not processes statistics, and clears all statistic memory. | Yes | No |
| 431 | Measurement condition set (4000-series) | Sets measurement conditions. | Yes | No |
| 432 | Measurement condition release (4000-series) | Releases measurement conditions that have been set. | Yes | No |
| 433 | Measurement condition list request (4000-series) | Requests the measurement conditions that have been set and other settings. | No | Yes |
| 434 | Single run measurement start (4000-series) | When the sample measurement condition is from 1 to 999 , performs a single run measurement and requests the measurement results. | No | Yes |
| 435 | Deflection measurement start (4000-series) | Starts a deflection measurement. | No | No |
| 436 | Continuous measurement start (scan) (4000-series) | Starts a continuous measurement. The scan notification method is used for receive data. | No | Yes |
| 437 | Continuous measurement start (interrupt) (4000-series) | Starts a continuous measurement. The interrupt notification method is used for receive data. | No | Yes |
| 438 | Measurement termination (4000-series) | Terminates continuous measurement. | No | No *1 |


| Sequence <br> No. | Communications sequence <br> name |  | Function | Ladder interface <br> Send word <br> allocation |  | Receive <br> word <br> allocation |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| 439 | Data request (4000-series) | Requests measurement data in the idle <br> measurement status or the latch data <br> generated by the measurement com- <br> mand. | No | Yes |  |  |
| 440 | Forced positive zero <br> (4000-series) | Sets the forced zero direction to positive <br> (+). | No | No |  |  |
| 441 | Forced negative zero <br> (4000-series) | Sets the forced zero direction to negative <br> $(-)$. | No | No |  |  |
| 442 | Forced zero release (4000-se- <br> ries) | Releases the forced zero direction. | No | No |  |  |
| 443 | 3Z4L initialize (4000-series) | Clears the 3Z4L, sets the mm unit, and <br> clears the memory unit settings. | Yes | No |  |  |
| 444 | General-purpose command 1 | Used to send data of a specified data <br> length, and receive only OK as the re- <br> ceive data. | Yes | No |  |  |
| 445 | General-purpose command 2 | Used to send data of a specified data <br> length, and receive data other than OK. | Yes | Yes |  |  |

*1 Depends on the measurement contents.

## Note Ladder Interface Settings

YES: User settings are required for the 2nd and 3rd operands of PMCR.
NO: Send word allocation: Set a dummy word address for the 3rd operand (D).
Receive word allocation: Set the constant 0000 for the 2rd operand (S).

## Connections

The connections for the 3Z4L Laser Micrometer Protocol are shown below.

## RS-232C Connection



Communications Board:
D-sub 9 pin (female)

| Signal <br> name | Pin No. |  | 25 pin (female) |  |
| :--- | :--- | :--- | :--- | :--- |
| FG | 1 |  | Pin No.Signal <br> name |  |
| SD | 2 |  | 2 | FG |
| RD | 3 |  | 3 | TXD |
| RS | 4 |  | 4 | RXD |
| CS | 5 |  | 5 | CTS |
| DR | 7 |  | 6 | DSR |
| ER | 8 |  | 7 | SG |
| SG | 9 |  | 20 | DTR |

## DIP Switch Settings

Shown below are the settings of $3 Z 4 \mathrm{~L}-3000,3 Z 4 \mathrm{~L}-4000$-series DIP switches required to use the system protocol sequences.

## 3Z4L-3000 Series

## - DIP Switch 1

| No. | Setting | Status |
| :--- | :--- | :--- |
| 1 | Baud rate | ON/OFF |
| 2 |  | ON/OFF |
| 3 | Handshaking procedure | ON/OFF |
| 4 | RS-232C interface use | ON/OFF |
|  | selection | ON/OFF |
| 6 |  | ON/OFF |

## - DIP Switch 2

| No. | Setting | Status |
| :---: | :---: | :---: |
| 1 | Selection for measurement section | ON/OFF |
| 2 |  | ON/OFF |
| 3 |  | ON/OFF |
| 4 |  | ON/OFF |
| 5 | Setting of minimum read value | ON/OFF |
| 6 |  | ON/OFF |
| 7 | Setting of transparent body measurement function | ON/OFF |
| 8 | Setting of simultaneous measurement function | ON/OFF |

Set these settings according to the sensor connected.

Set these settings for 4 digits in the decimal portion.

| No. | Setting | Status |
| :--- | :--- | :--- |
| 1 | Setting of measurement <br> function by 2 <br> measurement <br> instruments | ON/OFF |
|  |  | ON/OFF |
| 3 |  | ON/OFF |
| 4 |  | ON/OFF |
| 5 | Error data exclusion <br> function | ON/OFF |
| 6 | Multistep selection <br> function | ON/OFF |

This protocol does not sup-
port the error data exclusion function

## 3Z4L-4000 Series

## - DIP Switch 1

| No. | Setting | Status |
| :--- | :--- | :--- |
| 1 | Baud rate | ON/OFF |
| 2 |  | ON/OFF |
| 3 | Hand-shake procedure | ON/OFF |
| 4 | Delimiter | ON/OFF |
| 5 |  | ON/OFF |
| 6 | RS-232C interface use | ON/OFF |
|  | selection |  |
| 8 |  | ON/OFF |
|  |  |  |

## - DIP Switch 2

| No. | Setting | Status |  |
| :---: | :---: | :---: | :---: |
| 1 | Selection for measurement section | ON/OFF | Set these settings according to the sensor connected. |
| 2 |  | ON/OFF |  |
| 3 |  | ON/OFF |  |
| 4 |  | ON/OFF |  |
| 5 | Setting of minimum read value | ON/OFF | Set these settings for 4 digits in the decimal portion. |
| 6 |  | ON/OFF |  |
| 7 | Display unit | ON/OFF |  |
| 8 | External command setting | ON/OFF |  |

## Delimiter Control Code Setting

## 3Z4L-4000 Series

The delimiter control codes must be set on DIP switch SW1 for the 3Z4L-4000 Series. Turn off pins 4 and 5, set the delimiter codes to CR+LF, and set the delimiter code control setting in the sequence to CR+LF. See the setting for CR+LF in the following diagram.


## 3Z4L-3000 Series

The delimiter control code does not need to be set on the DIP switch for the 3Z4L-3000 Series. Set the delimiter
control codes in the sequence to CR+LF for the send code and to CR or CR+LF for the receive code. See the settings in the following diagram.


The High-speed 3Z4L-3000-series Meters must have the delimiter control codes set using the memory switches. Set both the send and receive codes to CR+LF.

## 3Z4L Clear (Sequence No. 400)

This sequence resets errors, data, analog output, and decision result, and puts the Laser Micrometer into standby.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Memory Switch Set (Sequence No. 401)

This sequence sets memory switches and the area for the work position LED.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 data$+1$ | Number of send data words |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | W | X | Y | Z |
| +2 | (Undefined) |  |  | V |


| Offset | Contents (data format) | Data |  |
| :---: | :---: | :---: | :---: |
|  |  | 3000-series | 4000-series |
| +0 | Number of send data words (4 digits BCD) | 0003 (fixed) | 0003 (fixed) |
| +1 | w (1 digit BCD) | Using buzzer sound: 0 to 3 | Number of digits for extinguishing indicator: 0 to 2 |
|  | $\mathrm{x}(1$ digit BCD$)$ | Automatic latch release time: 0 to 9 | I/O IF RUN Input: 0 or 1 |
|  | $y$ (1 digit BCD) | Using print timer, the setting for simultaneous measurement: 0 to 3 (high-speed), 0 to 1 (other) | Display of Err-0: 0 or 1 |
|  | $z$ (1 digit BCD) | Display of the comma for 1/1000s digit, number of display digits: 0 to 5 (high-speed), 0 to 3 (other) | Averaging method: 0 to 2 (high-speed), 0 (other) |
| +2 | $v$ (1 digit BCD) | Measurement interval 4: 0 to 6 | Use of comma: 0 or 1 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## mm Unit Set (Sequence No. 402)

This sequence sets the display unit to mm .
Send Data Word Allocation (2nd Operand of PMCR)
None.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note This sequence can be used for the 3Z4L-4000 Series only when pin 8 on DIP switch SW2 is turned ON.

## E Unit Set (Sequence No. 403)

This sequence sets the display unit to E .

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.
Note This sequence can be used for the 3Z4L-4000 Series only when pin 8 on DIP switch SW2 is turned ON.

## Calibration Set (Sequence No. 404)

This sequence calibrates the Laser Micrometer.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send data | +0 | Number of send data words |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | +1 | Decimal portion |  |  |  |  |  |
|  | +2 | (Undefined) |  | Decimal integer portion |  | High calibration gauge dimension |  |
|  | +3 | Sign |  | (Undefined) |  | gauge dimension |  |
|  | + | Decimal portion |  |  |  |  |  |
|  | +5 | (Undefined) |  | (Decimal integer portion) |  | Low calibration gauge dimension |  |
|  | +6 | Sign |  | (Undefined) |  |  |  |
|  | Offset |  | Contents (data format) |  | Data |  |  |
|  | +0 |  | Number of send data words (4 digits BCD) |  | 0007 (fixed) |  |  |
|  |  | +1 | HC gauge dimension (Decimal portion) (4 digits BCD) |  | 0000 to 9999 |  | Example -123.4567 |
|  |  |  |  |  | +1 | 4567 |
|  |  |  |  |  | +2 | 0123 |
|  |  |  |  |  | +3 | 2D00 |
|  | +2 |  | HC gauge dimension (integer portion) ( 3 digits BCD) |  |  | 000 to 999 |  | Example-123.4567 |
|  |  |  | +1 | 4567 |  |  |
|  | +3 |  |  |  | HC gauge dimension (Sign) (ASCII 1 character) |  | if +: 20( ') | +2 | 0123 |
|  |  |  | if -: $2 \mathrm{D}\left({ }^{(-\prime)}\right.$ | +3 |  |  | 2D00 |
|  | $\begin{aligned} & \hline+4 \text { to } \\ & +6 \end{aligned}$ |  | LC gauge dimensions |  | Same as HC gauge dimensions |  |  |

Note 1. For this sequence, both the high and low calibration gauges must be set.
2. The limit value, reference value, and offset value can be set to 3 digits for the integer portion and to 4 digits for the decimal portion.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Calibration Release (Sequence No. 405)

This sequence releases the calibration of the Laser Micrometer.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.
Note This sequence releases both the high and low calibration.

## Program Number Set (3000-series) (Sequence No. 406)

This sequence switches the program number to a specified number.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Program number (1 digit BCD) | 0 to 9 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note Retry processing is not performed for this sequence.

## Measurement Condition Set (3000-series) (Sequence No. 407)

This sequence sets measurement conditions. Conditions to be set can be selected by setting Yes/No flags.
Send Data Word Allocation (2nd Operand of PMCR)




| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| $\begin{aligned} & +30 \text { to } \\ & +32 \end{aligned}$ | Reference value | Same as lower limit values |
| +33 | Analog output scale number (1 digit BCD) | 1 to 3 |
| $\begin{aligned} & +34 \text { to } \\ & +35 \end{aligned}$ | Offset classification (ASCII 3 characters) | 4F4620 ("OF"), 4F4D20 ("OM") |
| $\begin{aligned} & +36 \text { to } \\ & +38 \end{aligned}$ | Offset value | Same as lower limit values |
| +39 | Data output conditions (1 digit BCD) | 0 to 6 |
| +40 | Scheduled output timer (3 digits BCD) | 000 to 999 |
| +41 | Sample measurement pulse (3 digits BCD) | 000 to 999 |
| $\begin{aligned} & +42 \text { to } \\ & +43 \end{aligned}$ | Sample measurement classification (ASCII 3 characters) | 415647 ("AVG"), 4D4158 ("MAX") 4D494E ("MIN"), 524E47 ("RNG") |
| $\begin{aligned} & +44 \text { to } \\ & +45 \end{aligned}$ | Unused | Undefined |
| +46 | Yes/No for segment setting (1 digit BCD) | Set: 1 (SG) <br> Don't set: 0 |
| +47 | Yes/No for measurement interval number setting (1 digit BCD) | Set: $\quad 1$ (M) <br> Don't set: 0 |
| +48 | Yes/No for upper/lower limit value setting <br> (1 digit BCD) | $\begin{aligned} & \text { Set: } \quad 1 \text { (LL,LH) } \\ & \text { Don't set: } 0 \end{aligned}$ |
| +49 | Yes/No for multistep selection limit value (1 digit BCD) | Set: 1 (L1,L2,L3,L4,L5,L6) <br> Don't set: 0 |
| +50 | Yes/No for reference setting (1 digit BCD) | ```Set: }1\mathrm{ (REF,SCL) Don't set: 0``` |
| +51 | Yes/No for offset value setting (1 digit BCD) | Set: 1 (OF or OM) <br> Don't set: 0 |
| +52 | Yes/No for data output condition setting (1 digit BCD) | Set: 1 (PR,PRT) <br> Don't set: 0 |
| +53 | Yes/No for sample measurement pulse setting (1 digit BCD) | Set: $\quad 1$ (SMP, MAX or MIN or RNG or AVG) Don't set: 0 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. This sequence cannot be used to set the error lower limit (EL), error upper limit (EH), error exclusion counter (CNT) of the error data exclusion function (centerless grinder function).
2. The following settings must be made together with this sequence; they cannot be set separately.

Lower limit, upper limit
Multistep selection limit
Reference value, analog output scale number
Data output conditions, scheduled print timer
3. The limit value, reference value, and offset value can be set to 3 digits for the integer portion and to 4 digits for the decimal portion.

## Measurement Condition Release (3000-series) (Sequence No. 408)

This sequence releases the measurement conditions that have been set.

## Send Data Word Allocation (2nd Operand of PMCR)

Send data word allocation is similar to that of sequence No. 407 (Measurement Condition Set). However, only the setting Yes/No flags at +46 to +53 from the send data leading word can be used.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. The following conditions are used when the measurement conditions are released: Segment becomes 1, measurement interval becomes 1 , the number of sample measurement pulses becomes 1 .
2. The following conditions cannot be released with this sequence: error lower limit (EL), error upper limit (EH), error exclusion counter (CNT) of the error data exclusion function (centerless grinder function).
3. The following settings cannot be released separately using this sequence.

Lower limit, Upper limit
Multistep selection limit
Reference value, analog output scale number
Data output conditions, scheduled print timer

## Measurement Condition List Request (3000-series) (Sequence No. 409)

This sequence requests the measurement condition settings that have been set and other settings.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

First word of send data



Note This sequence cannot be used to request the lower limit (EL), error upper limit (EH), error exclusion counter (CNT) of the error data exclusion function (centerless grinder function).

## Single Run Measurement Start (3000-series) (Sequence No. 410)

When the sample measurement condition is from 1 to 999 , this sequence performs a single run measurement and requests the measurement results

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
Receive data storage words


| Offset | Contents (data format) | Data |  |
| :---: | :---: | :---: | :---: |
| +0 | Number of receive data words (4 digit BCD) | With no reference setting: 0006 With reference setting: 0009 |  |
| +1 | Program number (1 digit BCD) | 0 to 9 |  |
| +2 | Decision result (ASCII 2 characters) | With no limit setting: 0000 <br> With limit setting: 2B4E (" +N "), 4F4B ("OK"), 2D4E ("-N") |  |
| +3 | Measurement value (decimal portion) (4 digits BCD) | 0000 to 9999 Exam <br>   <br> +3  | $\begin{aligned} & \mathrm{e}-123.4567 \\ & \hline 4567 \\ & \hline \end{aligned}$ |
| +4 | Measurement value (integer portion) (3 digits BCD) | 000 to 999 +4 <br> +5  | $\begin{aligned} & 0123 \\ & \text { F000 } \end{aligned}$ |
| +5 | Measurement value (Sign) (BIN) | $\begin{aligned} & \text { If }+: 0 \\ & \text { If }-: ~ F \end{aligned}$ |  |
| $\begin{aligned} & +6 \text { to } \\ & +8 \end{aligned}$ | Deviation value | Same as measurement value <br> *The deviation will be stored in this area only when reference setting is made. |  |

## Zero Run Measurement Start (3000-series) (Sequence No. 411)

If the sample measurement condition is zero, a zero run measurement is started.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.
Note The zero run measurement keeps measuring until sequence No. 414 (Measurement Termination) is executed.

## Continuous Measurement Start (Scan) (3000-series) (Sequence No. 412)

A continuous measurement is started. The scan notification method is used for the receive data.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
The receive data word allocation is similar to that of sequence No. 410 (Single Run Measurement Start).

Note 1. Since this sequence repeats itself within the sequence, once it is executed, it remains in the execution state until cancelled.
2. Even if execution is cancelled, the Laser Micrometer still keeps measuring. Execute sequence No. 414 (Measurement Termination) to end the sequence.

## Continuous Measurement Start (Interrupt) (3000-series) (Sequence No. 413)

A continuous measurement is started. The interrupt notification method is used for the receive data and the interrupt No. is 101.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of sequence No. 410 (Single Run Measurement Start).
Note 1. Since this sequence repeats itself within the sequence, once it is executed, it remains in the execution state until cancelled.
2. Even if execution is cancelled, the Laser Micrometer still keeps measuring. Execute sequence No. 414 (Measurement Termination) to end the sequence.

## Measurement Termination (3000-series) (Sequence No. 414)

This sequence terminates a continuous measurement.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
For continuous measurement: Not available
For Zero Run Measurement
The receive data word allocation is similar to that of sequence No. 410 (Single Run Measurement Start).

## Data Request (3000-series) (Sequence No. 415)

This sequence requests display data in the idle measurement status or the latch data generated by the measurement command.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
The receive data word allocation is similar to that of sequence No. 410 (Single Run Measurement Start).

## Statistic Processing Execution (3000-series) (Sequence No. 416)

This sequence lights the statistic processing LED and implements the statistic processing.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Statistic Processing Non-execution (3000-series) <br> (Sequence No. 417)

This sequence turns the statistic processing LED off and does not carry out the statistic processing.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## All Statistic Memory Clear (3000-series) (Sequence No. 418)

This sequence clears statistic processing memories of all programs.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Statistic Processing Memory Clear (3000-series) (Sequence No. 419)

This sequence clears statistic processing memories of the program under display.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Statistic Result Request (3000-series) (Sequence No. 420)

This sequence requests the statistic processing results.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)


| Offset | Contents (data format) | Data |  |
| :---: | :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0019 (fixed) |  |
| +1 | Program number (1digit BCD) | 0 to 9 |  |
| $\begin{aligned} & +2 \text { to } \\ & +3 \end{aligned}$ | Number of statistic data ( 6 digits BCD) | 000000 to 999999 |  |
| +4 | Average value (decimal portion) (4 digits BCD) | 0000 to 9999 | Example - 123.4567 |
| +5 | Average value (integer portion) (4 digits BCD) | 000 to 999 | +4 4567 <br> +5 0123 |
| +6 | Average value (Sign) (BIN) | $\begin{aligned} & \text { If }+: 0 \\ & \text { If }-: \text { F } \end{aligned}$ | +6 F000 |
| $\begin{aligned} & \hline+7 \text { to } \\ & +9 \end{aligned}$ | Maximum value | Same as average value |  |
| $\begin{aligned} & +10 \text { to } \\ & +12 \end{aligned}$ | Minimum value | Same as average value |  |
| $\begin{aligned} & +13 \text { to } \\ & +15 \end{aligned}$ | Range | Same as average value |  |
| $\begin{aligned} & +16 \text { to } \\ & +18 \end{aligned}$ | Standard deviation | Same as average value |  |

Note The number of digits of the Decimal portion is fixed to 4 digits. If a deviation calculation results in a value with 5 decimal places, it will be stored with one digit overflowing into the integer portion.
Examples: The value -0.1234 is stored as follows:
Area of decimal portion: 1234; Area of integer portion: 0000; Sign area: F000 The value -0.12345 is stored as follows:
Area of decimal portion: 2345; Area of integer portion: 0001; Sign area: F000

## Memory Switch Set 1 (3000-series, High-speed Type) (Sequence No. 421)

This sequence sets memory switches.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 data | Number of send data words |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | W | X | Y | Z |
| +2 | (Undefined) |  |  | V |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0003 (fixed) |
| +1 | w (1 digits BCD) | 0 : For single run or zero run measurement start displaying '- .' <br> 1: For single run or zero run measurement start displaying the previous measured value |
|  | x (1 digit BCD) | 0: Perform single run measurement to the RUN signal of I/O IF <br> 1: Repeat measurement while the RUN signal of I/O IF is input |
|  | y (1 digit BCD) | $\begin{aligned} & \text { *0: RS-232C Delimiter CR+LF } \\ & \text { 1: RS-232C Delimiter CR } \\ & \text { 2: RS-232C Delimiter LF } \end{aligned}$ |
|  | z (1 digit BCD) | 0: RS-232C no parity check <br> 1: RS-232C odd parity check <br> 2: RS-232C even parity check |
| +2 | v (1 digit BCD) | 0 : Displaying 'Err-0' <br> 1 : Displaying ' 0 ' |

Note Settings marked with asterisks are required for this protocol.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Memory switches cannot be set when DIP switch SW3, pin 5 of the Laser Micrometer is not turned ON.
2. The setting $(y, z)$ of RS-232C takes effect when the power supply is turned back on.

## Memory Switch Set 2 (3000-series, High-speed Type) (Sequence No. 422)

This sequence sets memory switches.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 data$+1$ | Number of send data words |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | W | X | Y | Z |
| +2 | (Undefined) |  |  | V |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0003 (fixed) |
| +1 | w (1 digit BCD) | $0:$ Work automatic detection is not performed <br> $1:$Work automatic detection is performed <br> Diameter detection method (1 scan) <br> 2: Work automatic detection is performed <br> Diameter detection method (8 scan) <br> 3: Work automatic detection is performed <br> Position detection method (1 scan) |

Note Settings marked with asterisks are required for this protocol.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note Memory switches cannot be set when DIP switch SW3, pin 5 of the Laser Micrometer is not turned ON.

## Simple AVG Times Set (3000-series, High-speed Type)

## (Sequence No. 423)

This sequence uses the simple average as the averaging method and sets the averaging times per measurement interval 4.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send +0

|  | Number of send data words |
| :---: | :---: |
|  | Number of averaging times |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0002 (fixed) |
| +1 | Number of averaging times <br> (4 digits BCD) | 1 to 2048 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note This sequence cannot be used when DIP switch SW3, pin 5 of the Laser Micrometer is not turned ON.

## AVG Move Interval Set (3000-series, High-speed Type) (Sequence No. 424)

This sequence uses the average move as the averaging method and sets the measurement interval number.
Send Data Word Allocation (2nd Operand of PMCR)


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Measurement interval number <br> (1 digit BCD) | 1 to 4 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note This sequence cannot be used when DIP switch SW3, pin 5 of the Laser Micrometer is not turned ON.

## AVG Move (H) Times Set (3000-series, High-speed Type) (Sequence No. 425)

This sequence uses the average move and high-speed data output as the averaging method and sets the averaging times per measurement interval 4.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Number of averaging times <br> (4 digits BCD) | 16 to 2048 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note This sequence cannot be used when DIP switch SW3, pin 5 of the Laser Micrometer is not turned ON.

## AVG Move (L) Times Set (3000-series, High-speed Type) <br> (Sequence No. 426)

This sequence uses the average move and low-speed data output as the averaging method and sets the averaging times per measurement interval 4.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 | Number of send data words |  |
| :--- | ---: | :--- |
|  |  |  |
| data | Number of averaging times |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Number of averaging times <br> (4 digits BCD) | 32 to 2048 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.
Note This sequence cannot be used when DIP switch SW3, pin 5 of the Laser Micrometer is not turned ON.

## Automatic Detection Set (3000-series, High-speed Type) (Sequence No. 427)

This sequence sets the work automatic detection function.

## Send Data Word Allocation (2nd Operand of PMCR)

Receive data storage words

| +0 | Number of send data words |  | Detection lower limit |
| :---: | :---: | :---: | :---: |
| +1 | (Undefined) | The number of measuring times |  |
| +2 | Invalid time |  |  |
| +3 | Decimal portion |  |  |
| +4 | (Undefined) | Integer portion |  |
| +5 | Sign | (Undefined) |  |
| +6 |  | Decimal portion |  |
| +7 | (Undefined) | Integer portion | Detection upper limit |
| +8 | Sign | (Undefined) |  |


| Offset | Contents (data format) | Data |  |  |
| :---: | :---: | :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0009 (fixed) |  |  |
| +1 | Number of measurements (3 digits BCD) | 001 to 999 |  |  |
| +2 | Invalid time (4 digits BCD) | 0001 to 9999 |  |  |
| +3 | Detection lower limit (decimal portion) <br> (4 digits BCD) | 0000 to 9999 | Example -123.4567 |  |
|  |  |  | +3 | 4567 |
| +4 | Detection lower limit | 000 to 999 | +4 | 0123 |
|  | (integer portion) <br> (3 digits BCD) |  | +5 | 2D00 |
| +5 | Detection lower limit (Sign) (ASCII 1 character) |  |  |  |
| $\begin{aligned} & +6 \text { to } \\ & +8 \end{aligned}$ | Detection upper limit | Same as detection lower limit |  |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.
Note This sequence cannot be used when DIP switch SW3, pin 5 of the Laser Micrometer is not turned ON.

## Automatic Detection Release (3000-series, High-speed Type) (Sequence No. 428)

This sequence releases the setting of work automatic detection function.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.
Note This sequence cannot be used when DIP switch SW3, pin 5 of the Laser Micrometer is not turned ON.

## Automatic Detection List Request (3000-series, High-speed Type) (Sequence No. 429)

This sequence requests the settings of work automatic detection function.
Send Data Word Allocation (2nd Operand of PMCR)
None.

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words



Note This sequence cannot be used when DIP switch SW3, pin 5 of the Laser Micrometer is not turned ON.

## 3Z4L Initialize (3000-series) (Sequence No. 430)

This sequence clears the $3 Z 4 \mathrm{~L}$, sets the mm unit, sets memory switches, does not process statistics, and clears the statistic memory.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of sequence No. 401 (Memory Switch Setting)
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Measurement Condition Set (4000-series) (Sequence No. 431)

This sequence sets measurement conditions. Conditions to be set can be selected by setting Yes/No flags.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |  |  |
| :---: | :---: | :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0025 (fixed) |  |  |
| +1 | Segment number (1 digit BCD) | 1 to 5 |  |  |
| +2 | Measurement interval number (1 digit BCD) | 1 to 7 |  |  |
| +3 | Lower limit value (Decimal portion) <br> (4 digits BCD) | 0000 to 9999 | $\begin{aligned} & \text { Example-123.4567 } \\ & + 3 \longdiv { 4 5 6 7 } \end{aligned}$ |  |
| +4 | Lower limit value (integer portion) (3 digits BCD) | 000 to 999 | +4 +5 | $\begin{array}{\|l\|} \hline 0123 \\ \hline 2000 \end{array}$ |
| +5 | Lower limit value (Sign) (ASCII 1 character) | $\begin{aligned} & \text { If }+ \text { : } 20\left({ }^{(‘)}\right) \\ & \text { If }-: 2 D\left({ }^{(‘-)}\right. \end{aligned}$ |  |  |
| $\begin{aligned} & +6 \text { to } \\ & +8 \end{aligned}$ | Upper limit value | Same as lower limit value |  |  |
| $\begin{aligned} & +9 \text { to } \\ & +11 \end{aligned}$ | Reference value | Same as lower limit value |  |  |
| +12 | Analog output scale number (1 digit BCD) | 0 to 3 |  |  |
| $\begin{aligned} & +13 \text { to } \\ & +15 \end{aligned}$ | Unused |  |  |  |
| +16 | Data output conditions (1 digit BCD) | 0 to 6 |  |  |
| +17 | Data output timer value ( 3 digits BCD) | 000 to 999 |  |  |
| +18 | Number of seconds for latch timer <br> (2 digits BCD) | 00 to 99 |  |  |
| +19 | Yes/No for segment setting (1 digit BCD) | Set: ${ }^{1(\mathrm{SG})}$ Don't set: 0 |  |  |
| +20 | Yes/No for measurement interval number setting (1 digit BCD) | Set: ${ }^{1(\mathrm{M})}$Don't set: 0 |  |  |
| +21 | Yes/No for upper/lower limit value setting <br> (1 digit BCD) | $\begin{aligned} & \text { Set: } \quad 1(\text { LL, LH }) \\ & \text { Don't set: } 0 \end{aligned}$ |  |  |
| +22 | Yes/No for reference setting (1 digit BCD) | Set: ${ }^{1(R E F, ~ S C L)}$Don't set: 0 |  |  |
| +23 | Yes/No for data output condition setting (1 digit BCD) | Set: ${ }^{1(P R, ~ P R T)}$Don't set: 0 |  |  |
| +24 | Yes/No for latch timer setting (1 digit BCD) | Set: ${ }^{1(R L T)}$Don't set: 0 |  |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. The following settings must be made together with this sequence; they cannot be set separately.
Lower limit, upper limit
Reference value, data output timer
Data output conditions, scheduled print timer
2. The limit value and reference value can be set to 3 digits for the integer portion and to 4 digits for the decimal portion.

## Measurement Condition Release (4000-series) (Sequence No. 432)

This sequence clears the measurement conditions that have been set.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of sequence No. 431 (Measurement Condition Setting). However, only the setting Yes/No flags at +19 to +24 from the send data leading word can be used.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. The following conditions are used when the measurement conditions are released: Segment becomes 1 and the measurement interval becomes 1 .
2. The following settings cannot be cleared separately using this sequence. They all must be cleared at the same time.

Lower limit, Upper limit
Data output conditions, Scheduled print timer
The scale (SCL) and data output timer (PRT) cannot be cleared.
3. This sequence can be used for the 3Z4L-4000 Series only when pin 8 on DIP switch SW2 is turned ON.

## Measurement Condition List Request (4000-series) (Sequence No. 433)

This sequence requests the measurement condition settings that have been set and other settings.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |  |
| :---: | :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0019 (fixed) |  |
| +1 | Segment number (1 digit BCD) | 1 to 5 |  |
| +2 | Measurement interval number ( 1 digit BCD ) | 1 to 7 |  |
| +3 | Lower limit value (Decimal portion) <br> ( 4 digits BCD) | 0000 to 9999 | $\text { Example - } 123.4567$ |
| +4 | Lower limit value (Integer portion) <br> (3 digits BCD) | 000 to 999 | +4 0123 <br>  F 000 |
| +5 | Lower limit value (Sign) (BIN) | $\begin{aligned} & \text { If }+: 0 \\ & \text { If }-: \text { F } \end{aligned}$ |  |
| $\begin{aligned} & \hline \begin{array}{l} +6 \text { to } \\ +8 \end{array} \\ & \hline \end{aligned}$ | Upper limit value | Same as lower limit value |  |
| $\begin{aligned} & +9 \text { to } \\ & +11 \end{aligned}$ | Reference value | Same as lower limit value |  |
| +12 | Analog output scale number (1 digit BCD) | 0 to 3 |  |
| $\begin{aligned} & +13 \text { to } \\ & +15 \end{aligned}$ | Forced zero number (ASCII 5 characters) | 5A45524F2B ("ZERO+") 4E4F524D20 ("NORM ") 5A45524F2D ("ZERO-") |  |
| +16 | Data output condition (1 digit BCD) | 0 to 6 |  |
| +17 | Data output timer value (3 digits BCD) | 000 to 999 |  |
| +18 | Number of seconds for latch timer <br> (2 digits BCD) | 00 to 99 |  |

Note This sequence can be used for the 3Z4L-4000 Series only when pin 8 on DIP switch SW2 is turned ON.

## Single Run Measurement Start (4000-series) (Sequence No. 434)

When the sample measurement condition is from 1 to 999 , this sequence performs a single run measurement and requests the measurement results.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
Receive data storage words



## Deflection Measurement Start (4000-series) (Sequence No. 435)

This sequence starts a deflection measurement.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

## None.

Note The deflection measurement keeps measuring until sequence No. 438 (Measurement Termination) is executed.

## Continuous Measurement Start (Scan) (4000-series) (Sequence No. 436)

This sequence starts a continuous measurement. The scan notification method is used for the receive data.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of sequence No. 434 (Single Run Measurement Start).
Note 1. Since this sequence repeats itself within the sequence, once it is executed, it remains in the execution state until cancelled.
2. Even if execution is cancelled, the Laser Micrometer still keeps measuring. Execute sequence No. 438 (Measurement Termination) to end the sequence.

## Continuous Measurement Start (Interrupt) (4000-series) (Sequence No. 437)

This sequence starts a continuous measurement. The interrupt notification method is used for the receive data and the interrupt No. is 101.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of sequence No. 434 (Single Run Measurement Start).
Note 1. Since this sequence repeats itself within the sequence, once it is executed, it remains in the execution state until cancelled.
2. Even if execution is cancelled, the Laser Micrometer still keeps measuring. Execute sequence No. 438 (Measurement Termination) to end the sequence.

## Continuous Measurement Termination (4000-series) (Sequence No. 438)

This sequence terminates continuous measurement.
Send Data Word Allocation (2nd Operand of PMCR) None.
Receive Data Word Allocation (3rd Operand of PMCR)
For continuous measurement: None.
For Deflection Measurement
The receive data word allocation is similar to that of sequence No. 434 (Single Run Measurement Start).

## Data Request (4000-series) (Sequence No. 439)

This sequence requests display data in the idle measurement status or latch data generated by the measurement command.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
The receive data word allocation is similar to that of sequence No. 434 (Single Run Measurement Start).

## Forced Positive Zero (4000-series) (Sequence No. 440)

This sequence sets the forced zero direction to positive (+)
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR) None.

## Forced Negative Zero (4000-series) (Sequence No. 441)

This sequence sets the forced zero direction to negative (-)
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Forced Zero Release (4000-series) (Sequence No. 442)

This sequence releases the forced zero direction.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## 3Z4L Initialize (4000-series) (Sequence No. 443)

This sequence clears the $3 Z 4 \mathrm{~L}$, sets the mm unit, and sets memory switches.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of sequence No. 401 (Memory Switch Setting).
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## General-purpose Command 1 (4000-series) (Sequence No. 444)

This general-purpose command is used to send data with a specified data length, and receive back only OK. The terminator (CR) is automatically attached to the send data.

## Send Data Word Allocation (2nd Operand of PMCR)



Receive Data Word Allocation (3rd Operand of PMCR)
None.

## General-purpose Command 2 (4000-series) (Sequence No. 445)

This general-purpose command is used to send data with a specified data length, and receive back receive data other than OK. The terminator (CR) is automatically attached to the send data.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0003 to 0129 |
| +1 | Send data byte length <br> (4 digits BCD) | 0001 to 0255 <br> The number of bytes of send data <br> excluding the terminator (CR) |
| +2 to | Send data (ASCII) | Send data up to 255 bytes maximum <br> Specify in ASCII. |
| +129 |  |  |

Receive Data Word Allocation (3rd Operand of PMCR)
Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0001 to 0128 |
| +1 to | Receive data (ASCII) | When the receive data exceed 254 bytes, <br> only 254 bytes are stored. |
| 127 |  |  |

# Appendix J <br> Visual Inspection System Protocol 

The Visual Inspection System Protocol is used to make various settings or control remotely the Visual Recognition Device connected to the Communications Board via RS-232C cable.

## Protocol Configuration

The configuration of the Visual Inspection System Protocol is shown below.

| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 450 | Measurement execution (F200) | Carries out one measurement one and stores the measurement results in the specified words. | No | Yes |
| 451 | Continuous measurement execution (scan) (F200) | Carries out continuously setting the F200 and storing the measurement results in the specified words. | No | Yes |
| 452 | Continuous measurement execution (interrupt) (F200) | Carries out continuously setting the F200 and storing the measurement results in the specified words. | No | Yes |
| 453 | Reference object registration (group) (F200) | Performs reference position registration and evaluation criterion registration at the same time. | No | No |
| 454 | Reference object registration (reference position) (F200) | Registers the reference position for measuring the amount of position displacement when a position displacement compensation is used. | No | No |
| 455 | Reference object registration (evaluation criterion) (F200) | Registers the reference value to discriminate the output format. | No | No |
| 456 | Evaluation condition change (F200) | Changes the upper and lower limit values of the evaluation condition of the designated output No. | Yes | No |
| 457 | Arbitrary measurement value acquisition (F200) | Stores the measurement values of arbitrary measurement item regardless of output format in the specified words. | Yes | Yes |
| 460 | Measurement execution (F300) | Carries out one measurement and stores the measurement results in the specified words. | No | Yes |
| 461 | Continuous measurement execution (scan) (F300) | Carries out continuously setting the F300 and storing the measurement results in the specified words. | No | Yes |
| 462 | Continuous measurement execution (interrupt) (F300) | Carries out continuously setting the F300 and storing the measurement results in the specified words. | No | Yes |
| 463 | Reference object registration command 1 execution (F300) | Performs a measurement for the input image and updates the reference object data of the full window. | No | No |
| 464 | Reference object registration command 2 execution (F300) | Performs a measurement for the input image and updates the reference object data of the full window | Yes | No |
| 465 | Illumination fluctuation follow execution (F300) | Executes an illumination fluctuation follow. | No | No |
| 470 | Measurement execution and positioning (F350) | Carries out one measurement and stores the measurement results in the specified words. | No | Yes |


| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 471 | Camera designation and positioning (F350) | Designates the camera for measurement. | Yes | No |
| 472 | Scene switching and positioning (F350) | Switches to a designated scene No. | Yes | No |
| 473 | Inspection execution and character inspection (F350) | Carries out one inspection and outputs inspection results to the video monitor. | No | No |
| 474 | Character string inspection and character inspection (F350) | Changes the inspection character string of a designated inspection area No. to a designated character string. | Yes | No |
| 480 | Camera change (decrease by 1) (F200/300) | Decreases the display camera No. by 1. | No | No |
| 481 | Camera change (increase by 1) (F200/300) | Increases the display camera No. by 1. | No | No |
| 482 | Binary level modification (F200/300) | Modifies the binary levels (upper limit and lower limit values) of a designated window number No. | Yes | No |
| 483 | Reset (F200/300) | Resets the F200/F300. | No | No |
| 490 | Scene switch (decrease by 1) | Decreases the scene No. by 1. | No | No |
| 491 | Scene switch (increase by 1) | Increases the scene No. by 1. | No | No |
| 492 | Scene switch (arbitrary) | Switches to a designated scene No. | Yes | No |
| 493 | Measurement, inspection termination | Terminates the measurement and returns to the home menu. | No | No |
| 494 | General-purpose command (send) | Sets and executes commands that are otherwise not supported. | Yes | No |
| 495 | General-purpose command (send/receive) | Sets and executes commands that are otherwise not supported. | Yes | Yes |

## Note Ladder Interface Settings

YES: User settings are required for the 2nd and 3rd operands of PMCR.
NO: Send word allocation: Receive word allocation: Set the constant 0000 for the 2rd operand (S).

## Connections

The connections for using the Visual Inspection System Protocol are shown below.

## RS-232C Connections



| Pin No. | Signal name | Abbreviation |
| :--- | :--- | :--- |
| 1 | Protective ground or earth | FG (GND) |
| 2 | Send data | SD (TXD) |
| 3 | Receive data | RD (RXD) |
| 4 | Request to send | RS (RTS) |
| 5 | Clear to send | CS (CTS) |
| 6 | Data set ready | DR (DSR) |
| 7 | Signal ground | SG (GND) |
| 8 | Carrier detection (Data word receive) | CD (DCD) |
| 20 | Data terminal ready | ER (DTR) |

Communications Board:
F300-E:
D-sub 9 pin (female)

| Signal Name | Pin No. |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| SD(TXD) | 2 |  | Pin No. | Signal Name |
| RD(RXD) | 3 |  | 2 | SD(TXD) |
| RS(RTS) | 4 |  | 3 | RD(RXD) |
| CS(CTS) | 5 |  | 5 | RS(RTS) |
| DR(DSR) | 7 |  | 6 | DR(CTS) |
| SG(GND) | 9 |  | 7 | SG(GND) |
| ER(DTR) | 8 |  | 8 | CD(DCD) |

## - For RS/CS Flow Control

| Communications Board: D-sub 9 pin (female) |  | $\begin{gathered} \text { F300-E: } \\ \text { D-sub } 25 \text { pin (female) } \end{gathered}$ |  |
| :---: | :---: | :---: | :---: |
| Signal Name | Pin No. | Pin No. | Signal Name |
| SD(TXD) | 2 | 2 | SD (TXD) |
| RD (RXD) | 3 | 3 | RD(RXD) |
| RS(RTS) | 4 | 4 | RS(RTS) |
| CS(CTS) | 5 | 5 | CS(CTS) |
| DR(DSR) | 7 | 6 | DR(DSR) |
| SG(GND) | 9 | 7 | SG(GND) |
| ER(DTR) | 8 | 8 | CD (DCD) |
|  |  | 20 | ER(DTR) |

## Measurement Execution (F200) (Sequence No. 450)

This sequence carries out one measurement and stores the measurement results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Content (data format) | Data |  |  |
| :--- | :--- | :--- | :--- | :---: |
| +0 | $\begin{array}{l}\text { Number of receive data words } \\ \text { (4 digits BCD) }\end{array}$ | 0006 |  |  |
| +1 | Output No. (2 digits BCD) | 00 to 07 |  |  |
| +2 | Evaluation result (1 digit BCD) | $0:$ OK |  |  |
| 1: NG |  |  |  |  |$]$

Note 1. Only one output No. can be stored.
2. The ranges of measurement values are as follows:

For calibration OFF setting :-2147483.648 to 2147483.647
For calibration ON setting : -9999999.999 to 9999999.999
3. If a measurement value exceeds the range of measurement values when calibration is turned off, undefined data is stored in the specified words.

## Continuous Measurement Execution (Scan) (F200) (Sequence No. 451)

This sequence carries out continuously the setting of the F200 and stores measurement results in the specified words. The scan notification method is used for the receive data.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| Offset | Content (data format) | Data |  |  |
| :--- | :--- | :--- | :--- | :---: |
| +0 | Number of receive data words <br> (4 digits BCD) | 0006 |  |  |
| +1 | Output No. (2 digits BCD) | 00 to 07 |  |  |
| +2 | Evaluation result (1 digit BCD) | $0:$ OK |  |  |
|  |  | $1:$ NG |  |  |

Note 1. Only one output No. can be designated.
2. Turn OFF CIO 28911 (if port A is used) or CIO 28915 (if port B is used) to terminate this sequence.
3. The ranges of measurement values are as follows:

For calibration OFF setting : -2147483.648 to 2147483.647
For calibration ON setting : -9999999.999 to 9999999.999
4. If a measurement value exceeds the range of measurement values when calibration is turned off, undefined data is stored in the specified words.

## Continuous Measurement Execution (Interrupt) (F200) (Sequence No. 452)

This sequence carries out continuously setting the F200 and stores measurement results in the specified words. The interrupt notification method is used for the receive data. The interrupt No. is 102.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Content (data format) | Data |  |
| :--- | :--- | :--- | :--- |
| +0 | Number of receive data words <br> ( 4 digits BCD) | 0006 |  |
| +1 | Output No. (2 digits BCD) | 00 to 07 |  |
| +2 | Evaluation result (1 digit BCD) | $0:$ OK |  |
|  |  | $1:$ NG |  |

Note 1. Only one output No. can be designated.
2. Turn OFF CIO 28911 (if port A is used) or CIO 28915 (if port B is used) to terminate this sequence.
3. The ranges of measurement values are as follows:

For calibration OFF setting :-2147483.648 to 2147483.647
For calibration ON setting : -9999999.999 to 9999999.999
4. If a measurement value exceeds the range of measurement values when calibration is turned off, undefined data is stored in the specified words.

## Reference Object Registration (Group) (F200)

## (Sequence No. 453)

This sequence performs reference position registration and criterion registration at the same time.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Reference Object Registration (Reference Position) (F200) (Sequence No. 454)

This sequence registers the reference position for measuring the amount of position displacement when a position displacement compensation is used.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Reference Object Registration (Criterion) (F200) (Sequence No. 455)

This sequence registers a reference value to discriminate the output format.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Evaluation Condition Change (F200) (Sequence No. 456)

This sequence changes the upper and lower limit values of evaluation condition of the designated output No.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Content (data format) | Data |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0010 |  |  |  |
| +1 | Output No. (2 digits BCD) | 00 to 07 |  |  |  |
| $\begin{aligned} & +2 \text { to } \\ & +5 \end{aligned}$ | Upper limit value (decimal portion) (3 digits BCD) | $\begin{aligned} & \text { Example } \\ & -123.456 \end{aligned}$ |  | Example$+123.456$ |  |
|  | Upper limit value (integer portion) | $\begin{aligned} & +2 \\ & +3 \\ & +4 \\ & +5 \end{aligned}$ | 0567 | $\begin{aligned} & +2 \\ & +3 \\ & +4 \\ & +5 \end{aligned}$ | 0678 |
|  | (7 digits BCD) |  | 1234 |  | 2345 |
|  | Upper limit value (sign) (ASCII 2 digits) |  | 0000 |  | 0001 |
|  |  |  | 2D00 |  | 3000 |
| $\begin{aligned} & +6 \text { to } \\ & +9 \end{aligned}$ | Lower limit value (decimal portion) (3 digits BCD) | Same as upper limit. |  |  |  |
|  | Lower limit value (integer portion) ( 7 digits BCD) |  |  |  |  |  |
|  | Lower limit value (sign) (ASCII 2 digits) |  |  |  |  |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Only one output No. can be designated.
2. Enter values so that upper limit $\geq$ lower limit.
3. Enter upper limit and lower limit values within the range -2147483.648 to 2147483.648.

## Arbitrary Measurement Value Acquisition (F200) (Sequence No. 457)

This sequence stores measurement values of arbitrary measurement items regardless of output format in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Data 1 |
| +2 | (Undefined) | Data 2 |
|  |  |  |


| Offset | Content (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0003 |
| +1 | Data 1 (2 digits BCD) | 00: Area <br> 01: Center of gravity x <br> 02: Center of gravity y <br> 03: Main axis angle <br> 04: Output format <br> 05: Reference value of output format <br> 06: X displacement <br> 07: Y displacement <br> 08: Angle displacement <br> 09: X reference position <br> 10: Y reference position <br> 11: Angle reference position |
| +2 | Data 2 (2 digits BCD) | When 00 to 03 is set to data 1 Window No.: 00 to 07 <br> When 04 to 05 is set to data 1 Output No.: 00 to 07 <br> When 06 to 11 is set to data 1 Camera No.: 00 to 01 |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words



Note 1. Only one output No. can be designated.
2. Measurement is not performed with this command. The measurement results of the last measurement will be stored in the specified words.
3. This command can acquire only the measurement value of the window No. set by output format.
4. For data 1 and 2 , the receive data is compared with the send data. If the receive data is not the same as the send data, CIO 28909 (if port A is used) or CIO 28913 (if port B is used) will turn ON.
5. The ranges of measurement values are as follows:

For calibration OFF setting : -2147483.648 to 2147483.647
For calibration ON setting : -9999999.999 to 9999999.999
6. If a measurement value exceeds the range of measurement values when calibration is turned off, unexpected data is stored in the specified words.

## Measurement Execution (F300) (Sequence No. 460)

This sequence carries out one measurement and stores measurement results in the specified words

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Content (data format) | Data |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0006: 1 measurement item <br> 0009: 2 measurement items <br> 0012: 3 measurement items <br> 0015: 4 measurement items <br> 0018: 5 measurement items |  |  |  |
| +1 | Window number (2 digits BCD) | 00 to 07 |  |  |  |
| +2 | Evaluation result (1 digit BCD) | $\begin{array}{ll} 0: & \text { OK } \\ 1: & \text { NG } \end{array}$ |  |  |  |
| $\begin{aligned} & \hline+3 \text { to } \\ & +5 \end{aligned}$ | Measurement value (decimal portion) (3 digits BCD) | Example Example <br> -123.456 +123.456 |  |  |  |
|  | Measurement value (integer portion) | +3 3456 |  |  | 345 |
|  | (7 digits BCD) | $\begin{aligned} & +4 \\ & +5 \end{aligned}$ | 0012 | +4 | 001 |
|  | $\begin{aligned} & \text { Measurement value (sign) } \\ & \text { (1 digit) } \end{aligned}$ |  | $\frac{\text { F000 }}{\text { s store }}$ |  |  |
| $\begin{aligned} & +6 \text { to } \\ & +8 \end{aligned}$ | Same as +3 to +5 . | Same as +3 to +5 . |  |  |  |
| $\begin{aligned} & +9 \text { to } \\ & +11 \end{aligned}$ | Same as +3 to +5 . | Same as +3 to +5. |  |  |  |
| $\begin{aligned} & +12 \text { to } \\ & +14 \end{aligned}$ | Same as +3 to +5. | Same as +3 to +5 . |  |  |  |
| $\begin{aligned} & +15 \text { to } \\ & +17 \end{aligned}$ | Same as +3 to +5 . | Same as +3 to +5 . |  |  |  |

Note 1. Exponential expressions are used for numbers larger than 9999999.999 and smaller than -999999.9.
2. The number of measurement items is up to 5 , but only one window number can be read.
3. The ranges of measurement values are as follows:

For calibration OFF setting :-2147483.648 to 2147483.648
For calibration ON setting : -9999999.999 to 9999999.999
4. The priority of measurement items being output are as follows:

Area
Center of gravity X , Center of gravity Y
Displacement in center of gravity X (reserved), displacement in center of gravity Y (reserved)
Main axis angle
Main axis angle aberration (reserved)
Edge angle
Edge angle (reserved)
Center $X$, center $Y$
Center X aberration (reserved), center Y aberration (reserved)
Inclination
Inclination aberration (reserved)
Intersecting point $X$, intersecting point $Y$
Intersecting point $X$ aberration (reserved), intersecting point $Y$ aberration (reserved)

## Continuous Measurement Execution (Scan) (F300) (Sequence No. 461)

This sequence carries out continuously the settings of F300 and stores measurement results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


Note 1. Exponential expressions are used for numbers larger than 9999999.999 and smaller than -999999.9.
2. The number of measurement items are up to 5 , but only one window number can be read.
3. The range of measurement values are as follows:

For calibration OFF setting :-2147483.648 to 2147483.648
For calibration ON setting : -9999999.999 to 9999999.999
4. The priority order of measurement items being output are as follows:

Area
Center of gravity X, Center of gravity Y
Displacement in center of gravity X (reserved), displacement in center of gravity Y (reserved)
Main axis angle

Main axis angle aberration (reserved)
Edge angle
Edge angle (reserved)
Center $X$, center $Y$
Center X displacement (reserved), center Y displacement (reserved)
Inclination
Inclination displacement (reserved)
Intersecting point X , intersecting point Y
Intersecting point X displacement (reserved), intersecting point Y displacement (reserved)

## Continuous Measurement Execution (Interrupt) (F300) (Sequence No. 462)

This sequence carries out continuously setting the F300 and stores measurement results in the specified words. The interrupt notification method is used for the receive data. The interrupt No. is 102.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)




Note 1. Exponential expressions are used for numbers larger than 9999999.999 and smaller than -999999.9.
2. The number of measurement items is up to 5 , but only one window number can be read.
3. The ranges of measurement values are as follows:

For calibration OFF setting :-2147483.648 to 2147483.648
For calibration ON setting : -9999999.999 to 9999999.999
4. The priority of measurement items being output are as follows:

Area
Center of gravity X, Center of gravity Y
Displacement in center of gravity X (reserved), displacement in center of gravity Y (reserved)
Main axis angle
Main axis angle displacement (reserved)
Edge angle
Edge angle(reserved)
Center X, center Y
Center X displacement (reserved), center Y displacement (reserved)
Inclination
Inclination displacement (reserved)
Intersecting point $X$, intersecting point $Y$
Intersecting point X displacement (reserved), intersecting point Y displacement (reserved)

## Reference Object Registration Command 1 Execution (F300) (Sequence No. 463)

This sequence performs a measurement for the input image and updates reference object data of the full window.

## Send Data Word Allocation (2nd Operand of PMCR)

None.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Reference Object Registration Command 2 Execution (F300) (Sequence No. 464)

This sequence performs a measurement for the input image and updates the reference object data of a designated window.
Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 | Number of send data words |  |  |
| :--- | ---: | ---: | ---: |
| data | +1 | (Undefined) | Window No. |
|  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 |
| +1 | Window No. (2 digits BCD) | 00 to 07 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Illumination Fluctuation Follow Execution (F300) (Sequence No. 465)

This sequence executes an illumination fluctuation follow.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Measurement Execution and Positioning (F350) (Sequence No. 470)

This sequence carries out one measurement and stores the measurement results in the specified words.

## Send Data Word Allocation (2nd Operand of PMCR)

None.
Receive Data Word Allocation (3rd Operand of PMCR)

| +0 | Number of receive data words |  |  | X displacement |
| :---: | :---: | :---: | :---: | :---: |
| +1 |  |  | Decimal portion |  |
| +2 | Sign |  | Integer portion |  |
| +3 |  |  | Decimal portion |  |
| +4 | Sign |  | Integer portion | displacement |
| +5 |  |  | Decimal portion |  |
| +6 | Sign | 0 | Integer portion | ,ion v |


| Offset | Content (data format) | Data |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| +0 | Number of receive data words | 0007 |  |  |  |
| $\begin{aligned} & +1 \text { to } \\ & +2 \end{aligned}$ | X displacement (decimal portion) <br> (3 digits BCD) | Example <br> -123.456 |  | Example <br> +123.456 |  |
|  | X displacement (integer portion) ( 3 digits BCD) | $\begin{aligned} & +1 \\ & +2 \end{aligned}$ | 3456 | $\begin{aligned} & +1 \\ & +2 \end{aligned}$ | 3456 |
|  | $X$ displacement (sign) (1 digit) (See note.) |  | $F$ is stored for negative values. |  |  |
| $\begin{aligned} & +3 \text { to } \\ & +4 \end{aligned}$ | Y displacement (decimal portion) (3 digits BCD) | $\begin{aligned} & \text { Example } \\ & -123.456 \end{aligned}$ |  | $\begin{aligned} & \text { Example } \\ & +123.456 \end{aligned}$ |  |
|  | Y displacement (integer portion) (3 digits BCD) | $\begin{aligned} & +1 \\ & +2 \end{aligned}$ | 3456 | $\begin{aligned} & +1 \\ & +2 \end{aligned}$ | 3456 |
|  | Y displacement (sign) (1 digit) (See note.) |  | $F$ is stored for negative values. |  |  |
| $\begin{aligned} & \hline+5 \text { to } \\ & +6 \end{aligned}$ | Correlation value (decimal portion) (3 digits BCD) | $\begin{aligned} & \text { Example } \\ & -12.345 \end{aligned}$ |  | $\begin{aligned} & \text { Example } \\ & +12.345 \end{aligned}$ |  |
|  | Correlation value (integer portion) (3 digits BCD) |  | $2345$ | $\begin{aligned} & +1 \\ & +2 \end{aligned}$ | 2345 |
|  | Correlation value (sign) (1 digit) (See note.) |  | $\frac{\text { F001 }}{\text { is store }}$ |  | e values. |

Note 1. The number of models that can be stored in a designated word is 1.
2. If a measurement is carried out without executing a camera designation, a measurement is executed for all cameras in which the measurement model is registered.
3. When the correlation value is less than 70 and the measurement value overflows, CIO 28909 (if port A is used) or CIO 28913 (if port B is used) will turn ON.
4. Data to be output is within the range 999.999 (upper limit) to -999.999 (lower limit).
5. Retry processing is not performed for this sequence.
6. Turn the Abort Bit ON and then OFF to end this sequence.

## Camera Designation and Positioning (F350) (Sequence No. 471)

This sequence designates the cameras for measurement.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

| Number of send data words |  |  |
| :--- | :--- | :--- |
|  |  |  |
|  | (Undefined) | First camera |
| +2 | No. |  |
|  | (Undefined) | Last No.era |


| Offset | Content (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digit BCD) | 0003 |
| +1 | First camera No. (1 digit BCD) | 0 to 7 |
| +2 | Last camera No. (1 digit BCD) | 0 to 7 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Set values so that the first camera No.< last camera No.
2. If a designated camera No. is abnormal, ClO 28909 (if port A is used) or CIO 28913 (if port B is used) will turn ON .

## Scene Switching and Positioning (F350) (Sequence No. 472)

This sequence switches to a designated scene No.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of
send data

| +0 | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) |  |
|  | Scene No. |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 |
| +1 | Scene No. (2 digits BCD) | 00 to 15 |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. If a scene No. is abnormal, CIO 28909 (if port A is used) or CIO 28913 (if port B is used) will turn ON .
2. Retry processing is not performed for this sequence.
3. Turn the Abort Bit ON and then OFF to end this sequence.

## Inspection Execution and Character Inspection (F350) (Sequence No. 473)

This sequence carries out one inspection and outputs the inspection results to a video monitor.
Send Data Word Allocation (2nd Operand of PMCR)
None.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.

## Character String Inspection and Character Inspection (F350) (Sequence No. 474)

This sequence changes the inspection character string of a designated inspection area No. to a designated character string.
Send Data Word Allocation (2nd Operand of PMCR)


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 to 0015 |
| +1 | Number of designated character <br> strings (4 digits BCD) | 0 to 24 |
| +2 | Inspection area No. <br> (2 digits BCD) | 00 to 07 |
| +3 to | Number of designated character <br> strings (ASCII) |  |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Camera Change (Decrease by 1) (F200/300) (Sequence No. 480)

This sequence decreases the display camera No. by 1.

[^1]
## Camera Change (Increase by 1) (F200/300) (Sequence No. 481)

This sequence increases the display camera No. by 1.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Binary Level Modification (F200/300) (Sequence No. 482)

This sequence modifies the binary levels (upper limit and lower limit values) of a designated output No. (F200) or window number No. (F300).
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data

|  | Number of send data words |  |  |
| :--- | :--- | :--- | :---: |
|  | (Undefined) |  |  |
| or Output No. | Window No. |  |  |
| +1 | Undef limit value |  |  |
| +2 | (Undefined) | Upper |  |
|  | (Undefined) | Lower limit value |  |
|  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0004 |
| +1 | Window No. (1 digit BCD) | 0 to 7 |
| +2 | Upper limit value (3 digits BCD) | 000 to 255 |
| +3 | Lower limit value (3 digits BCD) | 000 to 255 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.
Note Enter values so that the upper limit $\geq$ lower limit.

## Reset (F200/300) (Sequence No. 483)

This sequence resets the F200/F300 (to starting status).
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Scene Switching (Decrease by 1) (Sequence No. 490)

This sequence decreases the scene No. by 1.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Scene Switching (Increase by 1) (Sequence No. 491)

This sequence increases the scene No. by 1.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Scene Switching (Arbitrary) (Sequence No. 492)

This sequence switches to a designated scene No.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data

|  | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Scene No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 |
| +1 | Scene No. (2 digits BCD) | 00 to 15 |

Receive Data Word Allocation (3rd Operand of PMCR)
None.

## Measurement, Inspection Termination (Sequence No. 493)

This sequence terminates the measurement and returns to the home menu.
Send Data Word Allocation (2nd Operand of PMCR)
None.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

## General-purpose Command (Send) (Sequence No. 494)

This sequence can set and execute commands that are not otherwise supported. The delimiter (CR+LF) is automatically attached to the send data.
Send Data Word Allocation (2nd Operand of PMCR)
First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 003 to 0129 |
| +1 | Command length (4 digits BCD) | 0001 to 0253 |
| +2 to | Command (ASCII) | Specify ASCII data. |

Receive Data Word Allocation (3rd Operand of PMCR)
None.
Note 1. The processing depends on the command.
2. For a command with a response, use sequence \#495.

## General-purpose Command (Send/Receive) (Sequence No. 495)

This sequence can set and execute commands that are not otherwise supported. The delimiter (CR+LF) is automatically attached to the send data.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of

| +0 | Number of send data words |  |
| :--- | :--- | :---: |
|  | Command length |  |
|  | (Undefined) | Command |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 to 0129 |
| +1 | Command length (4 digits BCD) | 0001 to 0253 |
| +2 to | Command (ASCII) | Specify ASCII data. |

## Receive Data Word Allocation (3rd Operand of PMCR)

The reception data is stored in the reception data words without the delimiter (CR+LF),
Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) |  |
| +1 | Command length (4 digits BCD) |  |
| +2 to | Command (ASCII) | ASCII data is returned. |

Note 1. The processing depends on the command.
2. For a command with a response, use sequence \#495.

# Appendix K V600/V620 ID Controller Protocol 

The V600/V620 ID Controller Protocol is used to make various settings or control remotely the ID Controller Connected to the Communications Board via RS-232C or RS-422A cable.

## Protocol Configuration

The configuration of the V600/V620 ID Controller Protocol is shown below.

| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 500 | Read (ASCII/1) | Used when the number of Heads to be read from the Carrier is 1 . | Yes | Yes |
| 501 | Read (ASCII/2) | Used when the number of Heads to be read from the Carrier is 2. | Yes | Yes |
| 502 | Read (ASCII/4) | Used when the maximum number of Heads to be read from the Carrier is 4 . | Yes | Yes |
| 503 | Read (ASCII/8) | Used when the maximum number of Heads to be read from the Carrier is 8 . | Yes | Yes |
| 504 | Read (Hexadecimal/1) | Used when the number of Heads to be read from the Carrier is 1 . | Yes | Yes |
| 505 | Read (Hexadecimal/2) | Used when the number of Heads to be read from the Carrier is 2 . | Yes | Yes |
| 506 | Read (Hexadecimal/4) | Used when the maximum number of Heads to be read from the Carrier is 4 . | Yes | Yes |
| 507 | Read (Hexadecimal/8) | Used when the maximum number of Heads to be read from the Carrier is 8 . | Yes | Yes |
| 508 | Auto-read (ASCII/1) | Used when the number of Heads to be read from the Carrier is 1 . | Yes | Yes |
| 509 | Auto-read (Hexadecimal/1) | Used when the number of Heads to be read from the Carrier is 1 . | Yes | Yes |
| 510 | Polling Auto-read (ASCII) | Used when the number of Heads to be read from the Carrier is from 1 to 8. | Yes | No |
| 511 | Polling Auto-read Subcommand (ASCII/2) | Used when the number of Heads to be read from the Carrier is 2. | Yes | Yes |
| 512 | Polling Auto-read Subcommand (ASCII/4) | Used when the maximum number of Heads to be read from the Carrier is 4 . | Yes | Yes |
| 513 | Polling Auto-read Subcommand (ASCII/8) | Used when the maximum number of Heads to be read from the Carrier is 8 . | Yes | Yes |
| 514 | Polling Auto-read (Hexadecimal) | Used when the number of Heads to be read from the Carrier is from 1 to 8. | Yes | No |
| 515 | Polling Auto-read Subcommand (Hexadecimal/2) | Used when the number of Heads to be read from the Carrier is 2. | Yes | Yes |
| 516 | Polling Auto-read Subcommand (Hexadecimal/4) | Used when the maximum number of Heads to be read from the Carrier is 4 . | Yes | Yes |
| 517 | Polling Auto-read Subcommand (Hexadecimal/8) | Used when the maximum number of Heads to be read from the Carrier is 8. | Yes | Yes |
| 518 | Write (ASCII/1) | Used when the number of Heads to be written to the Carrier is 1 . | Yes | No |


| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 519 | Write (ASCII/2) | Used when the number of Heads to be written to the Carrier is 2. | Yes | No |
| 520 | Write (ASCII/4) | Used when the maximum number of Heads to be written to the Carrier is 4 . | Yes | No |
| 521 | Write (ASCII/8) | Used when the maximum number of Heads to be written to the Carrier is 8 . | Yes | No |
| 522 | Write (Hexadecimal/1) | Used when the number of Heads to be written to the Carrier is 1 . | Yes | No |
| 523 | Write (Hexadecimal/2) | Used when the number of Heads to be written to the Carrier is 2. | Yes | No |
| 524 | Write (Hexadecimal/4) | Used when the maximum number of Heads to be written to the Carrier is 4 . | Yes | No |
| 525 | Write (Hexadecimal/8) | Used when the maximum number of Heads to be written to the Carrier is 8 . | Yes | No |
| 526 | Auto-write (ASCII/1) | Used when the number of Heads to be written to the Carrier is 1 . | Yes | No |
| 527 | Auto-write (Hexadecimal/1) | Used when the number of Heads to be written to the Carrier is 1 . | Yes | No |
| 528 | Polling Auto-write (ASCII/2) | Used when the number of Heads to be written to the Carrier is 2. | Yes | No |
| 529 | Polling Auto-write Subcommand (ASCII/2) | Used when the number of Heads to be written to the Carrier is 2. | Yes | No |
| 530 | Polling Auto-write (ASCII/4) | Used when the maximum number of Heads to be written to the Carrier is 4 . | Yes | No |
| 531 | Polling Auto-write Subcommand (ASCII/4) | Used when the maximum number of Heads to be written to the Carrier is 4 . | Yes | No |
| 532 | Polling Auto-write (ASCII/8) | Used when the maximum number of Heads to be written to the Carrier is 8 . | Yes | No |
| 533 | Polling Auto-write Subcommand (ASCII/8) | Used when the maximum number of Heads to be written to the Carrier is 8 . | Yes | No |
| 534 | Polling Auto-write (Hexadecimal/2) | Used when the number of Heads to be written to the Carrier is 2. | Yes | No |
| 535 | Polling Auto-write Subcommand (Hexadecimal/2) | Used when the number of Heads to be written to the Carrier is 2. | Yes | No |
| 536 | Polling Auto-write (Hexadecimal/4) | Used when the maximum number of Heads to be written to the Carrier is 4 . | Yes | No |
| 537 | Polling Auto-write Subcommand (Hexadecimal/4) | Used when the maximum number of Heads to be written to the Carrier is 4 . | Yes | No |
| 538 | Polling Auto-write (Hexadecimal/8) | Used when the maximum number of Heads to be written to the Carrier is 8 . | Yes | No |
| 539 | Polling Auto-write Subcommand (Hexadecimal/8) | Used when the maximum number of Heads to be written to the Carrier is 8 . | Yes | No |
| 540 | Data check | Writes and verify the CRC code for the check blocks designated by the user. | Yes | Yes |
| 541 | Control management | Performs I/O or an I/O read. | Yes | Yes |
| 542 | Error information read | Reads information from the latest error log. | Yes | Yes |
| 543 | Command processing cancel | Cancels command processing except polling command processing and returns to the command waiting status. | Yes | Yes |


| Sequence <br> No. | Communications <br> sequence name | Function | Ladder interface |  |
| :--- | :--- | :--- | :--- | :---: |
|  |  | Send word <br> allocation | Receive word <br> allocation |  |
| 544 | Polling auto-read <br> command proces- <br> sing cancel | Cancels polling auto-read processing. | Yes | Yes |
| 545 | Polling auto-write <br> command proces- <br> sing cancel | Cancels polling auto-write processing. | Yes | Yes |
| 546 | General-purpose <br> command | Sends arbitrary data and stores receive data <br> to receive data words. | Yes | Yes |

## Note Ladder Interface Settings

YES: User settings are required for the 2nd and 3rd operands of PMCR.
NO: Send word allocation: Set a dummy word address for the 3rd operand (D).
Receive word allocation: Set the constant 0000 for the 2rd operand (S).

## Connections

Connections when using the V600/V620 ID Controller Protocol are shown below.

## RS-232C Connections

C200HX/HG/HE


Communications Board: ID Controller (CD1D):
D-sub 9 pin (female)


Shielded cable


## RS-422A Connections



Note 1. Ground the cable shield at either the ID Controller or the Communications Board to prevent malfunction.
2. Turn ON the pin 6 on DIP switch SW6 to set the host communications procedure to the 1 -to-N procedure for 1-to-N connections.

## DIP Switch Settings

## V600/620-CD1D DIP Switches

DIP Switch 1


Not used (Always keep it OFF.)

| SW7 | Local communications mode setting |
| :---: | :--- |
| 1 | Speed priority setting |
| 0 | Distance priority setting |

- SW7 Setting

This setting is only valid if the EEPROM-type (batterylesstype) Data Carrier (DC) is accessed. The setting of SW7 does not work with the SRAM-type (battery-type) DC. SW7 must be set to OFF when the V620 is used.

| SW4 | SW5 | SW6 | Data <br> length (bit) | STOP <br> bits (bit) | Parity type |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 7 | 2 | E |
| 0 | 0 | 1 | 7 | 2 | O |
| 0 | 1 | 0 | 7 | 1 | E |
| 0 | 1 | 1 | 7 | 1 | O |
| 1 | 0 | 0 | 8 | 2 | N |
| 1 | 0 | 1 | 8 | 1 | N |
| 1 | 1 | 0 | 8 | 1 | E |
| 1 | 1 | 1 | 8 | 1 | O |

DIP Switch 2


Not used (Always keep it OFF.)

| SW6 | Communications protocol setting with host devices |
| :---: | :--- |
| 1 | 1 -to-N protocol |
| 0 | 1 -to-1 protocol |

Note When selecting the "1-to-N" protocol, setting is limited to $N=1$. In this case, the FCS check code may be added.

- ID Controller Unit Number Setting (Valid Only for 1-to-N Protocol)

| SW3 | SW4 | SW5 | Unit No. |
| :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | No. 0 |
| 0 | 0 | 1 | No. 1 |
| 0 | 1 | 0 | No. 2 |
| 0 | 1 | 1 | No. 3 |
| 1 | 0 | 0 | No. 4 |
| 1 | 0 | 1 | No. 5 |
| 1 | 1 | 0 | No. 6 |
| 1 | 1 | 1 | No. 7 |

Note 1. Be careful not to set to the same unit number twice.
2. Set them to OFF for the 1-to-1 protocol.

| SW1 | SW2 | Synchronous condition |
| :---: | :---: | :--- |
| 0 | 0 | OFF (LL level) |
| 0 | 1 | ON (HL level) |
| 1 | 0 | Trailing edge |
| 1 | 1 | Leading edge |

## V600-CA $\square$ A DIP Switches


$\begin{aligned} \text { Note } \quad \text { 1. } & \begin{array}{l}\text { Data length setting } \\ 7 \text { bits: ASCII code } \\ \\ 8 \text { bits: JIS8 unit code }\end{array}\end{aligned}$
2. Parity setting

E: Even parity
O: Odd parity
N : No parity designation

## DIP Switch 2



- SW8: Receive Side Terminal Resistance Setting (Valid Only for the V600-CA2A)

| 1 | Connected (ID Controller send side) |
| :---: | :--- |
| 0 | Not connected |

- SW7: Receive Side Terminal Resistance Setting (Valid Only for the V600-CA2A)

| 1 | Connected (ID Controller receive side) |
| :---: | :--- |
| 0 | Not connected |

- SW6: Communications Protocol Setting

| 1 | 1-to-N protocol |
| :--- | :--- |
| 0 | 1-to-1 protocol |

- ID Controller Unit Number Setting (Valid Only for the 1-to-N Protocol)
- Local Communications Mode Setting

| 1 | Speed priority setting |
| :--- | :--- |
| 0 | Distance priority setting |

- SW1 Setting

This setting is only valid if the EEPROM-type (battery-less-type) Data Carrier (DC) is accessed. The setting of SW7 does not work with the SRAM-type (batterytype) DC.

- SW6 Setting

When selecting the 1 -to- N protocol for the V600-CA1A/RS-232C interface, the setting is limited to $\mathrm{N}=1$. In this case, the FCS check code may be added.

| SW2 | SW3 | SW4 | SW5 | Unit No. |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | No. 0 |
| 0 | 0 | 0 | 1 | No. 1 |
| 0 | 0 | 1 | 0 | No. 2 |
| 0 | 0 | 1 | 1 | No. 3 |
| 0 | 1 | 0 | 0 | No. 4 |
| 0 | 1 | 0 | 1 | No. 5 |
| 0 | 1 | 1 | 0 | No. 6 |
| 0 | 1 | 1 | 1 | No. 7 |
| 1 | 0 | 0 | 0 | No. 8 |
| 1 | 0 | 0 | 1 | No. 9 |
| 1 | 0 | 1 | 0 | No. 10 |
| 1 | 0 | 1 | 1 | No. 11 |
| 1 | 1 | 0 | 0 | No. 12 |
| 1 | 1 | 0 | 1 | No. 13 |
| 1 | 1 | 1 | 0 | No. 14 |
| 1 | 1 | 1 | 1 | No. 15 |

Note 1. Be careful not to set to the same unit number twice.
2. Set them to OFF for the 1-to-1 protocol.

## Read (ASCII/1) (Sequence No. 500)

This sequence is used when the number of Heads to be read from the Carrier is 1.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 data$+1$ | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
| +2 | (Undefined) | Head CH No. |
| +3 | Leading | ss No. |
| +4 | (Undefined) | Read bytes |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0005 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 07 (CD1D) <br> 00 to 15 (CA $\square$ A) |
| +2 | R/W Head channel <br> (CH) No. (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| +3 | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| +4 | Read bytes <br> (2 digits Hexadecimal) | 01 to F4 (1 to 244 bytes) |

## Receive Data Word Allocation (3rd Operand of PMCR)

| Receive data storage words | +0 | Number of receive data words |
| :---: | :---: | :---: |
|  | +1 | Read data |
|  | +2 | Read data |
|  | $\sim$ | , |
|  | +122 | Read data |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0002 to 0123 |
| +1 to +122 | Read data (ASCII) | Number of read bytes stored in ASCII |

Note Data from Data Carriers designated for ASCII is stored beginning with the smallest offset from the receive data words.

## Read (ASCII/2) (Sequence No. 501)

This sequence is used when the number of Heads to be read from the Carrier is 2 . Up to 118 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 data$+1$ | Number of send data words |  |
| :---: | :---: | :---: |
|  | Number | eads |
| +2 | (Undefined) | Unit No. |
| +3 | (Undefined) | Head CH No. |
| +4 | Leading | ss No. |
| +5 | (Undefined) | Read bytes |
| +6 | (Undefined) | Unit No. |
| +7 | (Undefined) | Head CH No. |
| +8 | Leading | ss No. |
| +9 | (Undefined) | Read bytes |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0006 to 0010 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0002 |
| $+(4(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(4(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> $(1$ digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(4(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(4(\mathrm{~N}-1)+5)$ | Read bytes <br> $(2$ digits Hexadecimal) | 01 to 76 (1 to 118 bytes) |

N: Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0002 to 0120 |
| $+(60(\mathrm{~N}-1)+1)$ to <br> $+(60(\mathrm{~N}-1)+59)$ | Read data (ASCII) | Number of read bytes store in ASCII |

N: Number of Heads
Note Data from Data Carriers designated for ASCII is stored beginning with the smallest offset from the receive data words.

## Read (ASCII/4) (Sequence No. 502)

This sequence is used when the maximum number of Heads to be read from the Carrier is 4 . Up to 48 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0006 to 0018 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0004 |
| $+(4(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(4(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(4(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(4(\mathrm{~N}-1)+5)$ | Read bytes <br> (2 digits Hexadecimal) | 01 to 30 (1 to 48 bytes) |

N: Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD $)$ | 0002 to 0097 |
| $+(24(\mathrm{~N}-1)+1)$ to <br> $+(24(\mathrm{~N}-1)+24)$ | Read data (ASCII) | Number of read bytes stored in ASCII |

$N$ : Number of Heads
Note Data from Data Carriers designated for ASCII is stored beginning with the smallest offset from the receive data words.

## Read (ASCII/8) (Sequence No. 503)

This sequence is used when the maximum number of Heads to be read from the Carrier is 8 . Up to 20 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0006 to 0034 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0008 |
| $+(4(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(4(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(4(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(4(\mathrm{~N}-1)+5)$ | Read bytes <br> (2 digits Hexadecimal) | 01 to 14 (1 to 20 bytes) |

N : Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data
storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0002 to 0081 |
| $+(10(\mathrm{~N}-1)+1)$ to <br> $+(10(\mathrm{~N}-1)+10)$ | Read data (ASCII) | Number of read bytes stored in ASCII |

N : Number of Heads
Note Data from Data Carriers designated for ASCII is stored beginning with the smallest offset from the receive data words.

## Read (Hexadecimal/1) (Sequence No. 504)

This sequence is used when the number of Heads to be read from the Carrier is 1.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send <br> data | Number of send data words |  |  |
| :--- | :--- | :--- | :--- |
|  | +1 | (Undefined) | Unit No. |
|  | +2 | (Undefined) | Head CH No. |
|  |  | Leading address No. |  |
|  |  | Read bytes |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0005 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 07 (CD1D) <br> 00 to 15 (CA $\square A) ~$ |
| +2 | R/W Head CH No. (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| +3 | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| +4 | Read bytes <br> (2 digits Hexadecimal) | 01 to 7A (1 to 122 bytes) |

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0002 to 0062 |
| +1 to +61 | Read data (Hexadecimal) | Number of read bytes stored in hexadecimal <br> data |

Note Data for Data Carriers designated for hexadecimal is stored beginning with the largest offset from the receive data words.

## Read (Hexadecimal/2) (Sequence No. 505)

This sequence is used when the maximum number of Heads to be read from the Carrier is 2 . Up to 60 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0006 to 0010 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0002 |
| $+(4(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(4(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(4(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(4(\mathrm{~N}-1)+5)$ | Read bytes <br> (2 digits Hexadecimal) | 01 to 3C (1 to 60 bytes) |

N: Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0002 to 0091 |
| $+(60(\mathrm{~N}-1)+1)$ to <br> $+(60(\mathrm{~N}-1)+30)$ | Read data (Hexadecimal) | Number of read bytes stored in hexadecimal <br> code |

N : Number of Heads
Note Data for Data Carriers designated for hexadecimal is stored beginning with the largest offset from the receive data words.

## Read (Hexadecimal/4) (Sequence No. 506)

This sequence is used when the maximum number of Heads to be read from the Carrier is 4 . Up to 24 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0006 to 0018 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0004 |
| $+(4(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(4(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(4(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(4(\mathrm{~N}-1)+5)$ | Read bytes <br> (2 digits Hexadecimal) | 01 to 18 (1 to 24 bytes) |

N: Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0002 to 0085 |
| $+(24(\mathrm{~N}-1)+1)$ to <br> $+(24(\mathrm{~N}-1)+12)$ | Read data (Hexadecimal) | Number of read bytes stored in hexadecimal <br> data |

Note Data for Data Carriers designated for hexadecimal is received beginning with the largest offset from the receive data words.

## Read (Hexadecimal/8) (Sequence No. 507)

This sequence is used when the maximum number of Heads to be read from the Carrier is 8 . Up to 10 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0006 to 0034 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0008 |
| $+(4(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(4(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(4(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(4(\mathrm{~N}-1)+5)$ | Read bytes <br> (2 digits Hexadecimal) | 01 to 0A (1 to 10 bytes) |

N : Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0002 to 0076 |
| $+(10(\mathrm{~N}-1)+1)$ to <br> $+(10(\mathrm{~N}-1)+5)$ | Read data (CH 1) <br> (Hexadecimal) | Number of read bytes stored in hexadecimal <br> data |

N : Number of Heads
Note Data for Data Carriers designated for hexadecimal is sent beginning with the largest offset from the receive data words.

## Auto-read (ASCII/1) (Sequence No. 508)

This sequence is used when the maximum number of Heads to be read from the Carrier is 1 .

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 500 (Read (ASCII/1)).

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 500 (Read (ASCII/1)).
Note For auto-read (AR), a response is not returned if the number of Heads is not read by the Carrier, the Abort Bit must be turned OFF to terminate the sequence.

## Auto-read (Hexadecimal/1) (Sequence No. 509)

This sequence is used when the maximum number of Heads to be read from the Carrier is 1 .

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 504 (Read (Hexadecimal/1)).

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 504 (Read (Hexadecimal/1)).
Note For auto-read (AR), a response is not returned if the number of Heads is not read by the Carrier, the Abort Bit must be turned OFF to terminate the sequence.

## Polling Auto-read (ASCII) (Sequence No. 510)

This sequence is used when the number of Heads to be read from the Carrier is from 1 to 8 .

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0006 to 0034 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0008 |
| $+(4(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(4(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(4(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 000 to FFFF |
| $+(4(\mathrm{~N}-1)+5)$ | Read bytes <br> (2 digits Hexadecimal) | If number of Heads is 2 or less <br> 01 to 76 (1 to 118 bytes) |
|  |  | If number of Heads is 4 or less <br> 01 to 30 (1 to 48 bytes) |
|  | If number of Heads is 8 or less <br> 01 to 20 (1 to 20 bytes) |  |

N: Number of Heads
Receive Data Word Allocation (3rd Operand of PMCR)
None.
Note 1. Execute Sequence No. 510 before executing Sequence No. 511, 512, 513.
2. Execute Sequence No. 544 (Polling Auto-read Command Processing Cancel) to cancel the polling auto-read.
3. Retry processing is not performed for this sequence.

## Polling Auto-read Sub-command (ASCII/2) (Sequence No. 511)

This sequence is used when the maximum number of Heads to be read from the Carrier is 2 . Up to 118 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 501 (Read (ASCII/2)). However, the leading address No. and number of read bytes are not used and will be the value specified for sequence \#510.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 501 (Read (ASCII/2)).
Note 1. Execute Sequence No. 510 before executing Sequence No. 511.
2. Data from Data Carriers designated for ASCII is stored beginning with the smallest offset from the receive data words.
3. Retry processing is not performed for this sequence.

## Polling Auto-read Sub-command (ASCII/4) (Sequence No. 512)

This sequence is used when the maximum number of Heads to be read from the Carrier is 4 . Up to 48 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 502 (Read (ASCII/4)). However, the leading address No. and number of read bytes are not used and will be the value specified for sequence \#510.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 502 (Read (ASCII/4)).
Note 1. Execute Sequence No. 510 before executing Sequence No. 512.
2. Data from Data Carriers designated for ASCII is stored beginning with the smallest offset from the receive data words.
3. Retry processing is not performed for this sequence.

## Polling Auto-read Sub-command (ASCII/8) (Sequence No. 513)

This sequence is used when the maximum number of Heads to be read from the Carrier is 8 . Up to 20 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 503 (Read (ASCII/8)). However, the leading address No. and number of read bytes are not used and will be the value specified for sequence \#510.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 503 (Read (ASCII/8)).
Note 1. Execute Sequence No. 510 before executing Sequence No. 513.
2. Data from Data Carriers designated for ASCII is stored beginning with the smallest offset from the receive data words.
3. Retry processing is not performed for this sequence.

## Polling Auto-read (Hexadecimal) (Sequence No. 514)

This sequence is used when the number of Heads to be read from the Carrier is from 1 to 8 .

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0006 to 0034 |
| +1 | Number of Heads (4 digits BCD) | 0001 to 0008 |
| +(4(N-1)+2) | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the maximum Unit No. depending on the model) |
| $+(4(\mathrm{~N}-1)+3)$ | R/W Head CH No. (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 |
| +(4(N-1)+4) | Leading address No. (4 digits Hexadecimal) | 0000 to FFFF |
| +(4(N-1)+5) | Read bytes (2 digits Hexadecimal) | If number of Heads is 2 or less 01 to 3C ( 1 to 60 bytes) |
|  |  | If number of Heads is 4 or less 01 to 18 ( 1 to 24 bytes) |
|  |  | $\text { If number of Heads is } 8 \text { or less }$ $01 \text { to } 0 \text { ( } 1 \text { to } 10 \text { bytes) }$ |

N: Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Execute Sequence No. 514 before executing Sequence No. 515, 516, 517.
2. Execute Sequence No. 544 (Polling Auto-read Command Processing Cancel) to cancel the polling auto-read.

## Polling Auto-read Sub-command (Hexadecimal/2) (Sequence No. 515)

This sequence is used when the maximum number of Heads to be read from the Carrier is 2 . Up to 60 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 505 (Read (Hexadecimal/2)). However, the leading address No. and number of read bytes are not used and will be the value specified for sequence \#514.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 505 (Read (Hexadecimal/2)).
Note 1. Execute Sequence No. 514 before executing Sequence No. 515.
2. Data from Data Carrier designated for hexadecimal is stored beginning with the largest offset from the receive data words.
3. Retry processing is not performed for this sequence.

## Polling Auto-read Sub-command (Hexadecimal/4) (Sequence No. 516)

This sequence is used when the maximum number of Heads to be read from the Carrier is 4 . Up to 24 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 506 (Read (Hexadecimal/4)). However, the leading address No. and number of read bytes are not used and will be the value specified for sequence \#514.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 506 (Read (Hexadecimal/4)).
Note 1. Execute Sequence No. 514 before executing Sequence No. 516.
2. Data from Data Carrier designated for hexadecimal is stored beginning with the largest offset from the receive data words.

## Polling Auto-read Sub-command (Hexadecimal/8) (Sequence No.517)

This sequence is used when the maximum number of Heads to be read from the Carrier is 8 . Up to 10 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of sequence No. 507 (Read (Hexadecimal/8)). However, the leading address No. and number of read bytes are not used and will be the value specified for sequence \#514.

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of sequence No. 507 (Read (Hexadecimal/8)).
Note 1. Execute sequence No. 514 before executing sequence No.517.
2. Data from Data Carriers designated for hexadecimal is stored beginning with the largest offset from the receive data words.
3. Retry processing is not performed for this sequence.

## Write (ASCII/1) (Sequence No.518)

This sequence is used when the number of Heads to be written to the Carrier is 1.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 data | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
| +2 | (Undefined) | Head CH No. |
| +3 | Leading address No. |  |
| +4 | Number of write bytes |  |
| +5 | Write data |  |
| $\sim$ |  |  |
| Max |  |  |
| +128 | Write data |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0006 to 0129 |
| +1 | Relevant Unit No. (2 digits BCD) | 00 to 07 (CD1D) <br> 00 to 15 (CA2A) |
| +2 | R/W Head CH No. (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| +3 | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| +4 | Number of write bytes <br> (4 digits BCD) | 0001 to 0248 |
| +5 to | Write data (ASCII) | Input in ASCII <br> Up to 248 bytes (max.) can be set |
| +128 |  |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note Write data designated for ASCII is sent beginning with the smallest offset from the send data words.

## Write (ASCII/2) (Sequence No. 519)

This sequence is used when the number of Heads to be written to the Carrier is 2 . Up to 118 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of send data words (4 digits BCD) | 0007 to 0129 |
| +1 | Number of Heads (4 digits BCD) | 0001 to 0002 |
| $+(64(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the maximum Unit No. depending on the model) |
| $+(64(\mathrm{~N}-1)+3)$ | R/W Head CH No. (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1 . |
| $+(64(\mathrm{~N}-1)+4)$ | Leading address No. (4 digits Hexadecimal) | 0000 to FFFF |
| $+(64(\mathrm{~N}-1)+5)$ | Number of write bytes (4 digits BCD) | 0001 to 0118 |
| $\begin{aligned} & +(64(\mathrm{~N}-1)+6) \text { to } \\ & (64(\mathrm{~N}-1)+64) \end{aligned}$ | Write data (ASCII) | Input in ASCII. <br> Up to 118 bytes (max.) can be set |

N : Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note Write data designated for ASCII is sent beginning with the smallest offset from the send data words.

## Write (ASCII/4) (Sequence No. 520)

This sequence is used when the number of Heads to be written to the Carrier is 4 . Up to 48 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0007 to 0114 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0004 |
| $+(28(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(28(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(28(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(28(\mathrm{~N}-1)+5)$ | Number of write bytes <br> (4 digits BCD) | 0001 to 0048 |
| $+(28(\mathrm{~N}-1)+6)$ | Write data (ASCII) |  |
| to (28(N-1) +29$)$ | Input in ASCII. |  |
| Up to 48 bytes (max.) can be set |  |  |

N: Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note Write designated for ASCII is sent beginning with the smallest offset from the send data words.

## Write (ASCII/8) (Sequence No. 521)

This sequence is used when the number of Heads to be written to the Carrier is 8 . Up to 20 bytes of data can be read for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data <br> words(4 digits BCD) | 0007 to 0114 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0008 |
| $+(14(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(14(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(14(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(14(\mathrm{~N}-1)+5)$ | Number of write bytes <br> (4 digits BCD) | 0001 to 0020 |
| $+(14(\mathrm{~N}-1)+6)$ <br> to (14(N-1)+15) | Write data (ASCII) | Input in ASCII <br> Up to 20 bytes (max.) can be set |

N : Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note Write data designated for ASCII is sent beginning with the smallest offset from the send data words.

## Write (Hexadecimal/1) (Sequence No. 522)

This sequence is used when the number of Heads to be written to the Carrier is 1.

## Send Data Word Allocation (2nd Operand of PMCR)

| $\begin{array}{ll} \text { First word of send } & +0 \\ \text { data } & +1 \end{array}$ | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
| +2 | (Undefined) | Head CH No. |
| +3 | Leading address No. |  |
| +4 | Number of write digits |  |
| +5 | Write data |  |
|  |  |  |
| Max +35 | (Undefined) | Write data |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0006 to 0036 |
| +1 | Relevant Unit No. (2 digits BCD) | 00 to 07 (CD1D) <br> 00 to 15 (CA2A) |
| +2 | R/W Head CH No. (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| +3 | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| +4 | Number of write digits <br> (4 digits BCD) | 0002 to 0122 |
| +5 to | Write data (Hexadecimal) | Input in hexadecimal <br> Up to 122 digits (max.) |

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Data of which Data Carrier designated for hexadecimal is sent beginning with the largest offset from the send data words.
2. Always set an even number of digits for the write data.

## Write (Hexadecimal/2) (Sequence No. 523)

This sequence is used when the number of Heads to be written to the Carrier is 2 . Up to 56 digits of data can be written for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0007 to 0084 |
| +1 | Number of Heads <br> (4 digits BCD) | 0002 to 0002 |
| $+(64(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(64(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> $(1$ digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(64(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(64(\mathrm{~N}-1)+5)$ | Number of write digits <br> (4 digits BCD) | 0002 to 0056 |
| $+(64(\mathrm{~N}-1)+6)$ <br> to $(64(\mathrm{~N}-1)+19)$ | Write data (Hexadecimal) | Input in hexadecimal <br> Up to 56 digits (max.) can be set |

N : Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Write data designated for hexadecimal is sent beginning with the largest offset from the send data words.
2. Always set an even number of digits for the write data.

## Write (Hexadecimal/4) (Sequence No. 524)

This sequence is used when the number of Heads to be written to the Carrier is 4 . Up to 24 digits of data can be written for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0007 to 0096 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0004 |
| $+(28(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(28(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(28(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(28(\mathrm{~N}-1)+5)$ | Number of write digits <br> (4 digits BCD) | 0002 to 0024 |
| $+(28(\mathrm{~N}-1)+6)$ <br> to (28(N-1)+11) | Write data (Hexadecimal) | Input in hexadecimal code <br> Up to 24 digits (max.) can be set |

N: Number of Heads

None.

Note 1. Write data designated for hexadecimal is sent beginning with the largest offset from the send data words.
2. Always set an even number of digits for the write data.

## Write (Hexadecimal/8) (Sequence No. 525)

This sequence is used when the number of Heads to be written to the Carrier is 8 . Up to 10 digits of data can be written for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)



CH 1

CH 2

CH 8

| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0007 to 0107 |
| +1 | Number of Heads <br> (4 digits BCD) | 0001 to 0004 |
| $+(14(\mathrm{~N}-1)+2)$ | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the model) |
| $+(14(\mathrm{~N}-1)+3)$ | R/W Head CH No. <br> (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |
| $+(14(\mathrm{~N}-1)+4)$ | Leading address No. <br> (4 digits Hexadecimal) | 0000 to FFFF |
| $+(14(\mathrm{~N}-1)+5)$ | Number of write digits <br> (4 digits BCD) | 0002 to 0010 |
| $+(14(\mathrm{~N}-1)+6)$ <br> to (14(N-1)+8) | Write data (Hexadecimal) | Input in hexadecimal code <br> Up to 10 digits (max.) can be set |

N : Number of Heads

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Write data designated for hexadecimal is sent beginning with the largest offset from the send data words.
2. Always set an even number of digits for the write data.

## Auto-write (ASCII/1) (Sequence No. 526)

This sequence is used when the number of Heads to be written to the Carrier is 1.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 518 (Write(ASCII/1)).

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 518 (Write(ASCII/1)).
Note For auto-write (AW), a response is not returned if the number of Heads is not written by the Carrier, the Abort Bit must be turned OFF to terminate the sequence.

## Auto-write (Hexadecimal/1) (Sequence No. 527)

This sequence is used when the number of Heads to be written to the Carrier is 1.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 522 (Write (Hexadecimal/1)).

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 522 (Write (Hexadecimal/1)).
Note For auto-write (AW), a response is not returned if the number of Heads is not written by the Carrier, the Abort Bit must be turned OFF to terminate the sequence.

## Polling Auto-write (ASCII/2) (Sequence No. 528)

This sequence is used when the number of Heads to be written to the Carrier is 2.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 519 (Write (ASCII/2)).

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 519 (Write (ASCII/2)).
Note 1. Execute Sequence No. 545 (Polling Auto-write Command Processing Cancel) to cancel the polling auto-write.
2. Retry processing is not performed for this sequence.

## Polling Auto-write Subcommand (ASCII/2) (Sequence No. 529)

This sequence is used when the number of Heads to be written to the Carrier is 2 . Up to 118 digits of data can be written for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 519 (Write (ASCII/2)). However, the leading address No., number of write, and write data are not used and become undefined.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Execute Sequence No. 528 before executing Sequence No. 529.
2. Retry processing is not performed for this sequence.

## Polling Auto-write (ASCII/4) (Sequence No. 530)

This sequence is used when the number of Heads to be written to the Carrier is 4.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 520 (Write (ASCII/4)).

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 520 (Write(ASCII/4)).
Note Execute Sequence No. 545 (Polling Auto-write Command Processing Cancel) to cancel the polling autowrite.

## Polling Auto-write Subcommand (ASCII/4) (Sequence No. 531)

This sequence is used when the number of Heads to be written to the Carrier is 4 . Up to 48 digits of data can be written for each Read/Write Head.
Send Data Word Allocation (2nd Operand of PMCR)
The send data word allocation is similar to that of Sequence No. 520 (Write (ASCII/4)). However, the leading address No., number of write, and write data are not used and become undefined.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Execute Sequence No. 530 before executing Sequence No. 531.
2. Retry processing is not performed for this sequence.

## Polling Auto-write (ASCII/8) (Sequence No. 532)

This sequence is used when the number of Heads to be written to the Carrier is 8 .

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 521 (Write (ASCII/8)).
Receive Data Word Allocation (3rd Operand of PMCR)
The receive data word allocation is similar to that of Sequence No. 521 (Write (ASCII/8)).
Note 1. Execute Sequence No. 545 (Polling Auto-write Command Processing Cancel) to cancel the polling auto-write.
2. Retry processing is not performed for this sequence.

## Polling Auto-write Subcommand (ASCII/8) (Sequence No. 533)

This sequence is used when the number of Heads to be written to the Carrier is 8 . Up to 20 digits of data can be written for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 521 (Write (ASCII/8)). However, the leading address No., number of write, and write data are not used and become undefined.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Execute Sequence No. 532 before executing Sequence No. 533.
2. Retry processing is not performed for this sequence.

## Polling Auto-write (Hexadecimal/2) (Sequence No. 534)

This sequence is used when the number of Heads to be written to the Carrier is 2.
Send Data Word Allocation (2nd Operand of PMCR)
The send data word allocation is similar to that of Sequence No. 523 (Write (Hexadecimal/2)).

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 523 (Write (Hexadecimal/2)).
Note 1. Execute Sequence No. 545 (Polling Auto-write Command Processing Cancel) to cancel the polling auto-write.
2. Retry processing is not performed for this sequence.

## Polling Auto-write Subcommand (Hexadecimal/2) (Sequence No. 535)

This sequence is used when the number of Heads to be written to the Carrier is 2 . Up to 56 digits of data can be written for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 523 (Write (Hexadecimal/2)). However, the leading address No., number of write, and write data are not used and become undefined.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Execute Sequence No. 534 before executing Sequence No. 535.
2. Retry processing is not performed for this sequence.

## Polling Auto-write (Hexadecimal/4) (Sequence No. 536)

This sequence is used when the number of Heads to be written to the Carrier is 4.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 524 (Write (Hexadecimal/4)).

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 524 (Write (Hexadecimal/4)).
Note 1. Execute Sequence No. 545 (Polling Auto-write Command Processing Cancel) to cancel the polling auto-write.
2. Retry processing is not performed for this sequence.

## Polling Auto-write Subcommand (Hexadecimal/4) (Sequence No. 537)

This sequence is used when the number of Heads to be written to the Carrier is 2. Up to 24 digits of data can be written for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 524 (Write (Hexadecimal/4)). However, the leading address No., number of write, and write data are not used and become undefined.
Receive Data Word Allocation (3rd Operand of PMCR)
None.

Note 1. Execute Sequence No. 536 before executing Sequence No. 537.
2. Retry processing is not performed for this sequence.

## Polling Auto-write (Hexadecimal/8) (Sequence No. 538)

This sequence is used when the number of Heads to be written to the Carrier is 8.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 525 (Write (Hexadecimal/8)).

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 525 (Write (Hexadecimal/8)).
Note 1. Execute Sequence No. 545 (Polling Auto-write Command Processing Cancel) to cancel the polling auto-write.
2. Retry processing is not performed for this sequence.

## Polling Auto-write Subcommand (Hexadecimal/8) (Sequence No. 539)

This sequence is used when the number of Heads to be written to the Carrier is 8 . Up to 10 digits of data can be written for each Read/Write Head.

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 525 (Write (Hexadecimal/8)). However, the leading address No., number of write, and write data are not used and become undefined.

## Receive Data Word Allocation (3rd Operand of PMCR)

None.
Note 1. Execute Sequence No. 538 before executing Sequence No. 539.
2. Retry processing is not performed for this sequence.

## Data Check (Sequence No. 540)

This sequence writes and verifies the CRC code for check blocks designated by the user.

## Send Data Word Allocation (2nd Operand of PMCR)



## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | $\begin{array}{l}\text { Number of receive data } \\ \text { words (4 digits BCD) }\end{array}$ | 0002 (fixed) |
| +1 | $\begin{array}{l}\text { Completion code } \\ \text { (2 digits Hexadecimal) }\end{array}$ | $\begin{array}{l}\text { (Verification, calculation designation) } \\ \text { 00: Normal completion for calculation processing } \\ \text { 75: Data in normal condition for verification } \\ \text { processing }\end{array}$ |
| 76: Error Data alarm for verification processing |  |  |
| (If management of number of write times is |  |  |
| designated) |  |  |
| 75:Number of write times is under those which is |  |  |
| specified. |  |  |$]$| 76:alarm for number of write times is over those |
| :--- |
| which is specified. |

Note If $L$ (management of number of write times) is designated by processing designation, management of number of write times for Data Carrier of EEPROM is performed.

## Control (Sequence No. 541)

This sequence performs I/O operations or I/O reads.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send +0 data

|  | Number of send data words |  |  |
| :--- | ---: | ---: | ---: |
|  |  |  |  |
|  | (Undefined) | Unit No. |  |
|  | (Undefined) | OUT1 operation | OUT2 operation |
|  |  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0003 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 07 (CD1D) |
| +2 | OUT1 operation (1 digit BCD) | 0: No operation <br> $1:$ turned ON <br> 2: turned OFF |
|  |  | $0:$ No operation <br> $1:$ turned ON <br> 2: turned OFF |
|  | OUT2 operation (1 digit BCD) |  |

## Receive Data Word Allocation (3rd Operand of PMCR)

|  | $\begin{array}{c}\text { Receive data } \\ \text { storage words }\end{array}$ |  | +0 |
| :--- | :--- | :--- | :--- |
|  | Number of receive data words |  |  |
|  | Current input status | $\begin{array}{c}\text { Output status after } \\ \text { operation }\end{array}$ |  |
|  |  |  |  |


| Offset | Contents (data format) | Data |
| :---: | :---: | :---: |
| +0 | Number of receive data words (4 digits BCD) | 0002 (fixed) |
| $+1$ <br> Leftmost 1 byte | Current input status <br> Leftmost 4 bits: IN1 operation <br> Rightmost 4 bits: IN2 operation | 1: ON status 0: OFF status |
|  | Output status after operation Leftmost 4 bits: <br> OUT1 operation <br> Rightmost 4 bits: <br> OUT2 operation | 1: ON status 0: OFF status |

Note 1. The V600/620-CA $\square \mathrm{A}$ does not support this command.
2. This sequence executes the equivalent of the CONTROL command.

## Error Information Read (Sequence No. 542)

This sequence reads information from the latest error log.

## Send Data Word Allocation (2nd Operand of PMCR)

|  | First word of send +0  Number of send data words  <br>     <br> data    |  | (Undefined) |
| :--- | ---: | :---: | :---: |
|  |  |  | Unit No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | 00 to 07 (CD1D) |

## Receive Data Word Allocation (3rd Operand of PMCR)



| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> $(4$ digits BCD) | 0004 to 0076 |
| +1 to +75 | Error log (ASCII) | One item of data is stored with 5 <br> characters of generated command, <br> generated Head No., generated <br> error code. |

Note 1. The V600/620-CA $\square \mathrm{A}$ does not support this command.
2. Up to 30 error records can be stored.
3. The most resent error records are stored first.

## Command Processing Cancel (Sequence No. 543)

This sequence cancels command processing except for polling command processing. The command waiting status is entered.

## Send Data Word Allocation (2nd Operand of PMCR)

|  | First word of send <br> data <br> data |  | Number of send data words |  |
| :--- | :--- | :---: | :---: | :---: |
|  |  | (Undefined) | Unit No. |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0002 (fixed) |
| +1 | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the <br> model) |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

| +0 | Number of receive data words |  |
| :---: | :---: | :---: |
| +1 | (Undefined) | Unit No. |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0002 (fixed) |
| +1 | Completion code <br> (2 digits Hexadecimal) | 00:Normal termination <br> 14: Auto or communications command processing <br> not executed |
|  | 75:Cancelled before the end of expansion <br> command receive or before sync input went <br> active or before detection of the existence of <br> Data Carrier | 76: Cancelled during read/write processing for Data <br> Carrier |

## Polling Auto-read Command Processing Cancel (Sequence No. 544)

This sequence cancels polling auto-read processing.

## Send Data Word Allocation (2nd Operand of PMCR)

| First word of send +0 data | Number of send data words |  |
| :---: | :---: | :---: |
|  | (Undefined) | Unit No. |
| +2 | (Not used) |  |
| +3 | (Undefined) | Head channel No. |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> $(4$ digits BCD) | 0004 (fixed) |
| +1 | Unit No. (2 digits BCD) | Arbitrary (However, there is a limit for the <br> maximum Unit No. depending on the <br> model) |
| +2 | Not used |  |
| +3 | R/W Head CH No. (1 digit BCD) | R/W Head CH 1 designation: 1 <br> R/W Head CH 2 designation: 2 <br> The CD1D must be set to 1. |

## Receive Data Word Allocation (3rd Operand of PMCR)

Receive data storage words

|  | Number of receive data words |  |
| :--- | :--- | :--- |
|  | (Undefined) |  |
|  | Completion code |  |
|  |  |  |


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data <br> words (4 digits BCD) | 0002 (fixed) |
| +1 | Completion code <br> (2 digits Hexadecimal) | 75:Cancelled before communications processing <br> with Data Carrier <br> 76: Cancelled after communications processing with <br> Data Carrier |

## Polling Auto-write Command Processing Cancel (Sequence No. 545)

This sequence cancels polling auto-write processing

## Send Data Word Allocation (2nd Operand of PMCR)

The send data word allocation is similar to that of Sequence No. 544 (Polling Auto-read Command Processing Cancel)

## Receive Data Word Allocation (3rd Operand of PMCR)

The receive data word allocation is similar to that of Sequence No. 544 (Polling Auto-read Command Processing Cancel)

## General-purpose Command (Sequence No. 546)

This sequence transmits arbitrary data and stores receive data to the receive data words. The characters "@", FCS (terminator) are not required in the send data words and receive data words. These characters will be automatically added for transmission and automatically removed before saving data.

## Send Data Word Allocation (2nd Operand of PMCR)

First word of send data


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of send data words <br> (4 digits BCD) | 0003 to 0128 |
| +1 | Send data byte length <br> (4 digits BCD) | 0001 to 0251 <br> The number of bytes in the send data <br> except for @, the FCS, and the terminator. |
| +2 to | Send data (ASCII) | Input send data up to 251 characters <br> (max.) in ASCII |
| +127 |  |  |

Receive Data Storage Word Allocation (3rd Operand of PMCR)
Receive data storage words


| Offset | Contents (data format) | Data |
| :--- | :--- | :--- |
| +0 | Number of receive data words <br> (4 digits BCD) | 0002 to 0127 |
| +1 to |  |  |
| +126 | Receive data <br> (ASCII) | Receive data is stored in ASCII. <br> Up to 251 characters (max.) |

# Appendix L <br> Hayes Modem AT Command Protocol 

The Hayes Modem AT Command Protocol is used to make various settings or control remotely a Hayes modem connected to the Communications Board via RS-232C cable.

## Protocol Configuration

The configuration of the Hayes Modem AT Command Protocol is shown below.

| Sequence No. | Communications sequence name | Function | Ladder interface |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Send word allocation | Receive word allocation |
| 550 | Initialize modem (general-purpose) | Initializes the modem connected to the Communications Board. The initialization command is set in the words specified for the second operand of PMCR. | Yes | No |
| $\begin{aligned} & 560 \\ & 570 \\ & 580 \\ & 580 \end{aligned}$ | Initialize modem (specialized) | Initializes certain OMRON Modems. | No | No |
| $\begin{aligned} & 561 \\ & 571 \\ & 581 \\ & \hline 8 \end{aligned}$ | Dial | Dials from the modem connected to the Communications Board. AT commands and telephone numbers are set set in the words specified for the second operand of PMCR. This sequence can be used only for certain OMRON modems. | Yes | No |
| 552 | Password | After the line is connected, the password sent from the other exchange is verified to confirm that the line is connected to the desired exchange. The normal value of a password is set in the words specified for the second operand of PMCR. | Yes | No |
| 553 | Data send/receive (general purpose sequence) | Sends arbitrary data to the exchange which the line is connected. Send data is set in the words specified for the second operand of PMCR. Receive data is stored in the words specified for the third operand of PMCR. | Yes | Yes |
| 554 | Escape | Shifts the modem to escape mode (the condition in which command input is available during data communications). The escape code is fixed to "+++" | No | No |
| 555 | Hang up | After shifting to escape mode, the line is disconnected. | No | No |
| $\begin{array}{\|l\|} \hline 562 \\ 572 \\ 582 \end{array}$ | Initialize and dial | Executes continuously from initialization to dialling operations for certain OMRON Modems. | Yes* | No |
| 590 | Escape to hang up | Executes continuously from shifting to the escape mode to hanging up. | No | No |

## Note 1. Ladder Interface Settings

YES: User settings are required for the 2nd and 3rd operands of PMCR.
NO: Send word allocation: Set a dummy word address for the 3rd operand (D). Receive word allocation: Set the constant 0000 for the 2rd operand (S).
2. For details about dialling, refer to sequences 561,571 and 581 .

## Connections

The connections when using the Hayes Modem AT Command Protocol is shown below.

## RS-232C Connection



## Compatible Modems

Although most of the sequences in this protocol can be used regardless of modem, the sequences Initialize Modem (specialized) and Dial sequences can be used only for the following Modems:

- MD24FB10V (OMRON Modem)
- MD144FB5V (OMRON Intelligent Modem)
- ME1414VB2/B2 (OMRON FAX/DATA Modem)

For other modems, create a modem initialization sequence using the general-purpose Initialize Modem sequence and dial using the Data Send/Receive sequence (Sequence No. 553).

## Modem Settings

When this protocol is used, it is required that the modem connected to the Communications Board be initialized to the following conditions:

| Command echo | No |
| :--- | :--- |
| Result code display format | Numeric format |
| Speed display, busy/dialling tone detection at <br> connection | Baud rate display enabled, busy and dialling tone <br> detection enabled. |
| Error correction data compression display | Error correction/data compression display enabled |
| MNP setting | Error correction provided (auto-reliable mode) |
| MNP class setting | MNP class 4 |
| V.42 compression, Error correction | Not enabled |
| Flow control between terminal modems | Not enabled |
| ER signal control | Always ON |
| Escape code | + |

Note 1. It is recommended that, in addition to the above settings, the abort timer should be set so that communications are cut off if a communications error happened due to incidents such as cable disconnection between the Communications Board and modem. Set the abort timer to 10 minutes for the modem initialization (specialized) (Sequence No. 560, 570,580). Refer to modem's manual for further information about abort timers.
2. The data format of the modem (baud rate, data length, parity, stop bit) is set by AT commands issued from a device connected to the modem. Its settings should conform to communications conditions of the device which issues AT commands. Therefore when communications are made between the modem and Communications Board, it is required that communications conditions should be set by issuing AT commands from the Communications Board.
3. Modem settings become invalid if the power supply is turned off and must be set again. However, a memory backup function can be used to protect settings so that even after the power supply to the modem is turned off, it can communicate with the previous setting conditions.
For Initialize Modem (specialized), the modem initialization command is built in as message data. However, for Initialize Modem (general-purpose), the command must be specified in PMCR.

| Operand 1 | $\# x 550$ (x: Communications port) |
| :--- | :--- |
| Operand 2 | First address for storing initialization command character string C |
| Operand 3 | None |


| $\mathrm{C}+0$ | Number of words from address set for operand 2 to end of data | 4 digits BCD |
| :--- | :--- | :--- |
| $\mathrm{C}+1$ | Number of bytes for send data (initialization command) | 4 digits BCD |
| $\mathrm{C}+2$ | Send data (initialization command) | ASCII |
| $\vdots$ | (Fill data to left for odd numbers of bytes) |  |
| $\mathrm{C}+\mathrm{n}$ |  |  |

## Setting Example for Modem Initialization Command <br> - MD24FB10V Using Sequence \#550 (OMRON)

The following command is set in the words specified by the second operand of PMCR.
ATE0V0X4IV2 2 N3\%C0*C0IX1\&M0S26=10


Note Turn ON pin 4 of DIP switches SW3 on for this Modem (ER signal always ON).

## MD144FB5V (OMRON)

The following command is set in the words specified by the second operand of PMCR.
ATEOV0X4IV2\N3\%C0*C0\Q0\&M0\&D0\%B9600S26=10


## ME1414VBII/ME1414BII (OMRON)

The following command is set in the words specified by the second operand of PMCR.
AT\J1B8E0V0S0=1X4\V2\N3\&M0\%C0\&D0\&EOXX1S26=10


Note Turn ON DIP switch SW3 on in the rear of the Modem.

## Dialling

To dial telephone numbers for the OMRON Modems using sequences No. 561, 571, 581, set the dialling command and telephone number in the words specified by the second operand of PMCR. However, for other Modems, make the following settings for the Data Send/Receive sequence.
This is an example of telephone number settings for the above mentioned 3 OMRON Modems.

## Operand and Word Settings of PMCR

| Operand 1 | MD24FB10V | $\# x 561$ (x: Communications port) |
| :--- | :--- | :--- |
|  | MD144FB5V | $\# x 571$ |
|  | ME1414VB2/B2 | $\# x 581$ |
| Operand 2 | First address C of send data (dialling operation) |  |
| Operand 3 | None |  |


| C +0 | Number of words from address set for operand 2 to end of <br> data | 4 digits BCD |
| :--- | :--- | :--- |
| C +1 | Number of bytes of send data (dialling operation) | 4 digits BCD |
| C +2 <br> $\vdots$ <br> C $+n$ | Send data (dialling operation) <br> (Fill data to left for odd numbers of bytes) | ASCII |

## Setting Example

If telephone number is 03-0123-4567

| 0010 | 0016 | 4154 | 4454 | 3033 | 2D30 | 3132 | 332D | 3435 | 3637 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 4 | 4 | A T | D T | 03 | -0 | 12 | 3 - | 45 | 67 |

Note 1. This example uses a tone line. Change ATDT to ATDP for pulse lines.
2. Fill the telephone number to the left in the words if the character string length of the dialling operation is an odd number of bytes.

| 0008 | 0011 | 4154 | 4454 | 3031 | 2 D 32 | 3334 | 3500 |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: |

## Password Verification

A password can be verified by executing sequence No. 552 of this protocol. It is required to set in advance the value of the password in the words specified by the second operand of PMCR.

## Operand and Word Settings of PMCR

| Operand 1 | $\# x 550$ (x: Communications port) |
| :--- | :--- |
| Operand 2 | First address of the words where the password is set |
| Operand 3 | None |


| C+0 | Number of words from address set for operand 2 to end of <br> data | 4 digits BCD |
| :--- | :--- | :--- |
| C+1 | Number of bytes of comparison data (normal value of <br> password) | 4 digits BCD |
| C+2 <br> $\vdots$ <br> C +n | Comparison value (password normal value) <br> (Fill data to left for odd numbers of bytes) | ASCII |

## Setting Example

When password is OMRON-CO.

| 0006 | 0008 | 4F4D | 524 F | 4E2D | 434F |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| C |  |  |  |  |  |  |

Character string length of password sent to modem (bytes)
Code length of PMCR when it is used (words)

## Password Verification Operation

The number of retries is 3 for password verification.


## Data Send/Receive

Data Send/Receive can be executed using sequence No. 553. The send data sent to another exchange is set in the words specified by the second operand of PMCR. Data received by the PC is stored in the words specified by the third operand of PMCR.

## Operand and Word Settings of PMCR

| Operand 1 | $\# x 553$ (x: Communications port) |
| :--- | :--- |
| Operand 2 | First address C1 of the words where send data is set |
| Operand 3 | First address C2 of the words where receive data is stored |

- Operand 2

| C1+0 | Number of words from address set for operand 2 to end of <br> data | 4 digits BCD |
| :--- | :--- | :--- |
| C1+1 | Number of bytes of send data | 4 digits BCD |
| C1+2 | Send data (dialling operation) <br> (Fill data to left for odd numbers of bytes) <br> C1 +n | ASCII |

- Operand 3

| $\mathrm{C} 2+0$ | Number of bytes of receive data | 4 digits BCD |
| :--- | :--- | :--- |
| $\mathrm{C} 2+1$ | Receive data (dialling operation) | ASCII |
| $\vdots$ | (Fill data to left for odd numbers of bytes) |  |
| $\mathrm{C} 2+\mathrm{n}$ |  |  |

## Setting Example

When send data is THIS IS SAMPLE.

| 0009 | 0014 | 5448 | 4953 | 2049 | 5320 | 5341 | 4D50 | 4C45 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  | SA | M P | LE |

Character string length of send data sent to modem (bytes)
Code length of PMCR when it is used (words)
A maximum of 200 bytes (including the CR) can be received. When the received data is RETURN OK, the content stored in the receive words is as follows:

| 0006 | 5245 | 5455 | 524 E | 204 F | $4 \mathrm{B00}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| RE |  |  |  |  |  |
| T R N |  |  |  |  |  |

Note An error will occur is the reception data is not received within 90 seconds after the data is sent.

## Escape Mode

Shifting to the escape mode can be made using sequence No. 554 . No setting is necessary for this sequence.
Note The character string to shift the online mode to the escape mode (i.e., the escape code) is ' + ' for modem settings.

## Hang Up Command

The hang up command (to disconnect the line) can be executed using sequence No. 555 . No setting is necessary for this sequence.

## Communication Errors

Three result codes are monitored after an AT command is sent to the modem. When a result code is returned, it will be checked. If the code is not the normal result code ("OK", "CONNECT 9600/REL4", "CONNECT 2400/REL4", in words), after a fixed time of waiting to send, the following retry processing will be repeated 2 times to send the AT command again and waiting for another result code.
The receive monitoring time and send wait time for each sequence are shown below.

| Sequence <br> No. | Sequence name | Receive monitoring time | Send wait time for retries |
| :--- | :--- | :--- | :--- |
| $\# 550$ | Initialize modem (general-purpose) | 10 s | 1 s |
| $\# 560$ | Initialize modem (specialized) | 10 s | 1 s |
| $\# 570$ |  |  |  |
| $\# 580$ |  | 90 s |  |
| $\# 561$ | Dial |  | 90 s |
| $\# 571$ |  | None |  |
| $\# 581$ |  | 10 s | 3 s |
| $\# 552$ | Password | 10 s | None |
| $\# 553$ | Data send/receive (general-purpose) | 90 s | 1.5 s (after first try) |
| $\# 554$ | Escape | 90 s | 1.5 s (after first try) |
| $\# 555$ | Hang up |  | Initializing: 1 s |
| $\# 562$ | Initialize and dial |  |  |
| $\# 572$ |  | 10 s | 1.5 s (after first try) |
| $\# 582$ |  |  |  |
| $\# 590$ | Escape and hang up |  |  |

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## Revision History

A manual revision code appears as a suffix to the catalog number on the front cover of the manual.

Cat. No. W304-E1-05

Revision code

The following table outlines the changes made to the manual during each revision. Page numbers refer to the previous version.

| Revision code | Date | Revised content |
| :---: | :---: | :---: |
| 1 | June 1996 | Original production |
| 2 | November 1997 | Revision to add V1 Communications Boards. The following pages were changed. xii, ix, x (added), 2 to 11 (pages added), 15, 16, 18 (pages added), 20 (pages added), 23 to 28 (pages added), essentially all appendix pages (pages added). |
| 3 | December 1998 | Additions and changes made to PRECAUTIONS. <br> Page 8: Note added. <br> Pages 8, 12, 15, 22, 23, 24, 25, 29, 85, 88, 89, 127, 129, 130, 141, 143, 144, 183, 186, 202, 267, 270: RS-422 changed to RS-422A. <br> Page 9: Information changed for "Terminator." Note added to graphic. <br> Page 46: Graphic changed. <br> Page 52: Number of connectable Units changed from 32 to 31. <br> Page 250: "Receive" changed to "send/receive." <br> Page 303: Note added to table. |
| 4 | April 2000 | Changes were made on the following pages. <br> Page ix: Information on related manuals added. <br> Page xii-xiv: Changes made to safety information in several places. <br> Pages 4, 32, 34: Information on support software added. <br> Page 11: Information on specifications added. <br> Pages 18: Parenthetic information on modes added in several places. <br> Page 19: Information on echoback disable functions added. <br> Pages 24, 52, 187: Information on maximum number of connectable devices added. <br> Pages 25, 26, 28: "7" replaced with "shell." <br> Pages 29, 143, 186, 270: Minor changes made to graphics. <br> Page 31: Information on receive messages added. <br> Page 35: Note added. <br> Pages 43, 44: Bit addresses corrected. <br> Page 46: Information on half-duplex mode and echoback added. <br> Page 47: Error code added. <br> Page 48: Information on Abort Flags added. <br> Page 188: Minor changes made to tables. <br> Pages 189-192, 194, 195, 198, 200, : "Most significant digit" changed to "5th BCD digit." |
| 05 | November 2003 | Page 19: Corrections made to error codes for bits 00 to 03 and 08 to 11 of SR 283. |

## OMRON Corporation

FA Systems Division H.Q.
66 Matsumoto
Mishima-city, Shizuoka 411-8511
Japan
Tel: (81)55-977-9181/Fax: (81)55-977-9045

## Regional Headquarters

OMRON EUROPE B.V.
Wegalaan 67-69, NL-2132 JD Hoofddorp
The Netherlands
Tel: (31)2356-81-300/Fax: (31)2356-81-388
OMRON ELECTRONICS LLC
1 East Commerce Drive, Schaumburg, IL 60173
U.S.A.

Tel: (1)847-843-7900/Fax: (1)847-843-8568
OMRON ASIA PACIFIC PTE. LTD.
83 Clemenceau Avenue,
\#11-01, UE Square,
Singapore 239920
Tel: (65)6835-3011/Fax: (65)6835-2711

## OmROn

Authorized Distributor:

## Read and Understand this Manual

Please read and understand this manual before using the product. Please consult your OMRON representative if you have any questions or comments.

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#### Abstract

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The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products:

- Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this manual.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
- Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.
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## Disclaimers

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It is our practice to change model numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifications of the products may be changed without any notice. When in doubt, special model numbers may be assigned to fix or establish key specifications for your application on your request. Please consult with your OMRON representative at any time to confirm actual specifications of purchased products.

## DIMENSIONS AND WEIGHTS

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## PERFORMANCE DATA

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## ERRORS AND OMISSIONS

The information in this manual has been carefully checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical, or proofreading errors, or omissions.


[^0]:    Caution When using the large-capacity C200HW-PA209R Power Supply Unit, be sure to use CPU Backplanes and Expansion I/O Backplanes with "-V1" at the end of the model number. If 8 -slot or 10 -slot Backplanes without "-V1" are used, deterioration and pattern disconnection on the Backplane may occur, leading to incorrect operation.

[^1]:    Send Data Word Allocation (2nd Operand of PMCR) None.
    Receive Data Word Allocation (3rd Operand of PMCR)
    None.

